#### Calcon 2013 Tutorial 1: Basics and Applications of Spectroradiometry



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## **Motivations**

- 1. Develop a calibration plan (SI-traceable) for a satellite sensor
	- a) Calibration requirements
	- b) Calibration approach
	- c) Use of on-board calibrators
	- d) Perform system-level end-to-end calibration (validation)
- 2. Elements of the plan should
	- a) Answer how the calibration requirements will meet the mission and instrument requirements
	- b) Develop a sensor design and radiometric model (measurement equation)
	- c) Characterize subsystems (uncertainty analysis)
	- d) Compare model predictions and validate system level calibrations
	- e) Establish pre-launch radiometric uncertainties

From: NISTIR 7637 (2009), "Best Practice Guideline…" R. Datla et al.



#### Outline of the Tutorial

- 1. Basics of Radiometry
- 2. Detector-based Radiometry
- 3. Source-based Radiometry
- 4. Tools of Spectroradiometry
	- a) Detectors
	- b) Filter Radiometers
	- c) Spectroradiometers
- 5. Measurement Equation and Uncertainty Analysis
- 6. Applications from the NIST Short Course



#### Possible Sources of Error





# 1. Basics of Radiometry



## Basics of Spectroradiometry: Outline

- 1.Definitions of radiometric terms
	- a) Flux, radiant intensity, irradiance, radiance
	- b) Property modifiers
	- c) The concept of solid angle
- 2.Radiometry basics
	- a) Point source
	- b) Extended source
	- c) Flux transfer and throughput
- 3.Applications
	- a) Calibration of radiometers
	- b) Some numerical examples



## Electromagnetic Radiation



$$
c=n\lambda v
$$

$$
\bigcap_{\lambda\in\mathbb{R}}\text{supp}(X_{\lambda},\lambda)
$$

Wavelength

 $c = speed of light$  $\lambda$  = wavelength  $n =$  index of refraction  $v = frequency$ 

The wavelength is determined by the speed of light and measurements of the frequency by comparison to the atomic standards.

> For example:  $\lambda = 555$  nm, then  $v = 540 \times 10^{12}$  Hz.



## Property modifiers





## Radiant quantities

2) Radiant flux,  $\Phi$  [W ], [J/s ] E.g. laser power meters,



3) Radiant intensity, *I* [ W/sr ] E.g. point sources such as



1) Radiant energy,  $Q [J]$  E.g. deposited laser energy at 650 nm 5.3 mJ (0.25 s)

> cryogenic radiometer (beam underfills the detector)

stars observed at great distances



## Radiant quantities, continued



irradiance

Boltzmann law

E.g. real sources (blackbodies, surface of the earth, moon, and other objects)



#### Comparison of Radiometric and Photometric Units



**Thermodynamic (equivalence of heat and radiant flux)**

**Specialized (human visual response for detector model)**



#### Spectral modifier—"spectroradiometry"





#### Plane and solid angles





## Solid angle: perpendicular surface

Point Source and Circular Aperture



Note: Distance *d* is large compared to aperture dimensions so that  $d^2 >> A_2$ .



## Solid angle: tilted surface

Point Source and Circular Aperture



$$
\omega \approx \frac{A_2 \cos \theta}{d^2} = \frac{A_2 \cos 60^\circ}{d^2} = \frac{A_2}{d^2} \frac{1}{2}
$$

Note: Distance *d* is large compared to aperture dimensions so that  $d^2 >> A_2$ .



#### Radiometry of point sources (Irradiance, E)





#### Irradiance distribution, point source on a plane

**Irradiance at**  $r_1$  **for different locations on a plane:** what is  $E_2/E_1$ ?

Point Source *A*  $d<sub>1</sub>$  $d_2$ 1 θ 2 θ  $E_1^{\text{L}}$ 

**The "off-axis" irradiance from an ideal point source in a plane falls off**   $\int$ **as cos<sup>3</sup>** $\theta$ **. Keep angles small if uniformity is critical!**

Point 1 is "on-axis"

At Point 2, the distance is greater by  $r_2 = r_1/cos\theta$  and the area is tilted by  $\theta$ .



$$
E_2 = E_1 \left[ \frac{A}{A/ \cos \theta} \right] \left[ \cos^2 \theta \right]
$$

$$
E_2 = E_1 \cos^3 \theta
$$



*I*

## Radiometry of extended sources (Radiance, *L*)

Real Sources 1) have finite size and 2) the flux depends on view direction, target size, location on source, and solid angle.







#### Lambert's law

Source



Trial model: A collection of point sources, uniformly spaced across the source area

**Lambert's Law:**  $L(\theta) = L(0)$ 

#### **Lambertian or "diffuse" source**

Radiance from one of the point sources:

Viewed perpendicular Viewed tilted *A*<sup>ω</sup> *L* ∆  $(0) = \frac{\Phi}{\Phi}$ θ <sup>ω</sup> θ  $L(\theta) = \frac{4}{\Delta A \cos \theta}$ ∆  $=\frac{\Phi}{\Phi}$ 

We conclude θ θ cos  $L(\theta) = \frac{L(0)}{a}$ 

But real sources don't increase in brightness when viewed off-axis, most in fact remain constant or become dimmer

Model not a collection of ideal point sources  $(I = \Phi/\omega)$ , but a collection of pseudo point sources ( $I = \Phi \cos{\theta/\omega}$ )



## Irradiance from an extended source (on-axis)



**The irradiance depends only on** *L* **and the solid angle of the source from the point on the plane.**

Irradiance at the plane from each point source (for  $d \gg a$ ) is  $I/d^2$ .

The intensity is  $I = L \Delta A$ , where ∆*A* is the "area" of each point source.

Sum over all point sources

$$
E = \frac{L\sum\Delta A}{d^2} = \frac{LA}{d^2} = L\omega
$$



#### Irradiance from an extended source (off-axis)



is smaller:  $\omega_1 \cos^3 \theta$ θ  $\omega_2 = \frac{A\cos\theta}{l^2} = \omega_1 \cos^3\theta$ 2  $\omega_2 = \frac{12}{d^2}$  =  $\omega_1$  cos cos  $=\frac{A\cos\theta}{d^2/2}$ 

As before, we have to remember the area on the plane is tilted by  $\theta$ :

$$
E_2 = E_1 \left[ \cos^3 \theta \right] \left[ \frac{A}{A} \right] = E_1 \cos^4 \theta
$$

**The irradiance distribution in a plane from an extended Lambertian source drops faster than from a point source (**∝ **cos3**θ**). Known as the "cosine fourth law"**



## Angular  $\cos^4$  output of the NIST 308 mm diameter integrating sphere



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#### Spatial scan of the 308 mm sphere irradiance



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#### Invariance of radiance





#### Radiant flux transfer, arbitrary orientation



2  $\frac{2}{2}$  cos  $\sigma_2$  $p_{1-2}$  = Solid angle subtended by  $A_2$  with respect to  $A_1 \quad \omega_{1-2} = \frac{A_2 \cdot \cos A_1}{12}$ *d*  $\omega_{1-2}$  = Solid angle subtended by  $A_2$  with respect to  $A_1$   $\omega_{1-2} = \frac{A_2 \cdot \cos \theta_2}{1^2}$ 

 $=[$ Radiance · Projected area $\int_1$  ·  $[$ Solid angle $\int_{1-2}$  $=[L_1 \cdot A_1 \cdot \cos \theta_1] \cdot [\omega_{1-2}]$  $\left[ L_1 \cdot A_1 \cdot \cos \theta_1 \right] \cdot \left[ \frac{A_2 \cdot \cos \theta_2}{d^2} \right]$  $=[L_1 \cdot A_1 \cdot \cos \theta_1] \cdot \left[ \frac{A_2 \cdot \cos \theta_1}{d^2} \right]$  $Φ =$ Radiant flux in the beam  $\frac{2 \cdot \cos \theta_2}{2}$  $_1 \cdot A_1 \cdot \cos \theta_1$ cos cos *d*  $L_1 \cdot A_1 \cdot \cos \theta_1$ ].  $\frac{A_2 \cdot \cos \theta_2}{2}$ 

For real surfaces, divide the two areas into many sub-areas and carry out two dimensional integration.



#### A review so far

#### 1.Irradiance from a source on a plane

a) Point source:  $E(0) = I/d^2$  and  $E(\theta) = E(0) \cos^3 \theta$ 

b) Extended source:  $E(0) = L\omega$  and  $E(\theta) = E(0) \cos^4 \theta$ 

- 2.Radiance and extended sources
	- a) Generally,  $L(\theta) = L(0)$  [Lambertian]
	- b) Invariance of radiance:  $L_1 = L_2$  (no absorption or scatter)
	- c) Throughput =  $A_1 \cos \theta_1 [A_2 \cos \theta_2]/d^2$  for large distances
- 3.Flux transfer (the detector responds to flux)
	- a)  $\Phi = L *$  throughput
	- b)  $\Phi = E * "detector" area$

4.Look at the units



#### Irradiance at a plane, radiance to the hemisphere The plane reflects in a "diffuse" manner—so the radiance is the same in all directions (Lambertian)

Now we must divide into small areas and integrate. For the spherical element,

$$
dA_{sp} = r^2 \sin \theta \, d\theta \, d\phi
$$

Then, for each flux element,

$$
d\Phi = L \, dA \cos \theta \, \frac{r^2 \sin \theta \, d\theta \, d\phi}{r^2}
$$

Integrate over the hemisphere

$$
\frac{\Phi}{dA} = E = L \int_{0}^{2\pi} d\phi \int_{0}^{\pi/2} \cos \theta \sin \theta d\theta
$$

$$
E = L \, 2\pi \, \frac{1}{2} \left( \sin^2 \theta \right)_{0}^{\pi/2} = \pi \, L
$$





#### "Lamp-Plaque Method"



**Classic example** of irradiance to radiance transfer, for producing a source of known radiance for instrument calibration.

> $\pi$  $L = \frac{E \rho}{\rho}$



#### What matters?

#### 1.Lamp-Plaque method

- a) Distance:  $E \propto 1/d^2$ . The relative uncertainty is then ∆*E*/*E*=2∆*d*/*d*. Standard lamps ("FELs") are calibrated at 500 mm; so a 1 mm uncertainty is 0.4% in irradiance.
- b) Correct lamp current and proper baffle placement.
- 2.Calibration methods
	- a) A irradiance detector must have its field of view "underfilled" by the source; distance matters
	- b) A radiance detector must have its field of view "overfilled" by the source; distance does not matter



#### Irradiance mode (see *E* from extended source)



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## Radiance mode (see invariance of radiance)



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#### Integrating sphere examples





Calibration of sun photometers using an integrating sphere source (NASA GSFC).

An up-looking sphere source for nadir-viewing, aircraftdeployed spectroradiometers (NASA Ames).



## Radiance mode (see invariance of radiance)





#### Example: Solar constant (irradiance at Earth's surface)



#### **Sun**:

Blackbody at  $T = 5800$  K;

Lambertian;

diameter =  $6.96 \times 10^8$  m; Earth-

sun distance  $d = 1.5 \times 10^{11}$  m

#### **Earth**:

Total irradiance (all wavelengths) is of interest for Earth's energy balance and solar physics research. diameter =  $6.38 \times 10^6$  m



#### Spectral aspects of radiometry

A blackbody source obeys Planck's law



$$
L_{\lambda} = \frac{c_{1L}}{\lambda^5 \exp[c_2/(\lambda \cdot T) - 1]}
$$

$$
[\mu W / cm^2 nm \text{ sr } ]
$$

The radiance drops very sharply below a particular wavelength. As the temperature increases, the radiance increases for all wavelengths and the peak moves to shorter wavelength  $(\lambda_{\text{max}} \alpha 1/T)$ .


## Total exitance, *M*



Integrate Planck's radiance law over all wavelengths and the entire hemisphere above the exit aperture.

 $M(T) = \sigma \cdot T^4 \quad [W/m^2]$  Stefan-Boltzmann law

 $\sigma$  = 5.67 x 10<sup>-8</sup> W m<sup>-2</sup> K<sup>-4</sup>

(total exitance)

The Stefan-Boltzmann relationship is useful when the detector responds over a wide range of wavelength with a nearly constant responsivity.



#### Example: Solar constant (irradiance at Earth's surface)



#### **Sun**:

Blackbody at  $T = 5800$  K; Lambertian; diameter =  $6.96 \times 10^8$  m; Earthsun distance  $d = 1.5 \times 10^{11}$  m

#### **Earth**:

Total irradiance (all wavelengths) is of interest for Earth's energy balance and solar physics research. diameter =  $6.38 \times 10^6$  m

$$
M = \sigma T^4
$$
  
\n
$$
L_s = \frac{M}{\pi}
$$
  
\n
$$
E_e = L_s \omega_{e-s}
$$
  
\n
$$
= \frac{\sigma T^4}{\pi} \frac{A_s}{d^2}
$$

We solved this problem using the point to hemisphere throughput derivation (Slide 22) and the irradiance on a plane from an extended source (Slide 16). The answer is  $E_e = 1389$  W m<sup>-2</sup>. We must assume sun is Lambertian.



## Measurements of the solar constant



Exoatmospheric measurements using electrical substitution radiometers (ESRs)

http://spot.colorado.edu/~koppg/TSI

Latest instrument: TIM on SORCE http://lasp.colorado.edu/sorce/ Launched January 25, 2003



## Measurement Equation Approach:

In general, we use the measurement equation approach for characterizing and calibrating sources and radiometers. A simplified measurement equation is:

$$
I(A, \omega, \Delta \lambda, \lambda_{o}) = \int_{\Delta \lambda} \int_{A} \int_{\omega} S_{\phi}(x, y, \theta, \phi, \lambda, \lambda_{o}) \cdot L_{\lambda}(x, y, \theta, \phi, \lambda, \lambda_{o}) \cdot \cos \theta \cdot d\omega \cdot dA \cdot d\lambda
$$

 $I\!\left(A ,\omega ,\Delta \lambda ,\lambda _{_{o}}\right)$  - the measured current

- $S_{\phi}$  the spectral flux (power) responsivity of the detector at a position x,y
- $L_{\lambda}$  the spectral radiance of the source
- receiving area of the detector *A*
- $\omega$  the solid angle of the source viewed by the detector

#### Linearity, polarization dependences not considered in this expression but can be added.



#### References:

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# 2. Detector-based Radiometry



## **Outline**

- 1. What is Detector-based Radiometry
- 2. Detector-based Scale Realizations
	- a) Electrical Substitution Radiometers (ESR)
		- Cryogenic Radiometers
	- b) Spectral Responsivity Measurement Facilities
		- Power, irradiance, and radiance responsivity
	- c) Scale Transfer to Measurement Facilities
- 3. Application Example (SRSC Laboratory #2)
	- **Photometry** 
		- Illuminance [lux]



## What Is Detector-based Radiometry?

- Radiometric measurements using detectors whose calibration is traceable to a detector (primary) standard
- Comparison of source and detector-based scales

Source-based Detector-based





#### Fundamental Radiometric Scales





## Definition of Traceability

"property of the result of a measurement or the value of a standard whereby it can be related to stated references, usually [national](http://ts.nist.gov/Traceability/supplmatls/suppl_matls_for_nist_policy_rev.cfm%23def05) or international [standards, through an unbroken chain of](http://ts.nist.gov/Traceability/supplmatls/suppl_matls_for_nist_policy_rev.cfm%23def06)  comparisons all having [stated uncertainties.](http://ts.nist.gov/Traceability/supplmatls/suppl_matls_for_nist_policy_rev.cfm%23def07)"



#### International System of Units (SI)

- 1. Established in 1960, SI is the modern metric system of measurement used throughout the world.
- 2. SI defines three classes of units: basic, derived and supplementary. Examples
	- a) Basic: Thermodynamic temperature kelvin [K]
	- b) Derived:  $Area$ , square meter  $[m^2]$ Steradian [sr]
	- c) Supplementary: Power, watt [W]



## Radiometric Quantities (Review)

#### Radiometric quantities with their symbols and SI units

 $W = w$ att, m = meter, sr = steradian





## Electrical Substitution Radiometer (ESR)

The principle of electrical substitution radiometry is to balance the electrical and optical power [Watt] needed to create the same temperature rise in the ESR





## NIST Cryogenic Radiometer

Cryogenic temperatures allow lower degree of non-equivalence:

- 1. Larger cavity due to increased heat capacity
- 2. Reduced lead heating due to superconducting leads
- 3. Reduced temperature gradients between electrical and optical heating
- 4. Reduced background radiation







## NIST Cryogenic Radiometer

Primary Optical Watt Radiometer (POWR) is the U.S. primary standard for optical power.

Cryogenic temperatures allow lower degree of non-equivalence:

- Larger cavity due to increased heat capacity
- Reduced lead heating due to superconducting leads
- Reduced temperature gradients between electrical and optical heating
- Reduced background radiation





# Primary Optical Watt Radiometer (POWR)

- 1. Shorter calibration chain
- 2. Greater power level dynamic range ( $\mu$ W to mW)
- 3. Continuous spectral coverage  $(200 \text{ nm to } 20 \text{ µm})$
- 4. Extend IR and UV coverage
- 5. Windowless transfer, decreasing transfer uncertainties
- 6. Explore irradiance measurements
- 7. Modular design allows for modifications to meet future requirements







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Measurement Facilities for Spectral Responsivity

Two principal detector measurement facilities:

- 1. Spectral Comparator Facilities (SCF)
	- a) Monochromator based
	- b) UV SCF: 200 nm to 500 nm
	- c) Visible to Near IR SCF: 350 nm to 1800 nm
- 2. Spectral Irradiance and Radiance Calibrations using Uniform Sources Facility (SIRCUS)
	- a) Tunable laser based
	- b) 210 nm to 1800 nm (UV-Vis-NIR SIRCUS)
	- c) 1000 nm to 5000 nm (IR SIRCUS)
	- d) Various source configurations tailored to the measurement (typically an integrating sphere)



When to Use Trap Detectors

Low uncertainty transfer standard from HACR

#### 1. Advantages

- a) Uniform responsivity
- b) Polarization insensitive
- c) Reflection measurements not needed
- 2. Drawbacks
	- a) Limited field-of-view (FOV)
	- b) "Impossible" to buy
	- Hard to make
	- d) Windowless diodes, potentially unstable
	- e) Lower shunt resistance (diodes in parallel) limits gain to less than with a single photodiode

- 6 - 4 - 2 0 y [m m ]

Uniformity at 550 nm

2 4 6 - 6 - 4 - 2 0 2 4 6

 $x \text{ [m m]}$ 

 $0.6$  $0.7$  $0.8$  $0.9$ 

Relative



## Trap Detector Examples and Uniformities



Contour Lines  $= 0.2 \%$ QED-200 at 500 nm





Contour Lines  $= 0.2$  % Tunnel Trap at 500 nm









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x [mm]



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# Current SCF uncertainty from 200 nm to 1800 nm SCF (Spectral Power Responsivity) Uncertainty





## Radiometric Measurement Configurations



2. Irradiance Measurement  $E = \text{flux/collectron area} = \Phi/A_1 \text{ [W/m}^2\text{]}$ 



3. Radiance Measurement *L* = flux/projected source area/solid angle



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## NIST Aperture Area Measurement Facility

- 1. Measures the geometric area of highquality circular apertures
- 2. Uncertainty (*k*=1) <0.01 % for aperture diameters ranging from 2 mm to 30 mm
- 3. Uses a precision microscope with stage position referenced to a laser interferometer
	- Standard uncertainty in relative stage position  $<$  50 nm
- 4. A separate, flux-transfer instrument is used for measurements relative to a standard
- 5. Currently participating in an international intercomparison







Spectral Irradiance and Radiance Calibrations using Uniform Sources (SIRCUS) Facility Radiance and Irradiance Responsivity





## Filter Radiometer Example



Component Function

Aperture Defines measurement area Diffuser Maintains cosine response (optional) Filter Spectral selection Detector Power measurement

$$
i = A \int_{\lambda} E(\lambda) s(\lambda) d\lambda
$$

The signal *i* observed from such a radiometer is the aperture area *A* multiplied by the integral of the product of the spectral irradiance of the source at the aperture  $E(\lambda)$ and the meter's spectral power responsivity  $s(\lambda)$ .



## Example Photometer





## Conversion to Photometric Units

The luminous flux is related to the radiant flux by:

$$
\Phi_{\rm v}=K_{\rm m}\int_{360\,{\rm nm}}^{830\,{\rm nm}}\Phi(\lambda)V(\lambda){\rm d}\lambda
$$

 $K<sub>m</sub>$  maximum spectral luminous efficacy [683 lm/W] *V*(λ) spectral luminous efficiency function

The luminous flux can also be written:

$$
\Phi_{\rm v} = A K_{\rm m} \int_{\lambda} E(\lambda) V(\lambda) d\lambda
$$

Note: for brevity the explicit notation of the photopic wavelength range is indicated by  $\lambda$ .



Luminous Flux and Illuminance Responsivity

The luminous flux responsivity [A/lm] of a photometer:

$$
s_{v,f} = \frac{\text{signal}_{\text{out}}}{\Phi_v} = \frac{\int_{\lambda} E(\lambda) s(\lambda) d\lambda}{K_{\text{m}} \int_{\lambda} E(\lambda) V(\lambda) d\lambda}
$$

The illuminance responsivity [A/lx] of a photometer is:  $\lambda V(\lambda) d\lambda$  $\lambda$ )s $(\lambda)$ d $\lambda$ λ λ  $(\lambda) V(\lambda) d$  $(\lambda) s(\lambda) d$ m  $v,i = \Delta v_{v,f}$  $K_{_{\rm m}}$   $E(\lambda)V$  $E(\lambda)s$  $s_{v,i} = As_{v,f} = A$ ∫ ∫  $=As_{vf}$ 

Given  $s_{v,f}$  is uniform over the aperture A



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- 9. T. C. Larason and C. L. Cromer, "Sources of Error in UV Radiation Measurements," *J. Res. Natl. Inst. Stand. Technol.*, **106**, 649–656 (2001)<sup>1</sup>.

<sup>1</sup>Articles in the Journal of Research of the NIST since 1995 are available as .pdf files at [http://www.nist.gov/jres.](http://www.nist.gov/jres) 2Available as a .pdf file from NIST web pages.



# 3. Source-based Radiometry



## Radiance and Irradiance

## 1.Radiance Sources

- a) Overfill the field-of-view of the radiometer
- b) Extended source that is spatially uniform
- c) Radiance is independent of view angle
- d) Radiance is independent of distance to radiometer

#### 2.Irradiance Sources

- a) Underfill the field-of-view of the radiometer
- b) Approximate a point source (follows  $1/d^2$  law)
- c) Uniform irradiance at the entrance pupil of the radiometer



#### Planck's Law



Ideal Blackbody

 $\exp(c_2/(n\lambda T)) - 1$  $(\lambda) = \frac{c_{1L}}{c_{2.25}} \frac{1}{\sqrt{1 - \frac{c_{1L}}{c_{1L}}}}$ 2 2  $2^5$  $\sigma_{\rm b}(\lambda) = \frac{c_{\rm IL}}{n^2 \lambda^5} \frac{1}{\exp(c_2/(n\lambda T)) - 1}$  $L_{\rm b}(\lambda) = \frac{c}{\lambda}$  $\lambda^3$  explc,  $\lambda^n$  $\mathcal{\lambda}$ `

- $c_{1L}$  = first radiation constant for spectral radiance
- $n(\lambda)$  = index of refraction of medium
- (1.00029 for air,1.00028 for argon)
- $c_2$  = second radiation constant
- $\lambda$  = wavelength of radiation

 $c_{1L} = 1.191\ 042\ 722(93)$  x  $10^8$  [W  $\mu$ m<sup>4</sup> m<sup>-2</sup> sr<sup>-1</sup>]  $c_2 = 14$  387.752 (25) [µm K]

Non ideal Blackbody:  $L(\lambda) = L_b(\lambda) \varepsilon(\lambda)$ 

#### Note nonlinear relationship between Spectral Radiance and Blackbody Temperature



## Spectral aspects of radiometry

A blackbody source obeys Planck's law



$$
L_{\lambda} = \frac{c_{1L}}{\lambda^5 \exp[c_2/(\lambda \cdot T) - 1]}
$$

$$
[\mu W / cm^2 nm \text{ sr } ]
$$

The radiance drops very sharply below a particular wavelength. As the temperature increases, the radiance increases for all wavelengths and the peak moves to shorter wavelength  $(\lambda_{\text{max}} \alpha 1/T)$ .

> Blackbody sources are often used to calibrate spectroradiometers.



## Lamps vs. blackbodies



If possible, match the temperature of the blackbody and the illumination geometries to result in similar signals. In this case, the goal is to assign irradiance values to FEL lamps.

For lamp-illuminated integrating sphere sources and reflecting plaques, the spectral radiance is modified by the surface reflectance and atmospheric absorption.

i




#### Spectral Distribution, *L*<sub>b</sub>(λ)





#### Stefan-Boltzmann Law

- Total exitance *M*: sum *L*(λ) over all directions (into the hemisphere above the opening) **and** sum  $L(\lambda)$  over all the electromagnetic spectrum (all wavelengths)
- For an ideal blackbody, the spectral radiance is lambertian
- With  $\varepsilon(\lambda) \approx \varepsilon$  and  $n(\lambda) \approx n$ , the sums yield  $M = \varepsilon n^2 \sigma T^4 \cong \varepsilon \sigma T^4$  (with  $n \approx 1$ )
- $\sigma$  = Stefan-Boltzmann constant

 $\sigma$  = 5.670 400 x 10<sup>-8</sup> [W m<sup>-2</sup> K<sup>-4</sup>]



#### Problems with Blackbodies

- 1.Temperatures above 3000 K are very difficult to achieve
- 2.Expensive to produce accurate systems (testing and modeling)
- 3.Not very transportable
- 4.Slow time constants



#### Radiance Temperature vs. Bulk Temperature



Question: What are the uncertainties associated with the comparison of  $T_{TC}$  with  $T_{\lambda}$ ?

- 1. Accuracy of contact thermometer
- 2. Cavity design
- 3. Temperature gradients
- 4. Spectral and directional effects
- 5. Heat transfer losses
- 6. Diffraction losses
- 7. Reflected radiance



#### Cavity Design Exact Solution for Effective Emittance of Spherical Cavity



When the aperture angle  $\phi$  is small, the effective emittance  $\varepsilon_0$  is close to unity, even for small values of cavity surface emittance  $\varepsilon$ .

D&N-669



#### **Example of Flat Plate BB Performance**



**Wavelength, microns** 

Strongly selective spectral properties of used black paint (left figure) may lead to calibration errors up to 20 C because of difference between actual and expected (calculated using emissivity 0.95) radiance temperatures (right figure).

This BB is made by a major international manufacturer and quite common (NASA Transfer Standard)





Figure on the Left: Difference between actual temperature and the set point temperature.



### Blackbody Alternatives

- 1.Lamps, arc sources (many types), heated refractories, light emitting diodes, lasers, synchrotron radiation
- 2.Examples:
	- a) tungsten filament strip lamps
	- b) tungsten quartz-halogen lamps
	- c) deuterium  $(D_2)$  gas discharge lamps
	- d) xenon arc lamps
	- e) Nernst glower and Globar



#### Tungsten strip lamp features



- Spectral Radiance or Radiance Temperature standards
- Vacuum or Gas-filled
- Quartz or glass windows
- Good stability (especially for the vacuum type)
- Small target area (0.6 mm wide by 0.8 mm tall)
- Careful alignment procedures required
- Calibrated by comparison to a blackbody or another strip lamp at  $0.654 \mu m$
- Suited for Devices Under Test with small field-of-views



#### Emittance of Tungsten





Tungsten strip lamp output

Gas-filled Lamps (to suppress tungsten evaporation)

For Radiance Temperature



#### For Spectral Radiance





# Comparison of blackbodies and tungsten strip lamps and integrating sphere sources





# Integrating Spheres



#### 1. Features:

- a) Spherical geometry
- b) Low absorbance
- c) Diffuse reflectance

#### 2. Result

- a) Flux "averager"
- 3. Applications
	- a) Radiance source (add lamp, laser, LED, etc)
	- b) Irradiance collector
	- c) Internal or external sources and detectors



### Sphere Performance

#### 1.Flux transfer equations yield

$$
L(\lambda) = \frac{\rho(\lambda)\Phi(\lambda)}{\pi A(1 - \rho(\lambda)(1 - f))}
$$
  $f = \frac{\sum \text{port areas}}{A}$ 

2.Baffles to shield direct view of lamps

- 3.Integrated monitor detectors to record performance
- 4.Stable power supplies and reflectance of interior wall



#### Reflectance and Throughput





### Radiance of Integrating Spheres



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#### Temporal changes in the sphere output





### Sphere Source Protocols

#### 1.Geometry for uniform illumination

- a) Lamps baffle
- 2.Document operation
	- a) Lamp current, lamp voltage drop, monitor detector signals, Lamp operating hours
- 3.Keep coating clean
- 4.Recalibrate
- 5.Map spatial uniformity and dependence on view angle



## Halogen Filament Lamps



•Illumination, heating, & irradiance standards

- •Wide commercial selection
- •Select on features:
	- •lifetime
	- •color temperature
	- •lumen efficacy
	- •current or voltage
	- •built in lens
	- •base configuration
- •Maximum wavelength range: 250 nm to 2.6 µm



#### FEL Lamp Irradiance Standards

- 1000 W output
- Coiled-coil structure to increase emittance
- FEL type (a model number)
- Modified by addition of bipost base
- Calibrated by comparison to a high temperature blackbody
- 50 cm from front of post
- 1 cm<sup>2</sup> collecting area
- Selected and screened for undesirable features





### FEL alignment system





# FEL Lamp Screening

- 1. Inspect, test, anneal, age, pot into base
- 2. Spectral line screening (currently 0 % pass rate)
	- a) 250 nm to 400 nm in 0.1 nm steps with 0.04 nm bandpass (emission and absorption lines)
- 3. Temporal stability (90 % pass rate)
	- a) <0.5 % before and after 24 h continuous operation at four wavelengths in UV to near infrared
- 4. Geometric (95% pass rate)
	- a)  $\lt 1\%$  in  $+1^\circ$  at 655 nm



## FEL Output



#### Undesirable Lines

240 260 280 300 320 340 360 380 400 420

Wavelength [nm]

#### Calibration Data, FEL at 8.2 A





 $\Omega$ 

1

2

3

Signal [V]

4

5

#### Dependence on horizontal and vertical angles Percent different from center





#### Power Supply Feedback Loop





## Lamp Orientations





#### Orientation dependence of the FEL



Frame, Lamp, and Radiometer



#### Protocols for FEL Standard Lamps

- 1. Orientation
	- a) 50 cm from front of posts, entrance pupil diameter of 1 cm2, use special alignment jig for FELs
- 2. Electrical
	- a) maintain polarity, constant current, log voltage drop and burning hours
	- b) Similar sensitivity to error in current as strip lamps
- 3. Operational
	- a) 30 min warm-up; recalibrate every 50 h
	- b) transfer to user working standards
	- c) don't touch the envelope; don't enclose the lamp during operation; baffle properly



# $D<sub>2</sub>$  Irradiance Standards



- •30 W output
- Stable relative spectral irradiance distribution
- 200 nm to 350 nm
- Modified by addition of bipost base (same as FEL)
- Calibrated by a) relative distribution from wall stabilized hydrogen arc and b) FEL at 250 nm
- 50 cm from front of post
- 1 cm<sup>2</sup> collecting area
- Selected and screened for undesirable features



#### Deuterium, Xe and FEL





#### NIST uncertainties  $(k=1)$  (lowest in the world)





# 4. Properties of Detectors



# **Outline**

- 1. Radiometric characteristics of photodiodes
- 2. Electronic characteristics of photodiodes
- 3. Comparison of basic detector characteristics
- 4. PMTs
- 5. Selection of detectors for different applications
- 6. Selection of signal meters for different detectors



# Radiometric characteristics of photodiodes

- **1. Internal Quantum Efficiency (IQE),**
- **2. External Quantum Efficiency (EQE), and**
- **3. Spectral Responsivity s(**λ**) of Quantum Detectors**
- **4. Noise Equivalent Power (NEP) and D\***
- **5. Radiometric Sensitivity, Photons/s**
- **6. Response Linearity of Photodiodes**
- **7. Spatial and Angular Responsivities**
- **8. Temperature Dependent Responsivity**



#### IQE, EQE, and  $s(\lambda)$  of quantum detectors

**Number of collected electrons**  $IQE = -$ **Number of absorbed photons**

 $EQE = (1-\rho) IQE$ 

**where** ρ **is the reflectance;**

**The power responsivity is:** *e* λ  $s(\lambda) = EQE$   $\longrightarrow$   $=$   $EQE * \lambda * const.$ *h c*



#### **Spectral power responsivity of frequently used photodiodes**



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#### Spectral responsivity variations within the same model

**Hamamatsu Model S1226-8BQ photodiodes**




Noise Equivalent Power (NEP) and D\* of detectors



where, S is the detector output signal for P incident radiant power, R is the detector responsivity, and N is the detector output noise.

$$
\mathbf{D}^* = \frac{\mathbf{A}^{1/2}}{\mathbf{N} \mathbf{E} \mathbf{P}} \quad [\text{cm} \ \mathbf{Hz}^{1/2}/\mathbf{W}],
$$

where A is the detector area.



#### **Spatial response of large-area photodiodes**



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### Angular response of a 1337 Si photodiode





### Temperature dependent responsivity of photodiodes





Fundamental electronic characteristics of detectors and photocurrent meters

- 1. Photodiode shunt resistance
- 2. Linear photocurrent measurements
- 3. Noise and drift
- 4. Settling time
- 5. Stability



#### Photodiode (PV) shunt-resistance





#### Linear PV photo-current measurement



**1. Example:** For  $R=10$  G $\Omega$  and open-loop gain A= $10^6$ ,  $R_1=10$  k $\Omega$ .  $R<sub>S</sub>=10$  M $\Omega$  is needed to obtain 0.1 % non-linearity.



#### Detector noise sources

- **1. Photon noise:** noise contained in the signal and noise due to background radiation
- **2. Detector-generated noise:**
	- **Johnson:** thermal motion of charged particles and thermal current fluctuations in resistors
	- **Shot:** in (PV) detectors with P-N junction (variance in the rate of photoelectron generation)
	- **G-R:** in PC detectors produced by fluctuations in the generation and recombination of current carriers
	- **1/f:** caused by non-perfect conductive contact and bias current or voltage in detectors
- **3. Preamplifier noise: Johnson, Shot, G-R, 1/f** and
	- **Phonon:** from temperature changes not caused by the detected radiation



#### Equivalent PV circuit showing the main noise components

The feedback impedance, *R* and *C*, of operational amplifier, OA, converts the photocurrent  $I_p$  of photodiode P into a voltage *V*.  $R_s$  and  $C_j$  are the photodiode impedance. Single circles illustrate voltage sources and double circles illustrate current sources. One signal (the photocurrent) source and three noise sources (voltage noise VN, current noise IN, and resistor noise RN) are shown in the circuit.





### Output total-noise measured in dark



Dark noise with S1226-8BQ photodiode  $(R_s = 7 \text{ G}\Omega)$  and OPA128LM. **The integration time of the DVM at the I-V output is 1.7 s.**



#### Settling time of a Si photodiode current meter using Model S1226 ( $R_s$ =7 GΩ) and OPA128LM



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### Long term stability of Si photometers





#### **Comparison of typical characteristics of radiometric quality detectors within the 200 nm to 20 µm range**





### Photomultiplier Tubes (PMT)

#### **Advantages:**

- Multiplication of secondary-electrons :
	- $\checkmark$  Extremely high responsivity
	- $\checkmark$  Exceptionally low noise
- Large photosensitive area
- Fast time response
- Virtually ideal constant-current source (very high shunt resistance)

#### **Disadvantages:**

- Poor spatial response uniformity
- Temperature dependent responsivity
- Fatigue and hysteresis (overshoot or undershoot for high-voltage and light )
- High-voltage, temperature, illumination, and time dependent dark-current
- Very stable high-voltage is required
- Affected by magnetic fields
- Drift and aging
- Linear and stable operation only at low signal levels



#### DC and AC PMT measurements



The current of the R voltage dividers must be much larger than  $I_{\mathbf{a}}$ !



### Comparison of PMT to Si photodiode



$$
N_{PMT} = \sqrt{2el_{ad}K\Delta f} = 54pA \qquad [W]
$$

where *e* is the elementary electron charge,  $I_{\text{ad}}$  is the PMT anode dark current [A], *K* is the PMT current amplification, and ∆*f* is the electrical bandwidth [Hz].



### Selection of detectors for different applications

- Radiant power measurement:
	- $\checkmark$  Detectors with high spatial-response uniformity are needed
- Irradiance and radiance measurements:
	- $\checkmark$  Spatially non-uniform detectors can be used with uniform sources
- Photometric and color measurements:
	- $\checkmark$  Si photodiodes should be used
- **UV** measurements:
	- $\checkmark$  Passivating Nitrided Oxides or Pt-Silicide front layers eliminate UV damage
- Scale extension to UV and IR:
	- $\checkmark$  Pyroelectric detectors and bolometers with high spatial-response uniformity
- SW-IR measurements  $(1 \mu m)$  to  $5 \mu m$ ):
	- $\checkmark$  NIR photodiodes, extended InGaAs and InSb photodiodes are preferred
- LW-IR measurements  $(5 \mu m)$  to  $20 \mu m$ ):
	- $\checkmark$  HgCdTe detectors, pyroelectric detectors, and cryogenic bolometers



### Scheme of optical radiation measurements

Matching preamplifier to a selected photodiode will dominate the performance (signal-to-noise ratio) of the overall measurement !





Frequency dependence of photodiodes

- The **internal speed** depends on the
	- $\checkmark$  Time to convert the accumulated charge into current
- The **maximum frequency** depends on the
	- $\checkmark$  Area of the photodiode
	- $\checkmark$  Type of material
- The **internal capacitance**  $C_i$  depends on the
	- $\checkmark$  Active area
	- $\checkmark$  Resistivity (can change from 1 Ωcm to 10 kΩcm for Si)
	- $\checkmark$  Reverse voltage



## Frequency dependence of photodiodes (cont.)

• **Time constant** of a photodiode

(with one dominating internal capacitance *C*<sup>j</sup> ):

 $\tau = C_{\rm j} R_{\rm L}$ where  $R_{\text{L}}$  is the load-resistance

• **Rise time** (for photodiodes with multiple time constants): The current changes from 10 % to 90 %



### Frequency dependence of photodiodes (cont.)



If the photodiode (shunt) resistance is much larger than  $R_{\text{L}}$ , the voltage on  $R_L$  is:  $V = I R_L / (1 + j\omega C_j R_L)$ The **upper roll-off frequency** is  $f_0 = \omega_0/2\pi = 1/2\pi C_j R_L$ where  $\omega_0 = 1/\tau$ , and I is the photocurrent. For *C*<sub>i</sub> =1 nF and *R*<sub>L</sub>=1 kΩ, *f*<sub>0</sub> = 160 kHz



AC (chopped) radiation measurement Chopping is needed to tune out measurement from the 1/*f* noise range (close to 0 Hz) and the eliminate DC background signal in infrared measurements. **Chopped measurements need partial frequency compensations !**

- **-** τ**1=***RC* **must be small to keep the roll-off higher than the signal frequency**
- **- Photodiode with small**  $C_i$  **is needed to decrease**  $\tau_2$ **, e.g. Hamamatsu S5226-8BQ**
- **- Wide band (high open loop gain and low noise) OPA is needed, e.g. OPA627.**



### AC (chopped) radiation measurement (cont.)

• **Signal gain curves (measured)**. The 3 dB roll-off frequencies for all gains are 80 Hz or higher except for gain  $10^{10}$  V/A.



**Partial compensations were made for all the signal gains shown here. No compensation was made for 1010 V/A. The operating point should be on the flat parts of the curves at 10 Hz chopping (or frequency stabilized chopper is needed) !**



## AC measurements with chopper and lockin

**Chopper:** 1. tunes out the signal (by modulation) from  $1/f$  noise and drift

> 2. Separates the signal to be measured from the DC background signal

- **Frequency:** needs to be stable if the operating point is on the slope of the signal-gain versus frequency curve
- Lockin: phase controlled rectifier + low-pass filter
	- **Phase control:** synchronized from chopper
	- **Low-pass filter:** smoothes out the rectified (structured but DC) signal
	- *Output:* in-phase and quadrature (X and Y) components of the signal (in rectangular form), or magnitude  $M=(X^2+Y^2)^{1/2}$  and phase  $\Phi$  (in polar form)
	- $\checkmark$  Input: sine or square wave. The sine wave measurement selects the fundamental frequency component of the chopped waveform.



#### Sine wave lockin measures square wave Calibration of the lockin reading against a DVM.

Signal to be measured:



- Theoretical reading of sine-wave lockin:  $S_1 =$ *H* 2 4  $\pi$ = 0.9003*H*
- Reference reading of a DVM in DCV mode (with large S/N):  $S_2 = H$  with running chopper, or  $S_2 = 2H$  if the chopper is stopped
- The real correction factor is the ratio of the lockin reading to the DVM reading:  $S_1/S_2$



### Selection of commercial signal meters for detectors

- DC or AC photocurrent from photodiodes:
	- $\checkmark$  Electrometers, current preamplifiers, and picoammeters can be used
	- $\checkmark$  The typical shunt resistance of a DVM in DC-I mode is 1 kQ in the lowest (300 µA f.s.) range. The input shunt resistance can be higher for DMMs. A "Burden" voltage of about 0.2 V can develop on this resistance causing an error in the measured current. The lower the detector resistance the larger the error.

#### **DO NOT DO THIS:**

- V-measurement on detectors or load resistors:
	- $\checkmark$  Non-linearity with biased PC detectors
	- $\checkmark$  High non-linearity with photodiodes (measurement along the V-axis of the I-V curve)
- Photodiode shunt resistance measurement with ohm-meters (A large current would be forced through the photodiode!)



# 5. Determining Measurement Uncertainties



## **Outline**

- 1. Measurement Uncertainty, Measurement Error
- 2. Accuracy & Precision
- 3. Measurement Equation
- 4. Measurement Steps
- 5. Direct Methods for Uncertainty Propagation
- 6. GUM Supplement 1



### Measurement Equation Approach:

In general, we use the measurement equation approach for characterizing and calibrating sources and radiometers. A simplified measurement equation is:

$$
I(A, \omega, \Delta \lambda, \lambda_{o}) = \int_{\Delta \lambda} \int_{A} S_{\phi}(x, y, \theta, \phi, \lambda, \lambda_{o}) \cdot L_{\lambda}(x, y, \theta, \phi, \lambda, \lambda_{o}) \cdot \cos \theta \cdot d\omega \cdot dA \cdot d\lambda
$$

 $I\!\left(A ,\omega ,\Delta \lambda ,\lambda _{_{o}}\right)$  - the measured current

 $S_{\phi}$  - the spectral flux (power) responsivity of the detector at a position x,y

- $L_{\lambda}$  the spectral radiance of the source
- receiving area of the detector *A*
- $\omega$  the solid angle of the source viewed by the detector



### Measurement Uncertainty

Measurement result is complete only when a quantitative estimate of the uncertainty in the measurement is stated.

The "true value" of the measurand is the value of the measurand.

#### Formal definition

*Uncertainty of measurement* is a parameter, associated with the result of a measurement, that characterizes the dispersion of the values that could reasonably be attributed to the measurand.

#### "Expressed as a standard deviation (*u*)*"*



### Why do you need an uncertainty budget?

Traceability- "Property of the result of a measurement or the value of a standard whereby it can be related to stated references, usually national or international standards, through an unbroken chain of comparisons, all having stated uncertainties."

ISO *International Vocabulary of Basic and General Terms in Metrology*, 2nd ed., 1993, definition 6.10

Uncertainty budget will enable one to identify the dominant terms in the uncertainties to reduce those terms.



### Repeatability and Reproducibility





### Accuracy and Precision

#### Accuracy

Closeness of agreement between the result of a measurement and the value of the measurand.

#### Precision

Closeness of agreement between the results of measurements of the same measurand.



Note: The ISO Guide to Uncertainty in Measurements (GUM) discourages the use of the terms, but are still used and confused in common usage.







#### Error of Measurement

Result of a measurement minus the value of the measurand. (Sum of random and systematic errors)



#### Systematic error

Mean that would result from an infinite number of measurements of the same measurand carried out under repeatability conditions **minus** the value of the measurand.

 $x_i - x$ 



#### Error of Measurement - Illustration




# Classification of Uncertainty Components

Due to random effects (Type A) Give rise to possible random error in the unpredictable result of the current measurement process.

Usually decrease with increasing number of observations

Due to systematic effects (Type B) Give rise to possible <u>systematic</u> error in the result due to recognized effects in the current measurement process.



### Correction and Correction Factor

### Used to account for systematic error

### **Correction**

Value added algebraically to the uncorrected result of a measurement to compensate for systematic error.

Correction = - (systematic error)

### Correction Factor

Numerical factor by which the uncorrected result of a measurement is multiplied to compensate for systematic error.

E.g. Linearity, offset, shunt resistance, drift, stray light



# Standard Uncertainty

Measurand (*y*) determined from *m* input parameters  $x_i$  through functional relationship

 $f(x_1, x_2, ..., x_i, ..., x_m)$ 

**Example: Radiometer signal measurement**  $v \approx \Gamma \cdot G \cdot s(\lambda) \cdot \tau(\lambda) \cdot L(\lambda, T) \cdot \Delta \lambda$ 

Input parameters are throughput  $(\Gamma)$ , gain  $(G)$ , responsivity  $(s)$ , transmittance  $(\tau)$ , radiance (L), wavelength ( $\lambda$ ), bandwidth ( $\Delta\lambda$ ) and source temperature (T)

### **Standard uncertainty**

Estimated standard deviation associated with each input estimate  $x_i$ , denoted  $u(x_i)$ Example:  $u(\Gamma)$ ,  $u(\lambda)$ ,  $u(\Gamma)$ , etc.

Standard uncertainty  $u(x_i)$  determined from probability distribution (P) of parameter  $(x_i)$ 





# Normal Probability Distribution





## Evaluation of Uncertainty

### Two Categories: Type A and Type B

Type A Evaluated using statistical methods for analyzing the measurements.

**Examples:** Standard deviation of a series of independent observations, Least squares fit

Type B Evaluated by methods other than statistical.

**Examples:** Scientific judgment,experience, manufacturer's specification, data from other sources (reports, handbooks)



### Statistical Parameter – Sample Mean





### Statistical Parameter – Sample Variance

Variance: 
$$
\sigma^2(x_{i,k}) = \frac{1}{n-1} \sum_{k=1}^n (x_{i,k} - x_i)^2
$$

Sum of the squares of the deviations of the sample values  $(x_{i,k})$  from the mean value  $(x_i)$ , divided by  $(n - 1)$ .

Measures the spread or dispersion of the sample values, and is positive.

Variance of the mean 
$$
\sigma^2(x_i) = \frac{\sigma^2(x_{i,k})}{n}
$$

**Example:** Five voltage readings: 0.9, 1.2, 1.1, 0.8, 1.0; Sample mean = 1.0 [V]

**Variance** =  $[(0.9-1.0)^2 + (1.2-1.0)^2 + (1.1-1.0)^2 + (0.8-1.0)^2 + (1.0-1.0)^2]/(5-1) = 0.025$  [V<sup>2</sup>] **Variance of the mean** =  $0.025/5$  =  $0.005$  [V<sup>2</sup>]



# Type A Evaluation of Standard Uncertainty

**Standard deviation = (Variance)<sup>** $1/2$ **</sup> =**  $\sigma(x_{i,k})$ (Positive square root of the sample variance)

**Standard deviation of the mean:**  $\sigma(x_i) = \sigma(x_{i,k}) / n^{1/2}$ 

**Standard uncertainty**  $u(x_i) = \sigma(x_i)$ 

(Standard deviation divided by the square root of the number of samples) **Relative standard uncertainty =**  $u(x_i)/x_i$ 

**Example:** Five voltage readings: 0.9, 1.2, 1.1, 0.8, 1.0 Sample mean = 1.0 [V], Variance = 0.025 [V<sup>2</sup>], Variance of the mean = 0.005 [V<sup>2</sup>]

**Standard deviation** =  $(Variance)^{1/2} = 0.025^{1/2} = 0.158$  [V] **Standard uncertainty** = Standard deviation of the mean =  $0.158/5^{1/2} = 0.071$  [V] **Relative standard uncertainty** =  $0.071/1.0 = 0.071$ 



# Type B Evaluation of Standard Uncertainty

**Evaluated based on scientific judgment, experience, manufacturer's specification, data from other sources (reports, handbooks)**

### Examples

Convert a quoted uncertainty (with a stated multiple) to a standard uncertainty by dividing by the multiple

Convert a quoted uncertainty (with a specified confidence level, such as 95 % or 99 %) to a standard uncertainty by dividing by the appropriate factor for a normal distribution **Computational methods**

Model the quantity by an assumed probability distribution such as normal, rectangular or triangular.



# Type B Calculation – Normal Distribution



Estimated the lower limit  $(a_+)$ , and the upper limit  $(a_+)$  of the quantity. Best estimated value of the quantity (mean) = center of the limits

**50.0** % probability, value lies in the interval  $a_$  to  $a_+$ , then  $u(x_i) = 1.48$  *a* **67.7** % probability, value lies in the interval  $a_$  to  $a_+$ , then  $u(x_i) = a$ **99.7** % probability, value lies in the interval  $a_$  to  $a_+$ , then  $u(x_i) = a/3$ 



# Type B Calculation – Rectangular Distribution

### **Equal probability the value lies in the interval** *a***<sub>c</sub> and**  $a_+$  **is 100 % and zero outside**

(Reasonable default model in the absence of any other information)





## Type B Calculation – Triangular Distribution

### **Probability the value lies in the interval** *a***<sub>c</sub> and**  $a_+$  **is 100 % and zero outside**



 $u(x_i) = a/6^{1/2}$  or  $\text{[max-min]}/(24)^{1/2}$ 



# Expressing Measurement Uncertainty

Functional relationship between measurand and input parameters  $y = f(x_1, x_2, ..., x_i, ..., x_m)$ 

Combined standard uncertainty,  $u_c(y)$ Represents the estimated standard uncertainty of the measurand *y*. *given by* Law of Propagation of Uncertainty

$$
u_c^2(y) = \sum_{i=1}^m \left(\frac{\partial f}{\partial x_i}\right)^2 u^2(x_i) + 2 \sum_{i=1}^{m-1} \sum_{j=i+1}^m \frac{\partial f}{\partial x_i} \frac{\partial f}{\partial x_j} u(x_i, x_j)
$$

∂*f*/∂*x*<sub>*i*</sub> : sensitivity coefficient,  $u(x_i)$ : standard uncertainty of  $x_i$  $u(x_i)/x_i$ : relative standard uncertainty of  $x_i$  $u(x_i, x_j)$ : covariance of  $x_i$  and  $x_j$  =  $u(x_i)$  $(v_i \cdot x_j) \cdot r(x_i, x_j)$  $r(x_i, x_j)$ : correlation coefficient  $r = 0$ , if uncorrelated  $[-1 \le r \le 1]$ 



# Expressing Measurement Uncertainty - Example

Additive function (Two independent random variables  $x_1$  and  $x_2$ ) Use standard uncertainties to calculate combined standard uncertainty

$$
y = a \cdot x_1 + b \cdot x_2
$$
  
\n
$$
\frac{\partial y}{\partial x_1} = a \qquad \frac{\partial y}{\partial x_2} = b
$$
  
\n
$$
u_c^2(y) = a^2 \cdot u^2(x_1) + b^2 \cdot u^2(x_2)
$$

$$
y = a \cdot x_1 \cdot x_2
$$
  
\n
$$
\frac{\partial y}{\partial x_1} = a \cdot x_2 \qquad \frac{\partial y}{\partial x_2} = a \cdot x_1
$$
  
\n
$$
u_c^2(y) = a^2 \cdot x_2^2 \cdot u^2(x_1) + a^2 \cdot x_1^2 \cdot u^2(x_2)
$$
  
\n
$$
\frac{u_c^2(y)}{y^2} = \frac{u^2(x_1)}{x_1^2} + \frac{u^2(x_2)}{x_2^2}
$$

Multiplicative function (Two independent random variables  $x_1$  and  $x_2$ ) Use relative standard uncertainties to calculate combined standard uncertainty



## Example: Frequency of pendulum

$$
\omega = \sqrt{\frac{g}{\ell}} \text{ then}
$$

$$
\frac{\partial \omega}{\partial \ell} = \frac{-1}{2} \frac{\sqrt{g}}{\ell^{\frac{3}{2}}} = \frac{-1}{2} \frac{\omega}{\ell},
$$

$$
\frac{\partial \omega}{\omega} = \frac{-1}{2} \frac{\partial \ell}{\ell}
$$

The relationship between frequency, $\omega$  and length is given by the sensitivity coefficient, ½.



# Expanded Uncertainty

Measure of uncertainty defining an *interval* about the result *y* within which the measurand is confidently believed to lie.

Expanded uncertainty  $(U)$  = Coverage factor  $(k)$  **x** Combined uncertainty  $u_c(y)$ 





# Uncertainty Evaluation Procedure – Summary

1. Express functional relationship between the measurand **(***y***)** and input parameters  $(x_i)$ .

 $y = f(x_1, x_2, \ldots, x_i, \ldots, x_m)$ 

- 2. Determine values of input parameters *xi* [Statistical analysis or other means].
- 3. Evaluate standard uncertainty  $u(x_i)$  of each input  $x_i$  (Type A or Type B) technique).
- 4. Calculate the value of measurand **(***y***)** from the functional relationship [Step 1].
- 5. Determine the combined standard uncertainty  $u_c(y)$  from the standard uncertainties associated with each input parameter  $(x_i)$ . [Step 3].
- 6. Calculate the expanded standard uncertainty **(***U***)** as the combined standard uncertainty  $u_c(y)$  times the coverage factor  $(k)$ .
- 7. Report the value of the measurand *y* [Step 4] **and** specify the combined standard uncertainty  $u_c(y)$  [Step 5] or the expanded uncertainty U [Step 6].



# 6a. Applications from the NIST Short Course:

# Photometer Responsivity Calibration



### Objectives of Lab #2

- Measure the spectral power responsivity of the NIST photometer by comparison to a NIST-traceable silicon photodiode standard (STD). (Calibration)
- 2. Use the previously calibrated NIST photometer to measure the 100 W QTH lamp at about 3 m distance, and compare the measured illuminance (lux) to those found using a separatelu calibrated commercial photometer. (Validation)



# Spectral Responsivity [A/W] (Lab #2, Step 1) Lab #2 Spectral Responsivity Measurement Setup





### Application Example from Photometry (Lab #2) Traceability Chain



Realization of Detector-based Illuminance [lux]

- 1. Start with calibrated Si diode
- 2. Calibrate the spectral power responsivity of a photometer using monochromator system
- 3. Convert to illuminance responsivity using aperture (and calculation)
- 4. Calibrate Test illuminance meter with Photometer



Uncertainty Calculation Example

Application to detector calibration (Lab #2)

Signal measurement equation

$$
S_{\rm x} = \frac{V_{\rm x}}{V_{\rm s}} \cdot \frac{G_{\rm s}}{G_{\rm x}} \cdot S_{\rm s}
$$

- *S*<sub>x</sub> Spectral responsivity of test detector
- *S<sub>s</sub>* Spectral responsivity of standard detector
- *V* Voltage from test detector (x) or standard detector (s)
- *V*<sub>m</sub> Voltage from monitor detector
- *G* Amplifier gain



Illuminance Responsivity [A/lx] (Lab #2, Step 2)

$$
S_{\text{v,i}} = A \frac{\int_{\lambda} P(\lambda) s(\lambda) d\lambda}{K_{\text{m}} \int_{\lambda} P(\lambda) V(\lambda) d\lambda}
$$

- $s_{v,i}$  illuminance responsivity [A/lx] (Note:  $lx = lm/m^2$ )
- *A* area of the photometer aperture [m<sup>2</sup>]
- $P(\lambda)$  spectral power distribution of the light source (CIE Illuminant A with 2856 K Planck distribution)
- $s(\lambda)$  photometer spectral power responsivity [A/W]
- $K<sub>m</sub>$  maximum spectral luminous efficacy [683 lm/W] *V*(λ) spectral luminous efficiency function



## Illuminance Meter Calibration [lx] (Lab #2, Step 3)

The illuminance  $E_{v,p}$  [lx] measured by the photometer is:

$$
E_{\rm v,p} = \frac{V_{\rm p}}{\rho} / \frac{1}{S_{\rm v,i} G_{\rm p}}
$$

- *V*<sub>p</sub> photometer signal [V] *s*<sub>v,i</sub> illuminance responsivity [A/lx]
- $G_p$  photometer gain [V/A]

The calibration factor for the test photometer is:

$$
CF_{v,t} = \frac{E_{v,p}}{E_{v,t}}
$$

 $E_{v,t}$  illuminance measured by the test photometer [lx]



# Spectral Responsivity, *V*(λ), and Illuminant A



**National Institute of Standards and Technology** Technology Administration, U.S. Department of Commerce

# Uniformity of SRSC FR #117 with *V*(λ) Filter

### Responsivity uniformity

0.2 % contours at 555 nm; 1.1 mm beam size; 0.5 mm/Step





### Relative Responsivity<br>
Surface Plot of Responsivity Relative to Center of Active Area



## Linearity of the NIST standard photometers







**Year**



# Stability of Silicon Photodiodes

### Scale Uncertainty (*k*=1): 0.1 %

### Differences in the Vis SCF Silicon WS H626/H629 ratios from 1992 to 2002.





# **Stability of SRSC FR #117 with** *V***(λ) Filter**





### Factors Contributing to Uncertainty Detector Calibration – Lab #2





### Combined Standard Uncertainty Detector Calibration – Lab #2

#### **Law of Propagation of Uncertainties**

Using absolute uncertainties

$$
u_{\rm c}^{2}(S_{\rm x}) = \left(\frac{\mathrm{d}S_{\rm x}}{\mathrm{d}S_{\rm s}}\right)^{2} u^{2}(S_{\rm s}) + \left(\frac{\mathrm{d}S_{\rm x}}{\mathrm{d}V_{\rm x}}\right)^{2} u^{2}(V_{\rm x}) + \left(\frac{\mathrm{d}S_{\rm x}}{\mathrm{d}V_{\rm s}}\right)^{2} u^{2}(V_{\rm s}) + \dots + \left(\frac{\mathrm{d}S_{\rm x}}{\mathrm{d}\lambda}\right)^{2} u^{2}(\lambda)
$$

Using relative uncertainties

$$
\left(\frac{u_{c}(S_x)}{S_x}\right)^2 = \left(\frac{u(S_s)}{S_s}\right)^2 + \left(\frac{u(V_x)}{V_x}\right)^2 + \left(\frac{u(V_s)}{V_s}\right)^2 + \dots + \left(\frac{d(V_x/V_s)}{d\lambda} \cdot \frac{u(\lambda)}{(V_x/V_s)}\right)^2
$$



### Uncertainty Summary Detector Calibration (at 550 nm) – Lab #2





### Findings: Difference from NIST Calibration Values





### The Uncertainties - Spectral Responsivity





### Goal 2: Calibration of the Illuminance meter using the Filter Radiometer

- 1. QTH source, close to illuminant A (2856 K)
- 2. Three detectors set up to 3 m from the source.
- 3. The filter radiometer was used to calibrate the two illuminance meters
- 4. A variation of baffling was used
- 5. Two different reference planes on the illuminance meter were used


## The Uncertainties - Illuminance Responsivity





## The Uncertainties - Illuminance Meter





#### The Results of the Illuminance Meter Calibrations Day 3





# 6b. Applications from the NIST Short Course:

# Spectral irradiance to spectral radiance transfer



# Diagram of the lab setup





Calibration and Validation of spectral radiance

The spectral radiances of the FEL-plaque can be determined in two ways:

- 1. Using spectral irradiance to spectral radiance transfer knowing the 45°/0° reflectance factor of a plaque and the spectral irradiances of a standard source. (Calibration)
- 2. Using spectral radiance responsivities from the known spectral radiances of an argon-filled tungsten-strip lamp. (Validation)



Equations for spectral irradiance to radiance transfer

The irradiance at the plaque surface is given by

$$
E_F(A, \omega, \lambda, t, d) = E(50 \text{cm}) \frac{(50 + \delta)^2}{(d + \delta)^2}
$$
 (1)

If the spectral irradiance is uniform then

$$
L_{PE} = \frac{E(50cm)}{\pi} \cdot \frac{(50+\delta)^2}{(d+\delta)^2} \cdot \rho(45/0,\lambda)
$$
 (2)

Since the spectral radiance responsivities of the detector system did not change, then the spectral radiance of the plaque is also

$$
L_{PR}(\lambda) = L_R(\lambda) \cdot \frac{G_R}{v_R} \cdot \frac{v_P}{G_P}
$$
 (3)



## Uncertainty Analysis – Experiment 3





### Uncertainties of Two Methods

- 1. Lamp irradiance transfer
	- a. Lamp distance (spectrally flat)
	- b. Lamp current (spectrally dependent)
	- c. Plaque reflectance
	- d. Plaque uniformity
	- e. Signal to noise (depends on signal level (spectrally dependent))
	- f. Wavelength (spectrally dependent)
- 2. Strip lamp radiance
	- 1. Strip lamp current (spectrally dependent)
	- 2. Signals
	- 3. Wavelength

Note: need to separate systematic and random effects since both lamps are traceable back to the same primary NIST standard



#### Uncertainties from the radiance lamp transfer





#### Uncertainties of the FEL/Plaque transfer





#### Comparison of the two different routes





## References

- 1. ISO, *Guide to the Expression of Uncertainty in Measurement* (International Organization for Standardization, Geneva, Switzerland, 1993).
- 2. B. N. Taylor and C. E. Kuyatt, *Guidelines for Evaluating and Expressing the Uncertainty of NIST Measurement Results*, NIST Technical Note 1297 (1994).
- 3. EAL, *Expression of the Uncertainty of Measurement in Calibration,* EAL-R2 (European Cooperation for Accreditation of Laboratories, 1997).
- 4. <http://www.physics.nist.gov/cuu/Uncertainty/index.html>
- 5. P.R. Bevington and D.K. Robinson, *Data Reduction and Error Analysis for the Physical Sciences,*McGraw-Hill Publishing Co.



# Conclusions:

- 1. A calibration-validation plan (SI-traceable) for a satellite sensor should
	- a) Meet the calibration requirements
	- b) Describe the calibration approach (calibration)
	- c) Describe the use of on-board calibrators
	- d) Describe the system-level end-to-end calibration performance (validation)
- 2. Elements of the plan should
	- a) Answer how the calibration requirements will meet the mission and instrument requirements
	- b) Develop a sensor design and radiometric model (measurement equation)
	- c) Characterize subsystems (uncertainty analysis)
	- d) Compare model predictions and validate system level calibrations
	- e) Establish pre-launch radiometric uncertainties

From: NISTIR 7637 (2009), "Best Practice Guideline…" R. Datla et al.

