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Darboux Integrability - A Brief Historial Survey

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Darboux Integrability —

A Brief Historical Survey

Symmetry in Variational Problems and Differential Equations

Ian Anderson

Utah State University

May 22, 2011

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History Past



The classical method of Monge. Given

$$F(x, y, u, u_x, u_y) = 0 \quad \text{add} \quad G(x, y, u, u_x, u_y) = 0$$

so that $u_x = A(x, y, u)$, $u_y = B(x, y, u)$ is consistent [Jacobi, Lie].

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so that $u_x = A(x, y, u)$, $u_y = B(x, y, u)$ is consistent [Jacobi, Lie].

The generalization of the Monge method to 2nd order PDE leads to the methods of Ampère and Darboux (and [Cartan, 1910])

$$F(x, y, u, p, q, r, s, t) = 0 \quad \text{add} \quad G(x, y, u, p, q) = 0$$

$$F(x, y, u, p, q, r, s, t) = 0 \quad \text{add} \quad G(x, y, u, p, q, r, s, t) = 0$$

$$F(x, y, u, p, q, r, s, t) = 0 \quad \text{add} \quad G(3\text{rd ord}) = 0$$

The compatible equation $G = 0$ is called an intermediate integral (order, complete, general ...)

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History Past

- Goursat and his students made many detailed investigations regarding the existence of these intermediate integrals.



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- Goursat and his students made many detailed investigations regarding the existence of these intermediate integrals.
- Classification of DI systems were made for restricted classes of equations.



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- Goursat and his students made many detailed investigations regarding the existence of these intermediate integrals.
- Classification of DI systems were made for restricted classes of equations.
- In more recent times an extended classification of DI systems has been given [Sokolov].



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- Higher order symmetries and conservation laws for these equations have been studied [Sokolov, IA, Kamran, Juras, and Bieseecker].



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- Bäcklund transformations for the classical DI systems of Goursat were studied [Clelland and Ivey].



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- DI systems always appear in geometric studies of PDE and in equivalence problems [eg. D. The].



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- Higher order symmetries and conservation laws for these equations have been studied [Sokolov, IA, Kamran, Juras, and Bieseecker].
- Bäcklund transformations for the classical DI systems of Goursat were studied [Clelland and Ivey].
- DI systems always appear in geometric studies of PDE and in equivalence problems [eg. D. The].
- Many papers in the theoretical physics literature (σ -models) on integrable systems unwittingly arrive at DI systems.



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Vessiot's Fundamental Discovery

Prior to 1939, the method of Darboux was always viewed from the viewpoint of compatibility theory. The method had no group theoretic interpretation.



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This changed with a fundamental observation of Vessiot.

$$u_{xy} = e^u, \quad u_{xx} - \frac{1}{2}u_x^2 = f(x), \quad u_{yy} - \frac{1}{2}u_y^2 = g(y)$$
$$p_x = f(x) + \frac{1}{2}p^2 \quad \dot{p} = a(x) + b(x)p + c(x)p^2.$$

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This is a Riccati equation. Riccati equations are ODE of Lie type, associated to SL_2 .

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Vessiot's great idea was to turn this around. For each equation of Lie type associated to a Lie group ($\dim \leq 3$), he produced a DI equation of the form $u_{xy} = f(x, y, u, u_x, u_y)$.

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He reproduced the classical classification of Goursat and even integrated one of the equations which the master was unable to solve.

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But the groups arising in Vessiot's approach are *not* symmetry groups in the usual sense.

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Vassiliou showed that the Vessiot group for the classical DI systems could in fact be constructed by derived flag calculations.

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IA, Fels and Vassiliou built upon these ideas in a recent article which:

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IA, Fels and Vassiliou built upon these ideas in a recent article which:

- gives a far-reaching generalization of the definition of DI in terms of EDS.

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- introduces the general idea of a non-linear superposition formula for EDS.

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- gives a general derivation of the Vessiot group.

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- introduces the general idea of a non-linear superposition formula for EDS.
- gives a general derivation of the Vessiot group.
- proves that the Vessiot group is an invariant of any DI system.

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- introduces the general idea of a non-linear superposition formula for EDS.
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- proves that the Vessiot group is an invariant of any DI system.
- uses the Vessiot group to construct a non-linear superposition formula for any DI system.

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- introduces the general idea of a non-linear superposition formula for EDS.
- gives a general derivation of the Vessiot group.
- proves that the Vessiot group is an invariant of any DI system.
- uses the Vessiot group to construct a non-linear superposition formula for any DI system.
- gives a completely algorithmic integration procedure, much better than the classical one.

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Example

Starting from $u_{xy} = e^u$, the theory tells us to



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Example

Starting from $u_{xy} = e^u$, the theory tells us to

- Consider two copies of jet space

$$J^3(\mathbf{R}, \mathbf{R})[x, X, X', X'', X'''] \quad \text{and} \quad J^3(\mathbf{R}, \mathbf{R})(y, Y, Y', Y'', Y''')$$

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- Look to the diagonal action of $SL(2)$ with infinitesimal generators

$$\partial_X + \partial_Y, \quad X\partial_X + Y\partial_Y, \quad \frac{1}{2}X^2\partial_X + \frac{1}{2}Y^2\partial_Y,$$

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$$\partial_X + \partial_Y, \quad X\partial_X + Y\partial_Y, \quad \frac{1}{2}X^2\partial_X + \frac{1}{2}Y^2\partial_Y,$$

- Calculate the reduced differential system $(J^3 \times J^3)/SL(2)$, that is, calculate joint differential invariants.

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- Look to the diagonal action of $SL(2)$ with infinitesimal generators

$$\partial_X + \partial_Y, \quad X\partial_X + Y\partial_Y, \quad \frac{1}{2}X^2\partial_X + \frac{1}{2}Y^2\partial_Y,$$

- Calculate the reduced differential system $(J^3 \times J^3)/SL(2)$, that is, calculate joint differential invariants.
- In the context of this simple example, the lowest order joint differential invariant gives the general solution.

$$u = \log \frac{2X'Y'}{(X - Y)^2}$$

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Every intermediate integral for any DI system is in fact a **differential invariant** for the Vessiot group action.

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Every intermediate integral for any DI system is in fact a **differential invariant** for the Vessiot group action.

All the classical work of Goursat on studying intermediate integrals is in fact (essentially) covered by Lie's work on differential invariants and invariant differential operators [Olver].

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From this new viewpoint:

There are as many DI EDS as there are symmetry groups of differential equations!



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From this new viewpoint:

There are as many DI EDS as there are symmetry groups of differential equations!

BUT, only certain symmetry groups of very special DE will lead to DI EDS representing a desired type of equation.



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Primitive and Imprimitive Actions



We have calculated all systems of DI equations arising from vector field systems in the plane [Lie, GLKO].

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We have calculated all systems of DI equations arising from vector field systems in the plane [Lie, GLKO].

- Vessiot groups with imprimitive actions give "triangularized" DI systems – essentially known examples

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Primitive and Imprimitive Actions

We have calculated all systems of DI equations arising from vector field systems in the plane [Lie, GLKO].

- Vessiot groups with imprimitive actions give "triangularized" DI systems – essentially known examples
- Vessiot groups with primitive actions give genuinely new examples.



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The Vessiot group dictates the solvability of the Cauchy problem.

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Cauchy Problem



The Vessiot group dictates the solvability of the Cauchy problem.

- Let \mathcal{I} be a DI integrable system. If the Vessiot group is solvable then the Cauchy problem can be solved by quadratures.

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$$u_{xy} = e^u$$

$$3 * u_{xx} u_{yy}^3 + 1 = 0$$

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The subgroups of the Vessiot group can be used to construct Bäcklund transformations for any DI integrable system



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The subgroups of the Vessiot group can be used to construct Bäcklund transformations for any DI integrable system

- All previously constructed examples can easily be derived by symmetry reduction.



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The subgroups of the Vessiot group can be used to construct Bäcklund transformations for any DI integrable system

- All previously constructed examples can easily be derived by symmetry reduction.
- Many new examples can easily be derived by symmetry reduction.

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The subgroups of the Vessiot group can be used to construct Bäcklund transformations for any DI integrable system

- All previously constructed examples can easily be derived by symmetry reduction.
- Many new examples can easily be derived by symmetry reduction.
- The equation

$$u_{xy} = \frac{\sqrt{1 - u_x^2} \sqrt{1 - u_y^2}}{\sin u}$$

has Vessiot group $SO(3)$. But $SO(3)$ has no real 2 dimensional subalgebras and therefore it does not admit a 1-dimensional Bäcklund transformation to the wave equation.

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- clean up the theory of generalized symmetries for DI systems.

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- clean up the theory of generalized symmetries for DI systems.
- verify Sokolov's classification using group theoretical methods.

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- clean up the theory of generalized symmetries for DI systems.
- verify Sokolov's classification using group theoretical methods.
- analyze completely the Toda lattice systems (parabolic geometries associated to simple Lie algebras).

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- clean up the theory of generalized symmetries for DI systems.
- verify Sokolov's classification using group theoretical methods.
- analyze completely the Toda lattice systems (parabolic geometries associated to simple Lie algebras).
- study multi-soliton solutions from our group theoretic non-linear superposition viewpoint.

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- clean up the theory of generalized symmetries for DI systems.
- verify Sokolov's classification using group theoretical methods.
- analyze completely the Toda lattice systems (parabolic geometries associated to simple Lie algebras).
- study multi-soliton solutions from our group theoretic non-linear superposition viewpoint.
- decide what to do about 'parabolic' DI systems ([Cartan, 1911])

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