



## ***A CubeSat Mission for Locating and Mapping Spot Beams of GEO Comm-Satellites***

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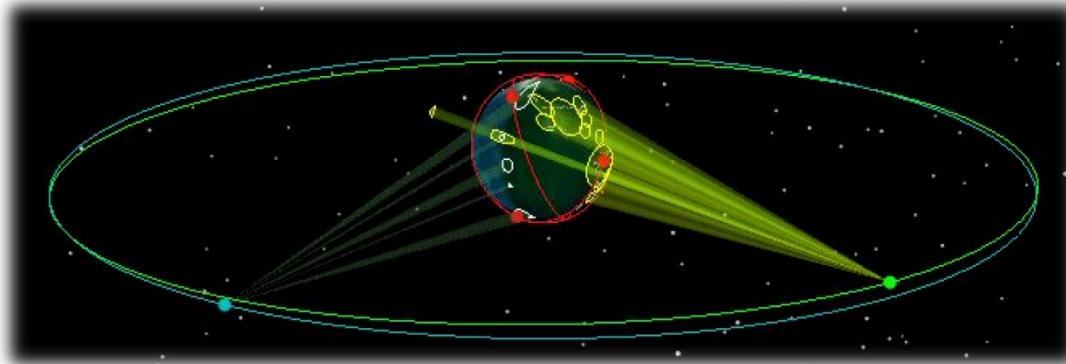
**August 9, 2015**



# Outline

*The AFIT of Today is the Air Force of Tomorrow.*

- Background & Motivation
- Spot Beam Mapping Mission + OV-1
- Design of Mission Model
- Software Tools
- Developed Simulations & Results
- Features of Operation
- Conclusion / Future Work





# Background

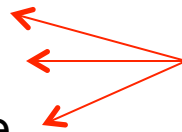


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## Radio Frequency domain verification from GEO... tied with small satellite mission development concepts

### -- Future space environment

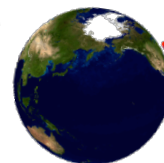
- Increased congestion
- Increasingly contested
- Increasingly competitive



**Especially at GEO!**

### -- GEO Spot beam mapping

- Analogous constellation-based RF collection missions
- Enhance RF domain knowledge
- Identify coverage areas



### -- Small Satellites (i.e. disaggregation)

- May reduce costs vs. larger space missions
- Maturing technology increases viability
- Missions include common features / architectures



# Motivation

## Spot Beam Mapping CubeSat



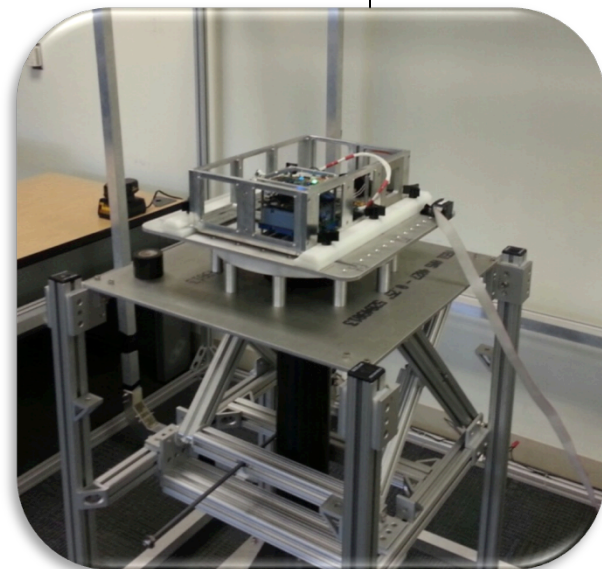
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### -- AFIT CubeSat Research

- Mission Analysis and Payload/Bus Design
- Satellite Design and Test Sequence (6U CubeSat)
  - 1) Systems Engineering
  - 2) Spacecraft Analysis & Design
  - 3) Spacecraft Build & Test

### -- RF Domain Verification / Analysis

- Identify spot beam locations (space-ground links)
- Manage frequency allocations (avoid interference)
- Improve ground trace knowledge
  - Increase link efficiency
  - Identify areas of poor signal coverage



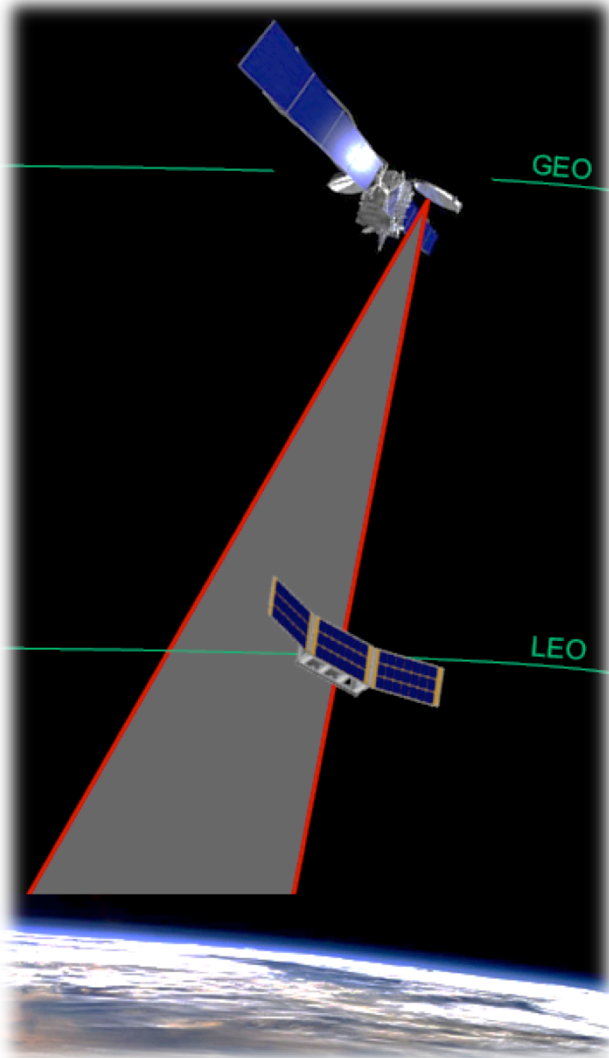
*AFIT 6U CubeSat Testbed*

**Key Focus:** Is it possible to effectively map spot beams coming from GEO Comm-Satellites using a CubeSat constellation?



# The Mission

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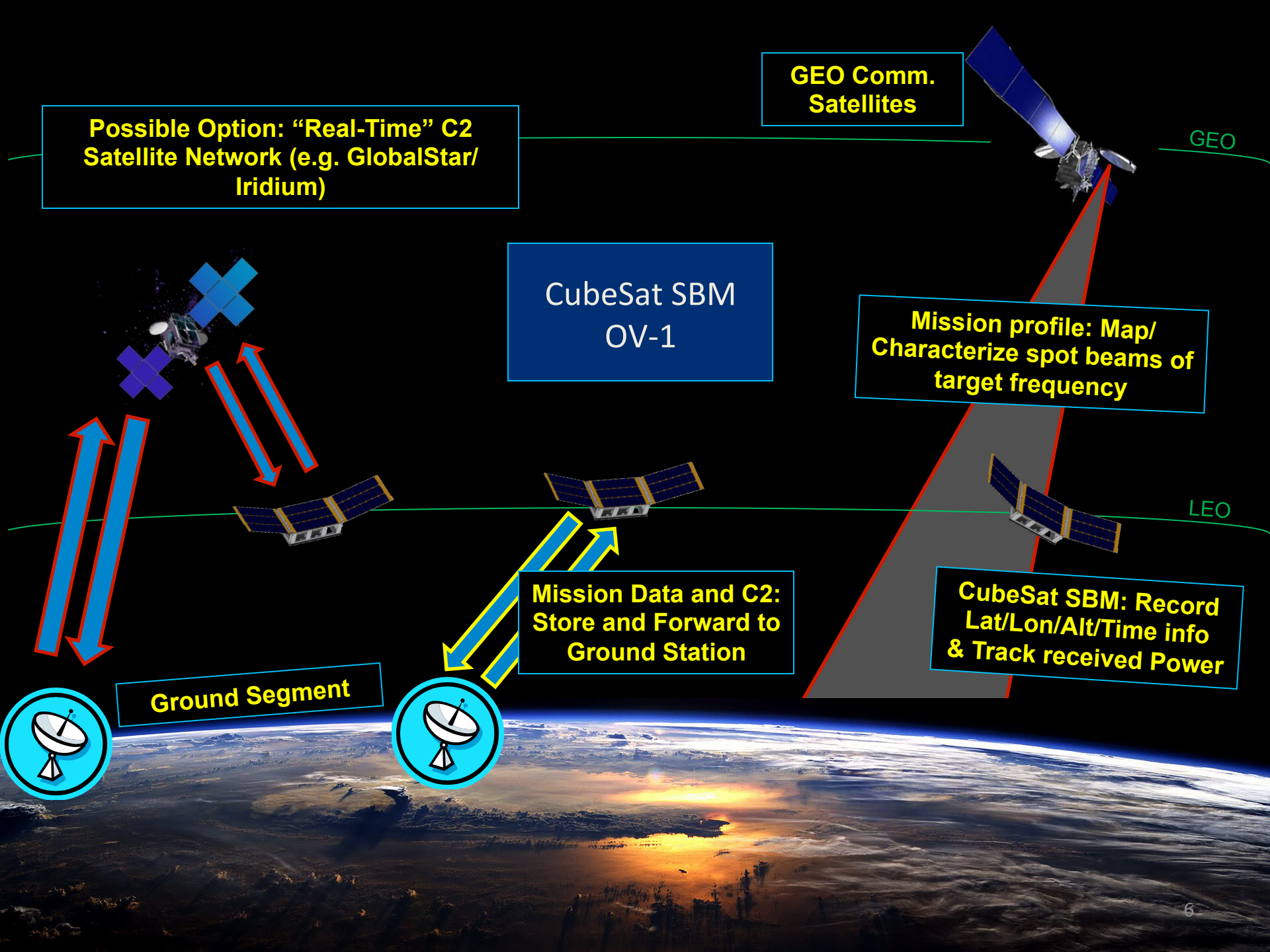
**Mission Statement:** “Detect and map the boundaries of geostationary (GEO) communications satellites spot beams by flying a CubeSat(s) through the spot beams at a low earth orbit (LEO) altitude.”

## -- Map Spot Beams from GEO

- Frequency targets up to Ka-Band
- Sizes: “Continent” size down to “Island” size

## -- CubeSat Bus / Payload

- Small/Simple form factor ==> Easy to integrate
- “Cheap,” possibly even expendable
- 6U version assumed
- Smaller Hardware Emerging
  - RF Payloads
  - “Miniaturized” Bus Subsystems



**GEO Comm. Satellites**

**Possible Option: "Real-Time" C2 Satellite Network (e.g. GlobalStar/Iridium)**

**CubeSat SBM OV-1**

**Mission profile: Map/Characterize spot beams of target frequency**

**Mission Data and C2: Store and Forward to Ground Station**

**CubeSat SBM: Record Lat/Lon/Alt/Time info & Track received Power**

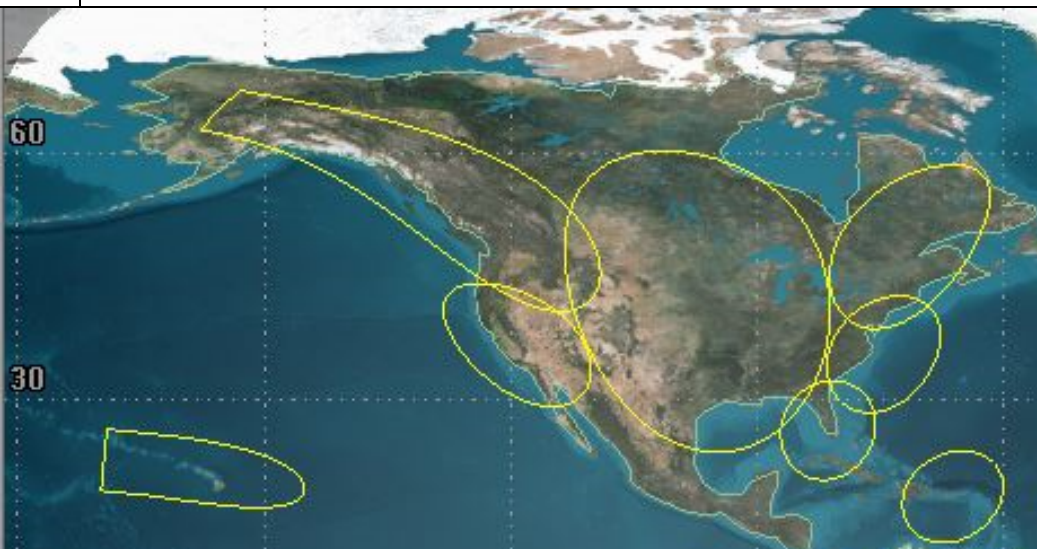
**Ground Segment**

GEO

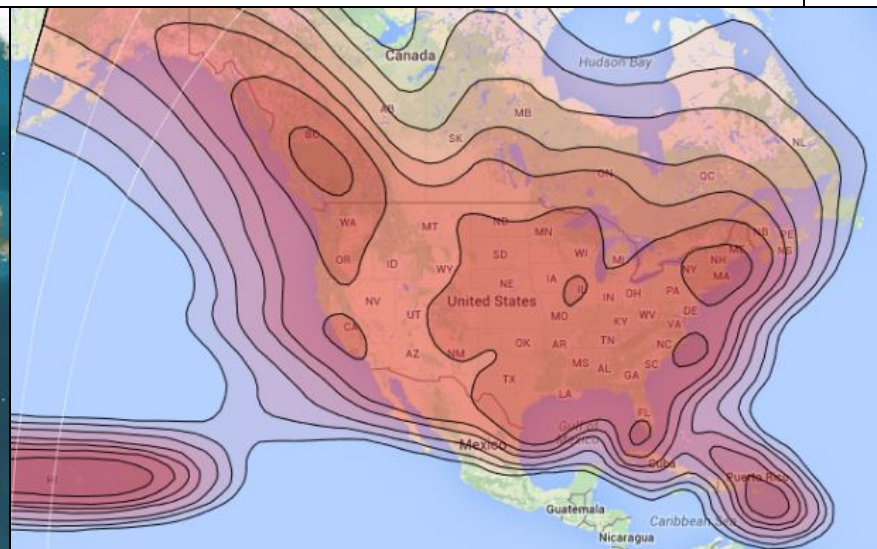
LEO

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- Objective: Simulate collections
- Model beam patterns of “realistic” spot beams
  - Chose Intelsat Galaxy 28 (G28) as a test case
  - Ku-Band beams -- North and South America (~12 GHz), HPBW
  - C-Band beams ignored (K-Band beams “harder” to find)



**Model: North American Region  
Intelsat Galaxy 28, Ku-Band Beams**



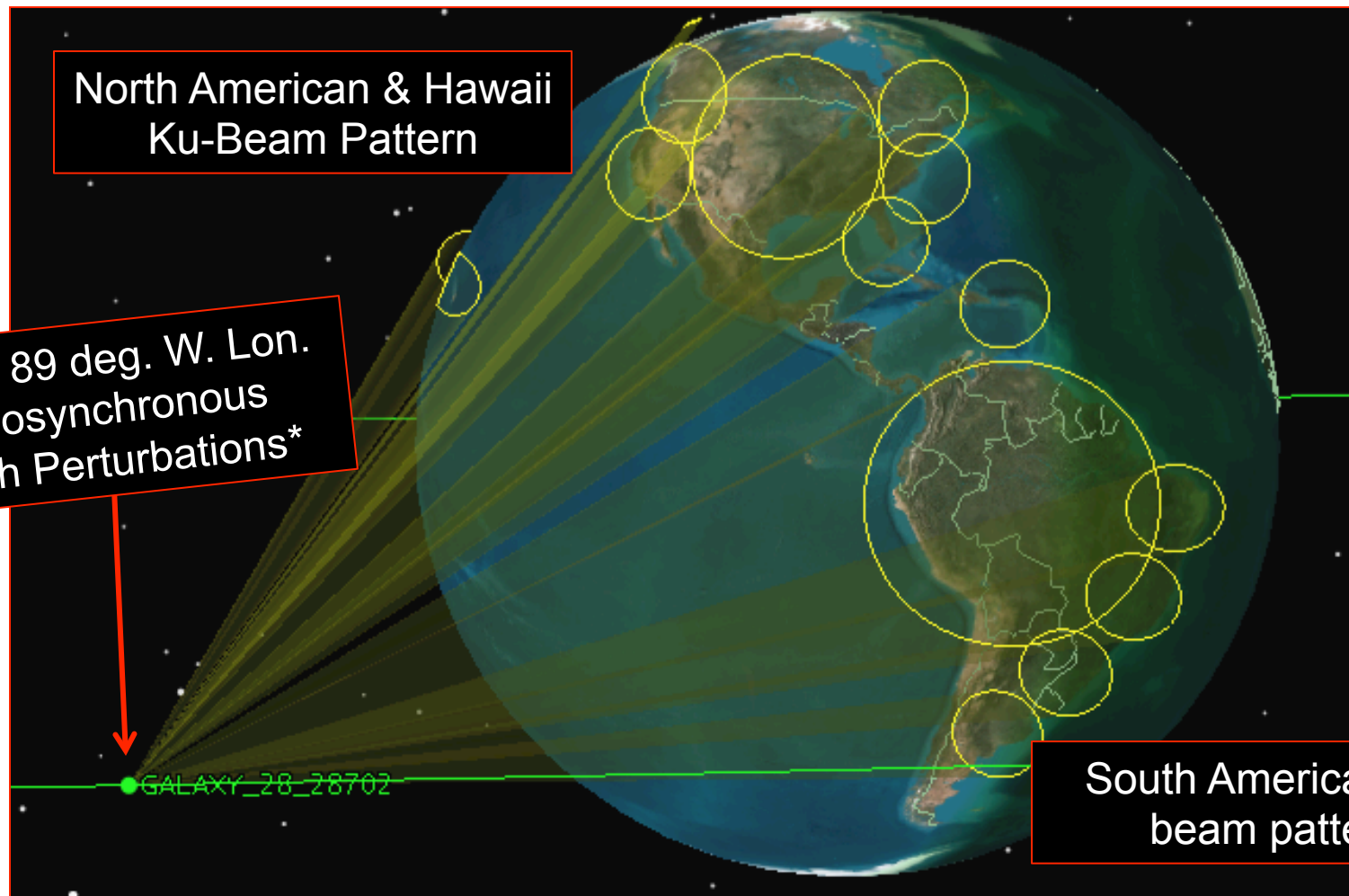
**Reference Shape: Satbeams  
Intelsat Galaxy 28, Ku-Band Beams**

*Note: Left is a spherical map projection, right is a Mercator (cylindrical) map projection!*



# Model: Galaxy 28 Beams

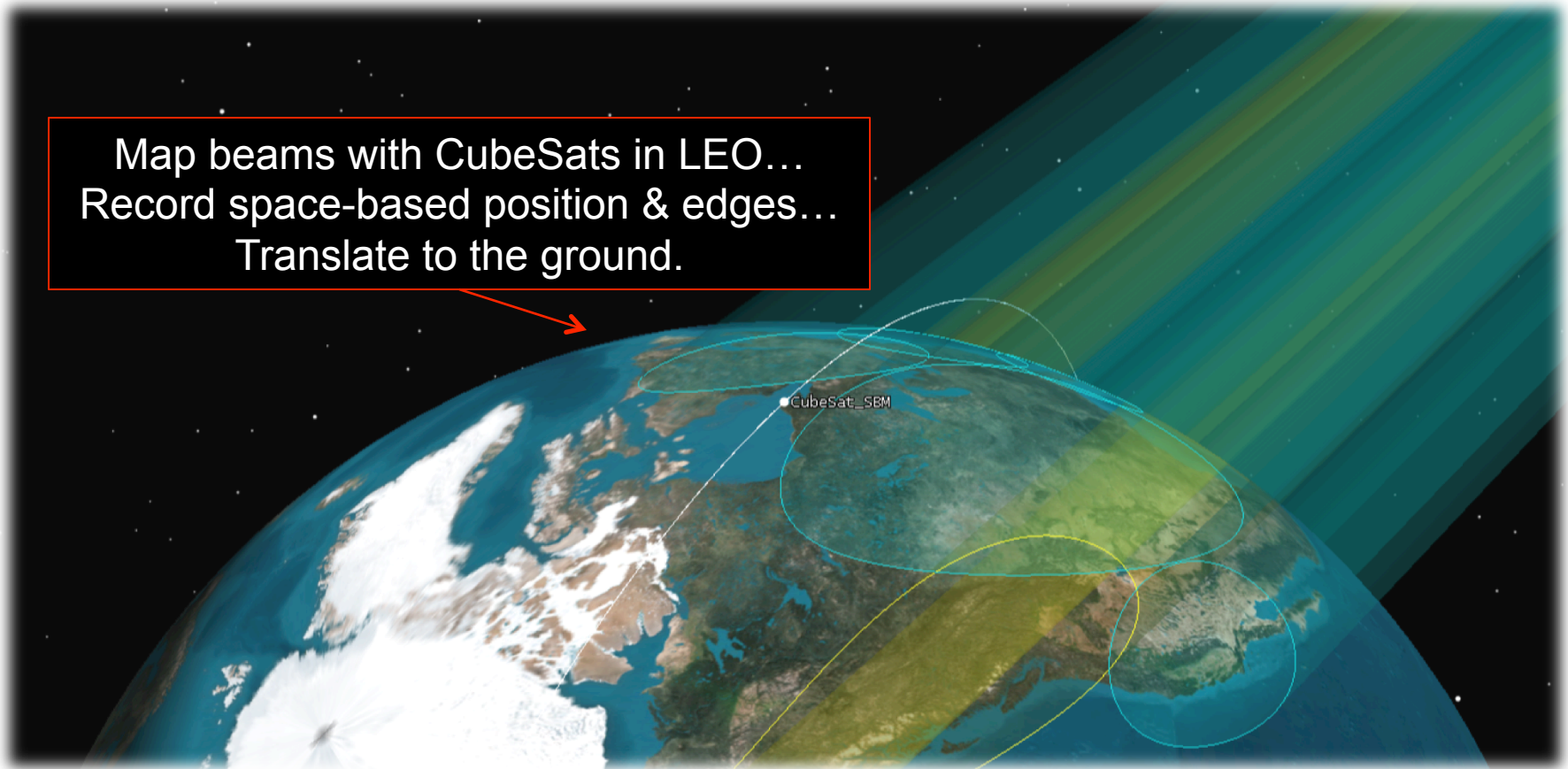
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**Full Version – Shows G-28 Position and South America Beams**

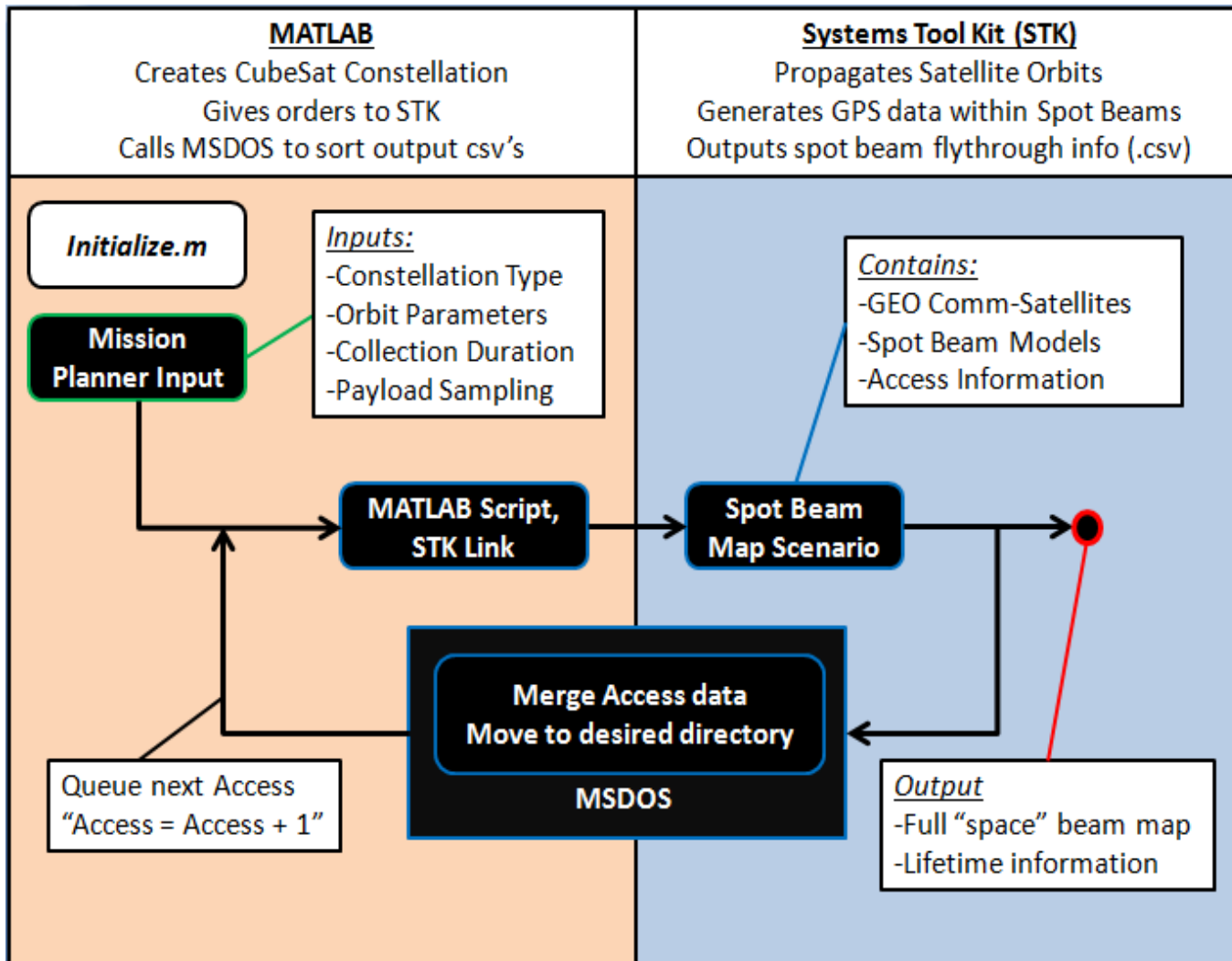
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Map beams with CubeSats in LEO...  
Record space-based position & edges...  
Translate to the ground.

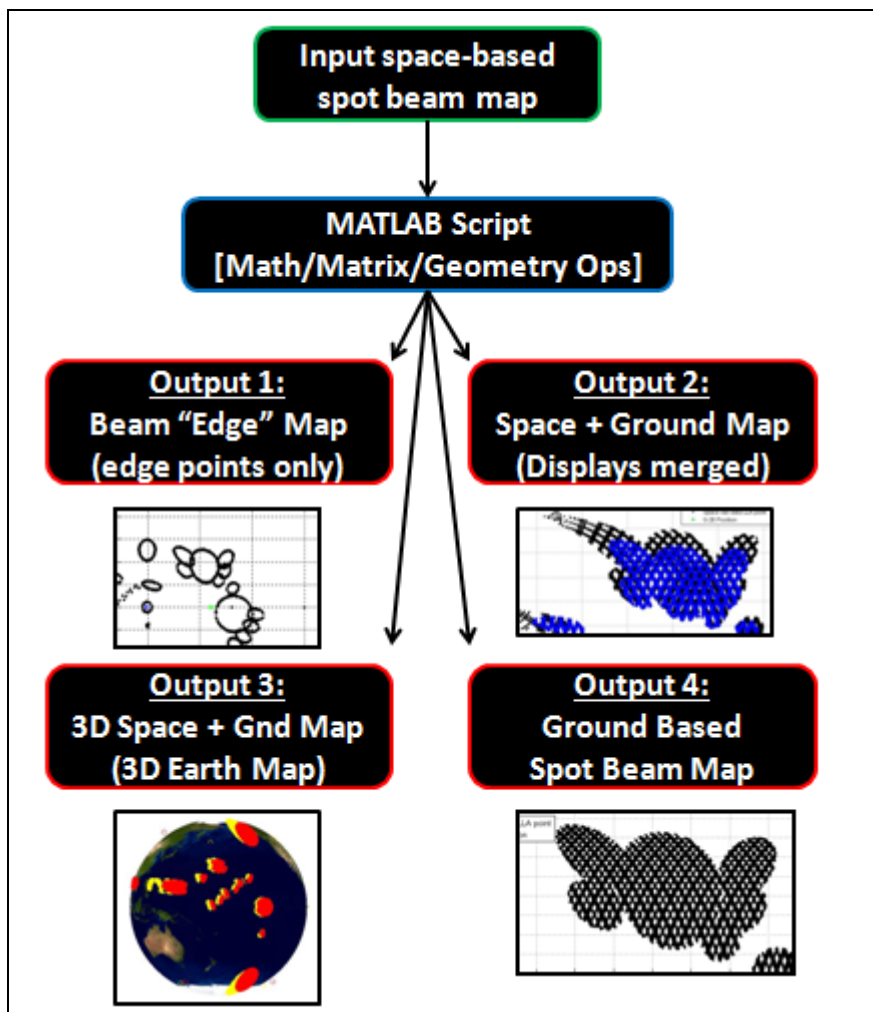


**3D Beam Pattern – Spot beam mapper in LEO**

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## Input: Mission "space" data

- Payload collection (GPS)
- Gain information

## Outputs:

- Beam edge locations
- "Full" space beam maps
- "Full" ground beam maps

## Can observe / analyze:

- Beam Patterns
- Size, position, spread of gaps
- Ground accuracy vs. STK
- Scenario change with time
- Gain patterns within beams

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## -- Constellation Types

- Single Plane
- Multi-Plane
- Walker Delta
- "Formations"

## -- Mission Altitudes

200 to 500 km

## -- Mission Inclination

68,75,82,90,98

## -- Payload Data Collection Rate

1, 5,10 seconds per data point

## -- Number of CubeSats per Plane

1-6,8

## -- Number of Orbital Planes

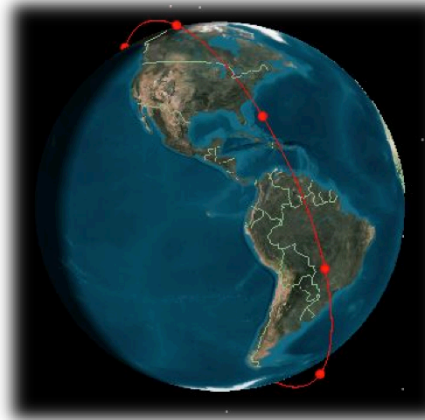
1 – 6 planes

## -- CubeSat Spacing / Plane Spacing

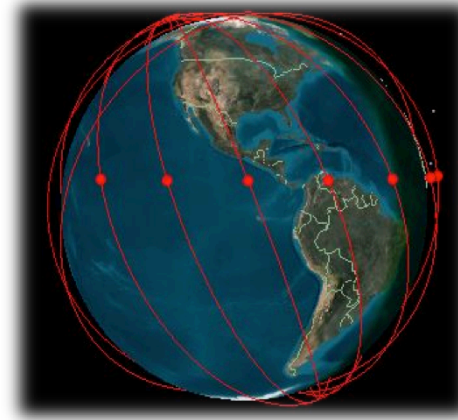
Even spacing vs. set sep. angle

## -- Collection Duration

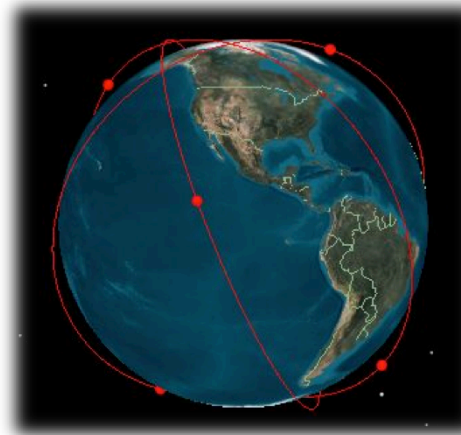
1 to 3 days



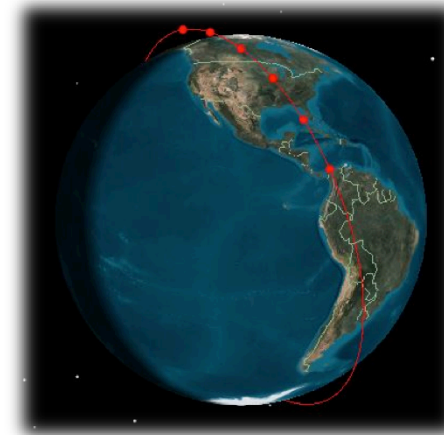
*Single Plane*



*Multiple Plane*



*Walker Delta*



*Fixed separation angle  
"Formation"*



# Simulation: Altitude Considerations



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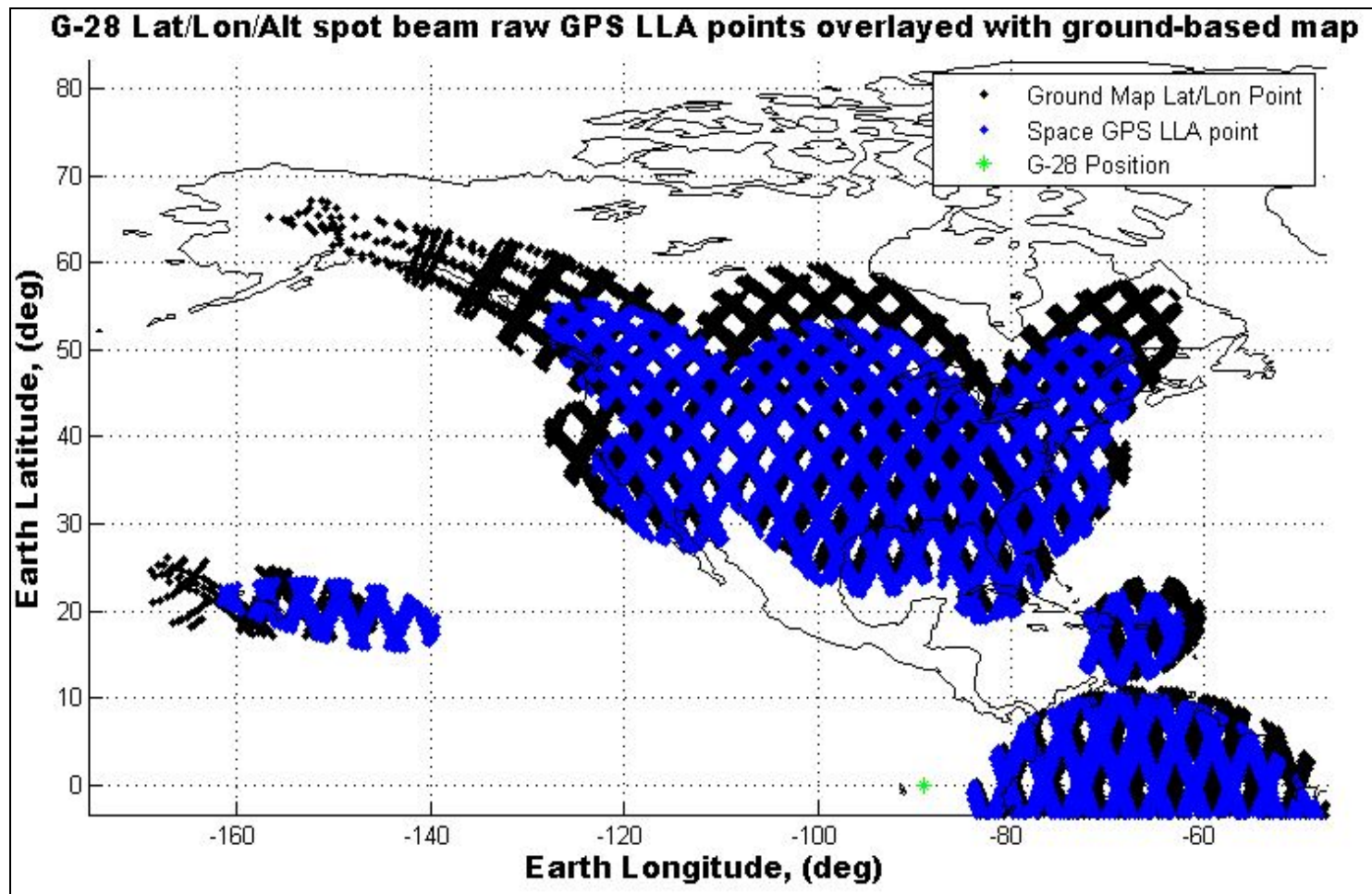
## Assumption: Fully loaded 6U CubeSat!

Orbit Altitude	Long Case Lifetime (days / years)	Intermediate Case Lifetime (days / years)	Short Case Lifetime (days / years)	Meets Mission Requirements?
200 km	9d / 0.025y	6d / 0.016y	3d / 0.008y	No
300km	167d / 0.45y	108d / 0.29y	51d / .14y	No
350km	584d / 1.6y	365d / 1y	177d / .48y	Possible
400km	2519d / 6.9y	1351d / 3.7y	548d / 1.5y	Yes
450km	5402d / 14.8y	4088d / 11.2y	2263d / 6.2y	Yes
500km	>9125d / 25y	8870d / 24.3y	4672d / 12.8y	Possible

Constant or Variable	Set Value
Drag Coefficient	2.2, models a "flat plate"
Solar Reflection Coefficient	1.0
Drag Area	0.06 square meters (short case) 0.03 square meters (intermed. case) 0.02 square meters (long case)
Satellite mass	12 kg (Fully loaded 6U) – long case 6 kg ("Light" 6U) – short case
Atmospheric Density Model	NRLMSIS-00 (Mass Spectrometer Incoherent Scatter) [37]

- 200 km: Too low
- 300 km: Too low
- 350km: Workable
- 400 km: Good
- 450 km: Good
- 500 km: Workable

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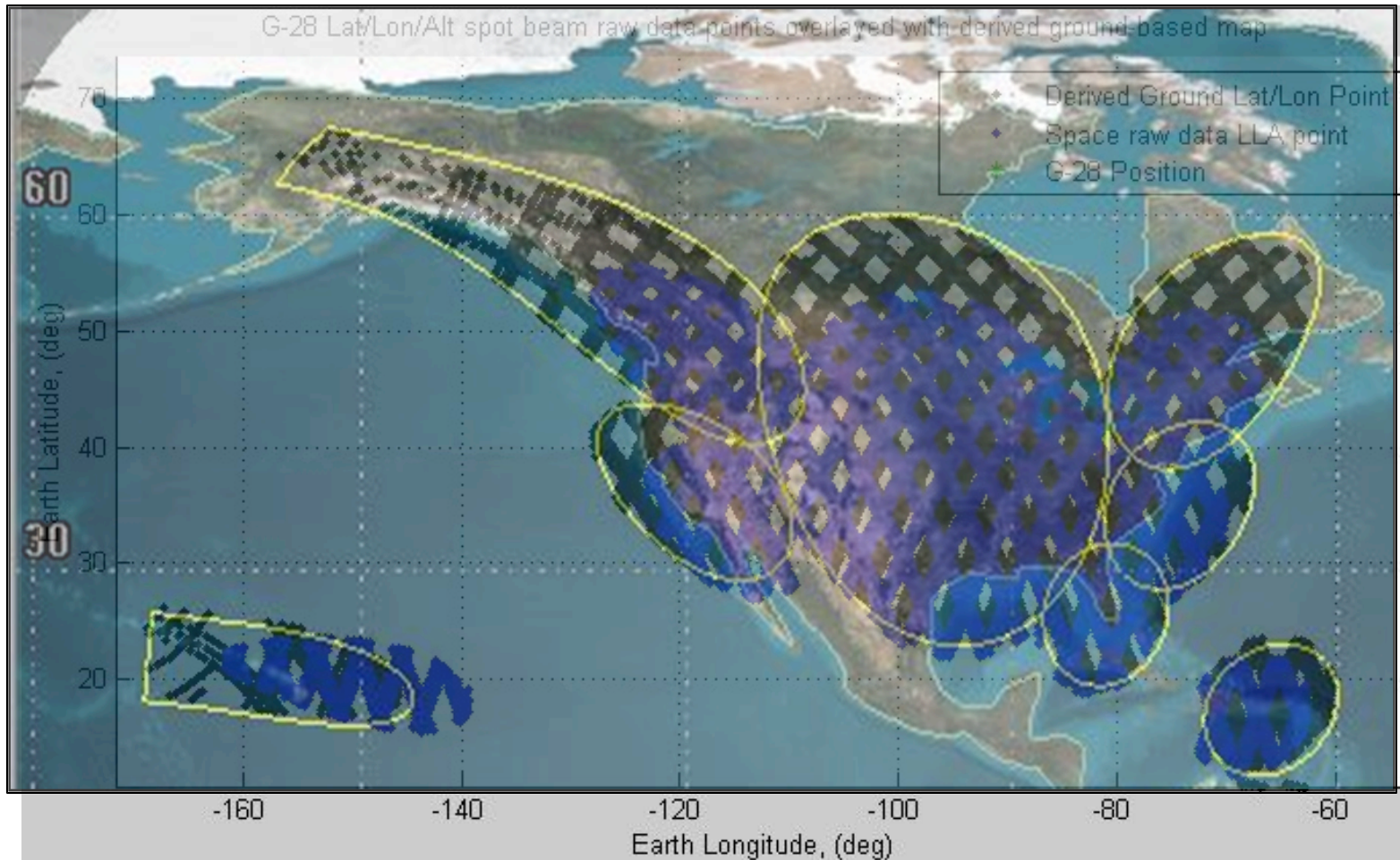


**Space-based GPS collects mapped to Ground-based points.**  
68 deg / 350 km / 0.2 Hz / 1 Plane / 6 Satellites / 72 Hour Collection



# Simulation: G-28 NA Beams Sample

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**Space-based GPS collects mapped to Ground-based points.  
68 deg / 350 km / 0.2 Hz / 1 Plane / 6 Satellites / 72 Hour Collection**

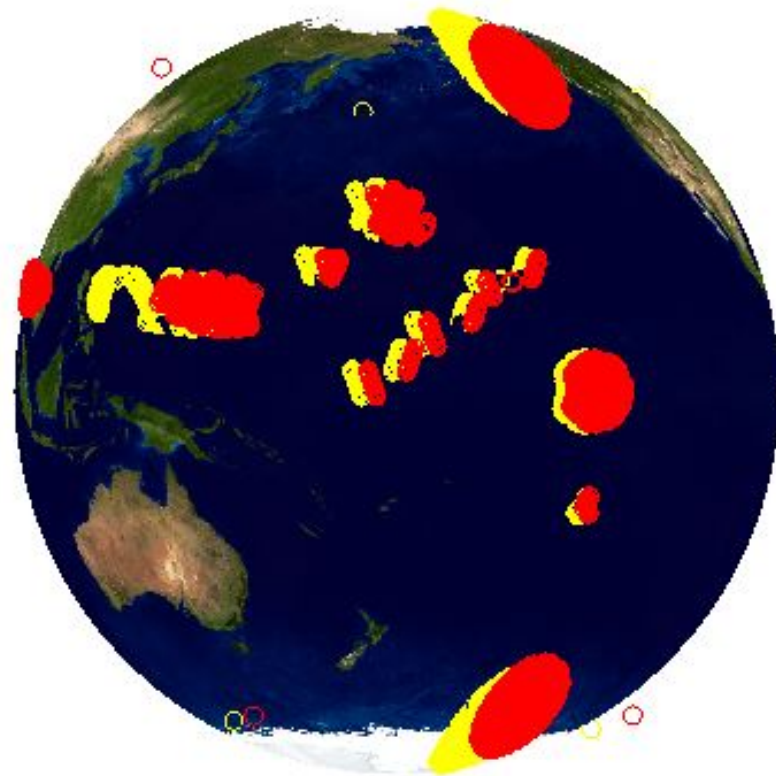
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# Simulation: Applied in 3-D

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**In 3D: Galaxy 28 Space-based GPS  
collects (Red) with ground trace  
map (Yellow)**



**In 3D: G-II Space-based GPS  
collects (Red) with ground trace  
map (Yellow)**

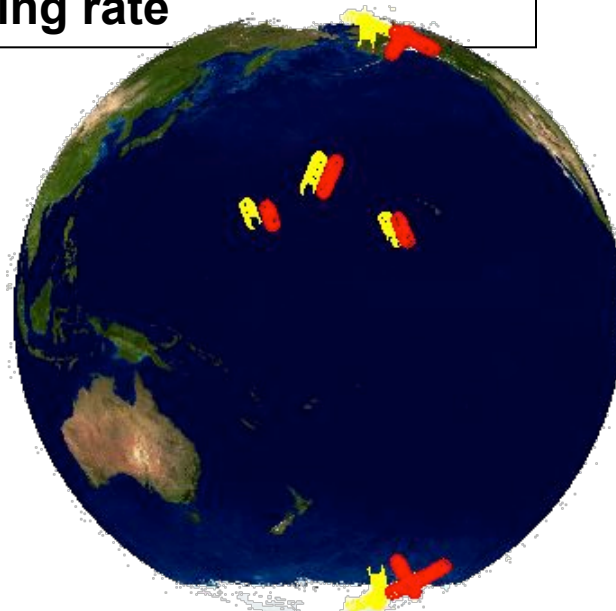
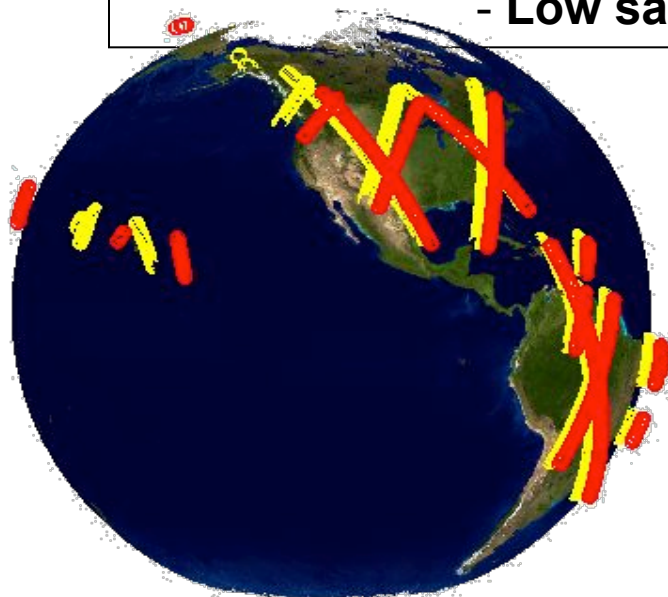


# Simulation: Less desirable...

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## Characteristics of a “Bad” collection:

- Not enough spacecraft
- Not enough collection duration (i.e. time)
- Directly repeating / harmonic ground traces
- Low sampling rate



## Specs:

68 deg

350 km

0.2 Hz

1 Plane

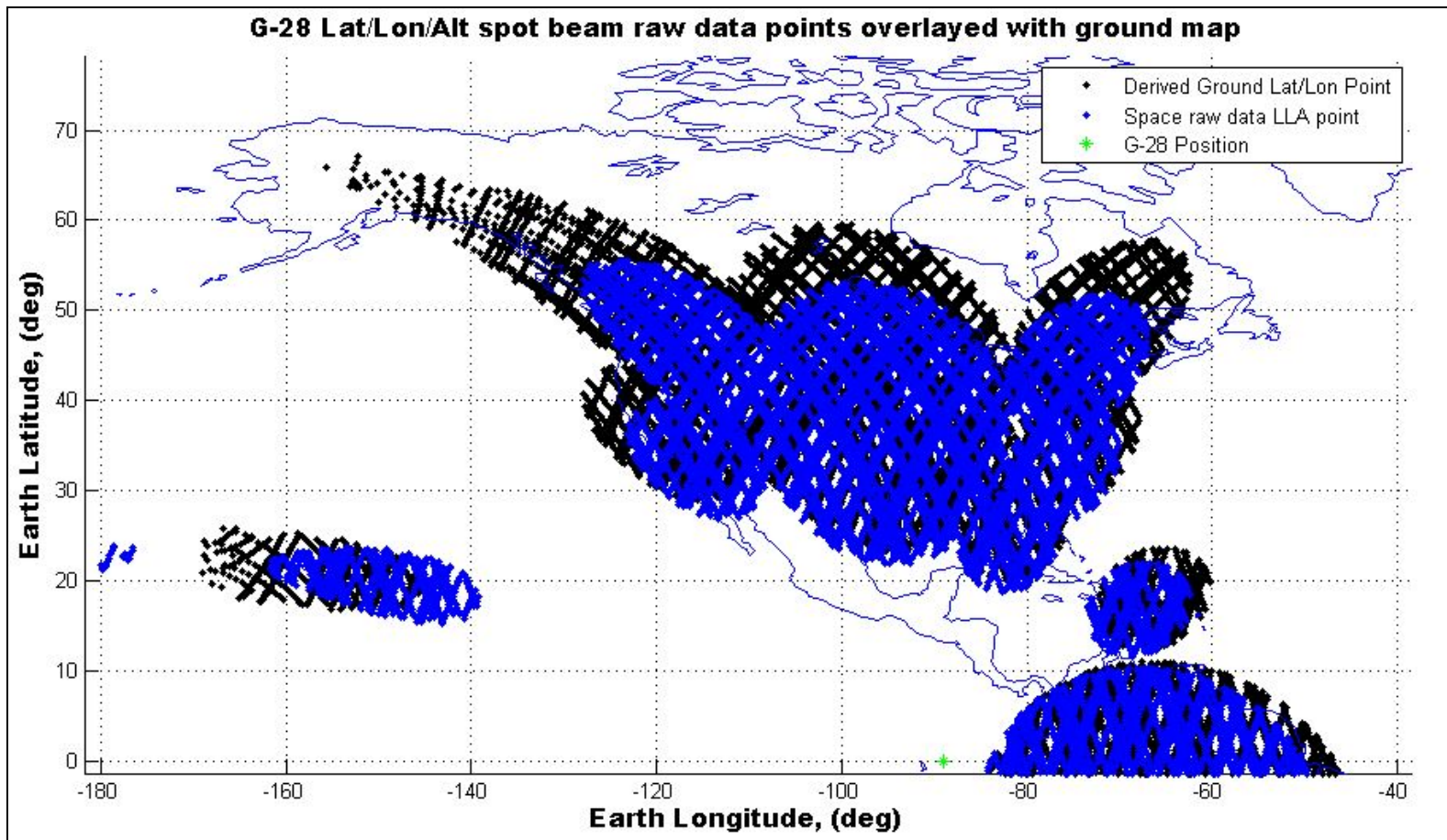
1 Sat.

24 Hour  
Collection

“Can’t Characterize Beam Shapes”  
 “Massive Gaps”  
 “Missing Beams”

# Simulation: More desirable

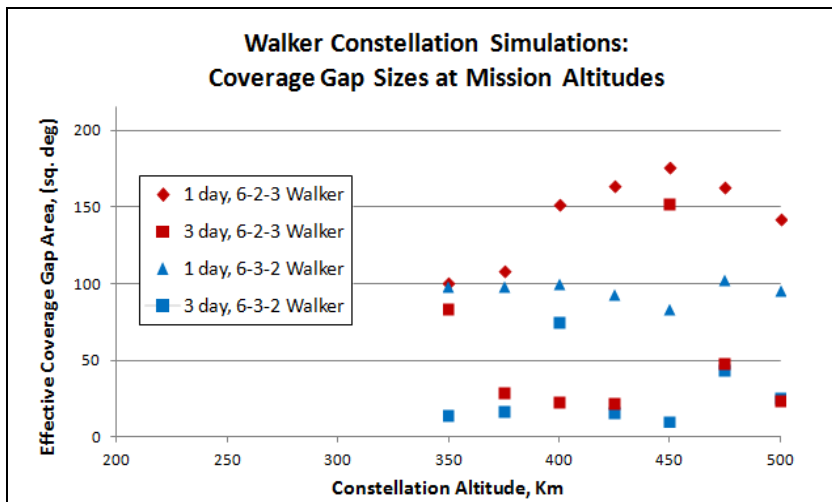
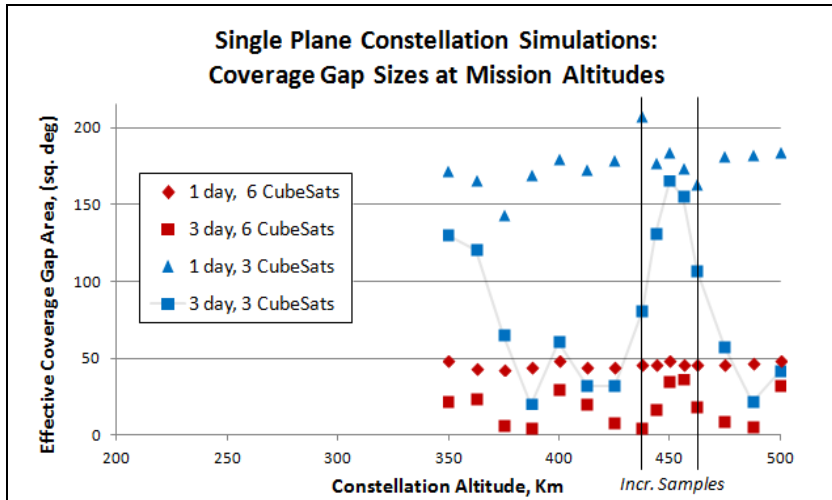
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Shown: 350km / 68 deg / 6-3-2 Walker Delta / 3 Day Collection

# Simulation: Altitude Effects

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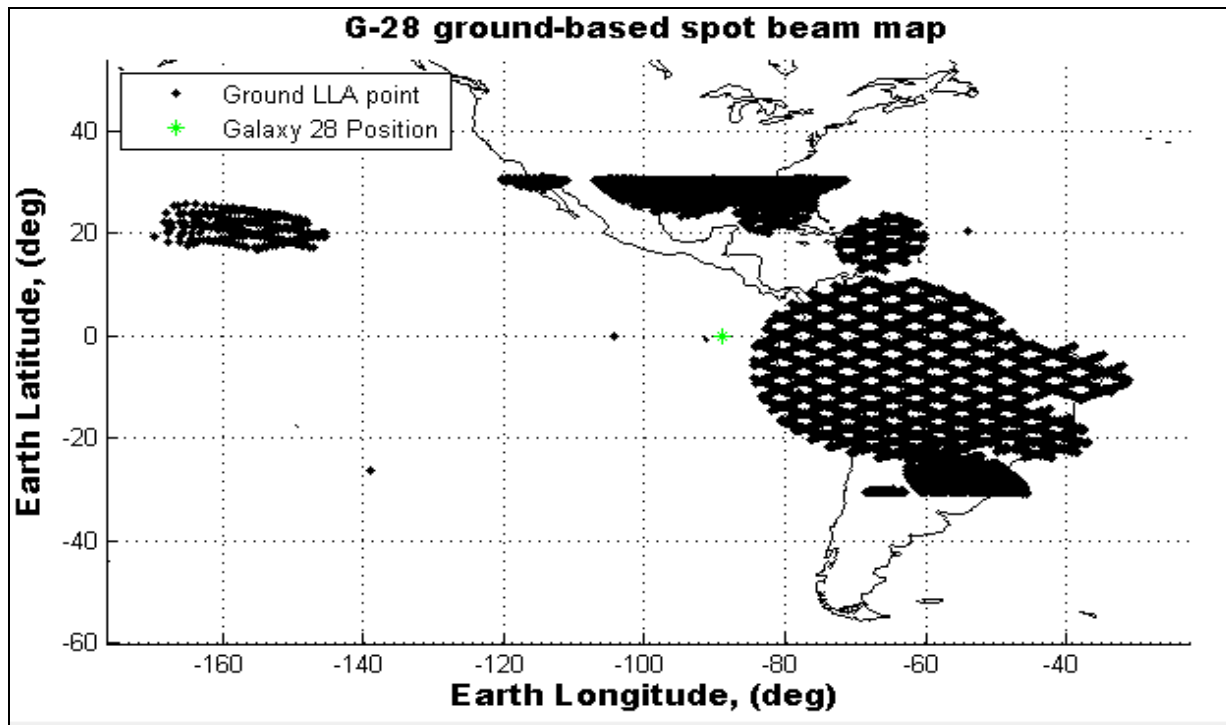
**Goal:** Check gap size at mission altitudes

**Observations / Main points:**

- Altitude selection impacts capability
- Performance can be tailored...
- Some constellations more stable
- More satellites = generally better
- Caveat: Less sats => Need more time
- Repeating ground track...  
Bad for spot beam mapping

# Simulation: Inclination Changes

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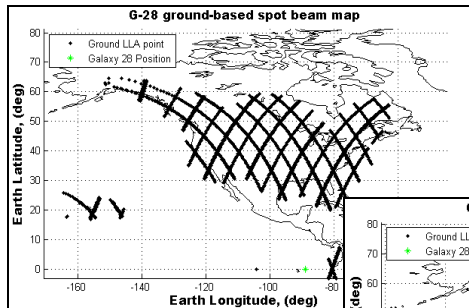


## Spot beam mapping at lower inclinations

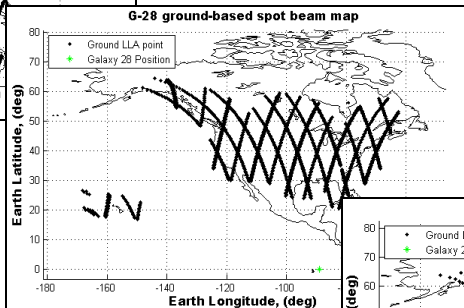
- Very good coverage for orbit region
- Shorter collection durations possible
- Cannot find beams at higher latitudes

# Simulation: Inclination Changes

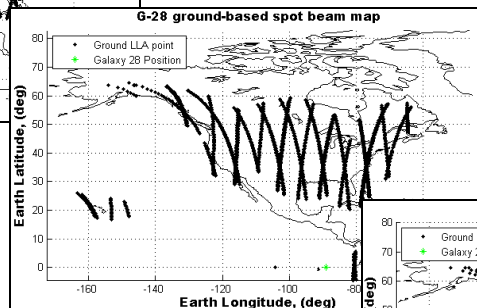
*The AFIT of Today is the Air Force of Tomorrow.*



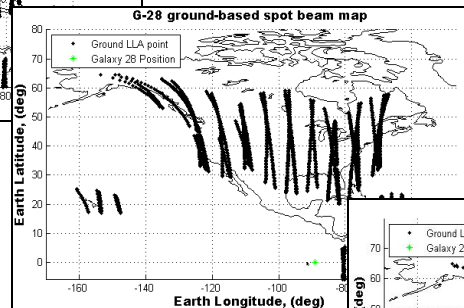
68 degrees



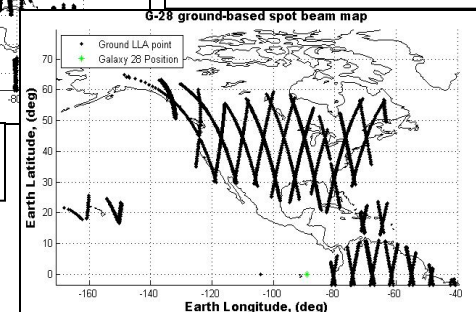
75 degrees



82 degrees



Polar



98 degrees

## Increasing inclination (up to polar):

- Increases size of latitude gaps
- Can tailor longitude gaps
- Reduces overall "time in beam"

## Inclinations for beam mapping:

- Lowest possible inclination
- Covers all desired latitudes



# Simulation: Xmitter Position Knowledge



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## -- Position knowledge of the GEO transmitters

- Mandatory to generate accurate ground beam map
- Increased GEO position accuracy = increased ground accuracy

## -- Option 1: (*Best*) Obtain GEO position information from other sources.

- Easy; No extra hardware required.
- Ground beam map derived from known transmitter location

## -- Option 2: (*Complex*) Perform GEO-location on board the CubeSat

- Difficult; adds \*stringent\* attitude knowledge requirements
- Extra dedicated hardware likely needed
- Requires more data flow, increases demand for data storage



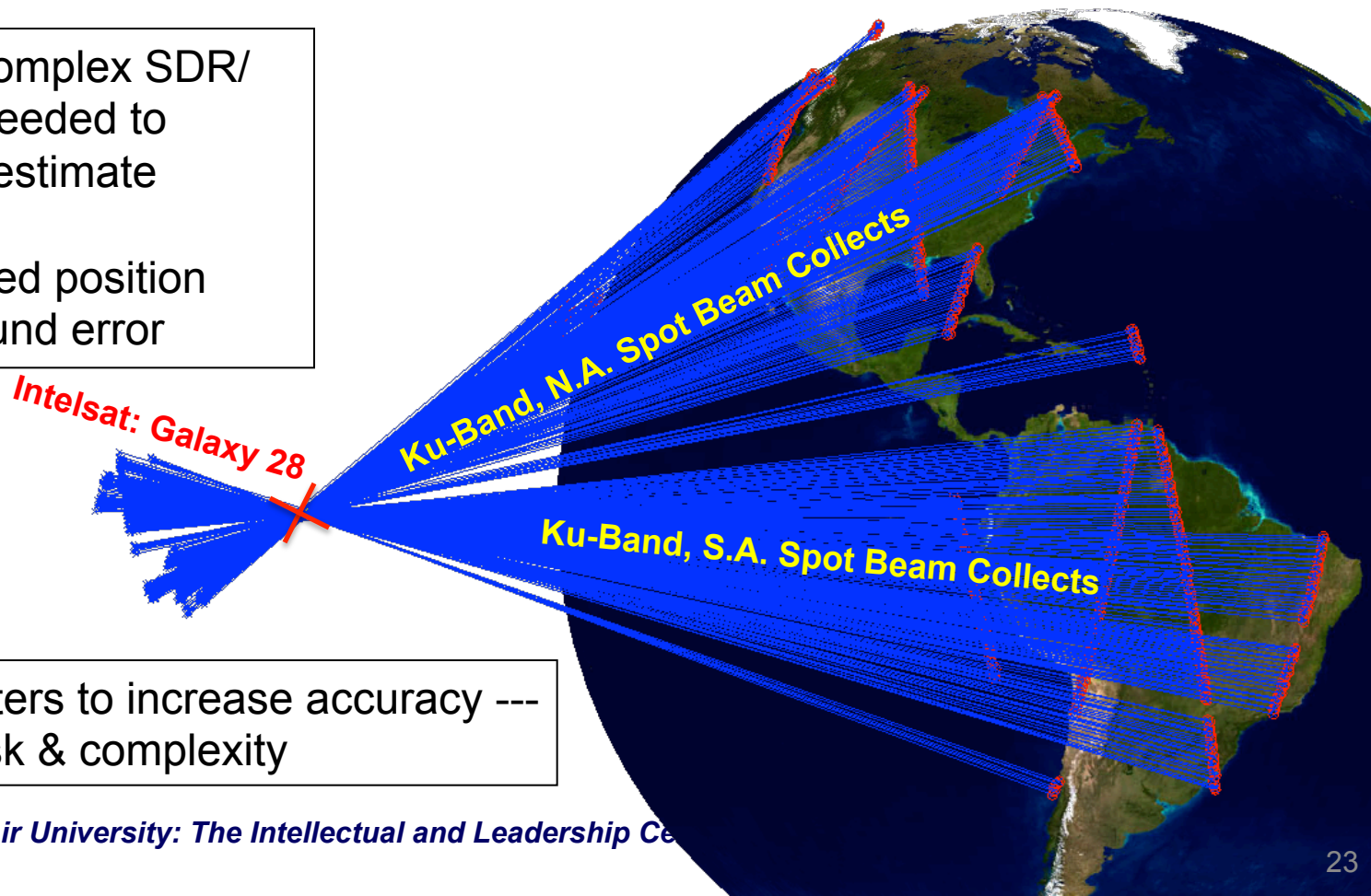
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## Option 2: Simulation of on-board GEO-location

i.e. If the CubeSat can draw Lines of Bearing to the Transmitter...

Parameters: 1 Sat / 450km alt / 0.2 hz sensor collect / minor sensor noise / 10m pos. error

- More difficult, complex SDR/ antennas likely needed to perform bearing estimate
- Error in estimated position correlates to ground error



- Could fly in clusters to increase accuracy --- adds too much risk & complexity

# Simulation: GEO-Location

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Attitude Knowledge “noise” reduces GEO-location capability. (i.e. large error)



Ground trace mapping becomes inaccurate when transmitter position knowledge is poorly known

Kalman-filtering attitude data reduces this error, ...even further w/SOA CubeSat sensors



# Spot Beam Mapping: On the whole



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## -- **Workable mission for CubeSat Platform**

- Simulation tools developed – can generate maps for any constellation
- Best altitudes for established 6U configuration: 350 – 500 km
- Best case: Transmitter position known accurately
- Worst case: Generate angular estimate on board CubeSat

## -- **Constellation needed for “best” results**

- 6+ evenly spaced CubeSats with my assumptions
- 6-3-2 Walker pattern was best from my data sets @ 450km / 68 deg
- Numerous configurations “work” – performance can be tailored.

## -- **Things to watch out for:**

- Directly repeating ground tracks are undesirable
- Accuracy of Ground map at extreme latitudes / longitudes
- Transmitter position knowledge (i.e. the importance of)



# Future Work

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## **-- Optimization**

- Incorporate tools developed to find best solution
- (Manual approach would take centuries)
- Requires more assumptions with no sponsor (i.e. cost)

## **-- CubeSat hardware / Subsystem Design & Dev.**

- COTS sources vs. new
- Payload selection & supporting hardware
- Form factor trade-offs
- GEO position determination hardware “black-box”

## **-- Mission Design/Build/Test/Fly**

- Would be interesting to compare orbit tests w/findings
- One issue with this “future work” is probably funding



# Conclusion



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- Background & Motivation
- Spot Beam Mapping Mission + OV-1
- Design of Mission Model
- Software Tools
- Developed Simulations & Results
- Features of Operation
- Conclusion / Future Work

Questions?



# Backup Slides

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- Mission Requirements
- Tracking Received Power
- Vehicle Profile Transition
- More Duration Information
- Results Format
- Simulation 3D
- Transmitter Position Knowledge
- Simulated Payload Sampling Rate
- More ADCS Information
- Geometry
- Ref. Equations
- References / Sources





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