

12th Annual Summer CubeSat Developers' Workshop Sunday, August 9, 2015

"G.A.U.S.S. Micro Satellites: Experiences and Proposals"

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G.A.U.S.S. Srl:







- ☐ Starting from the **experience** and the enthusiasm grown at the *School of Aerospace Engineering*, some professors, researchers and students decided to continue the tradition of the school founding the limited liable company G.A.U.S.S. Srl, evolving **from a didactical dimension to an innovative company reality**.
- ☐ The **company business** is mainly related to the design and manufacturing of space systems which are also intended as release platforms for CubeSat and PocketQube using the deployers PEPPOD and MRFOD, thus letting begin G.A.U.S.S. to be a launch provider for small satellites.

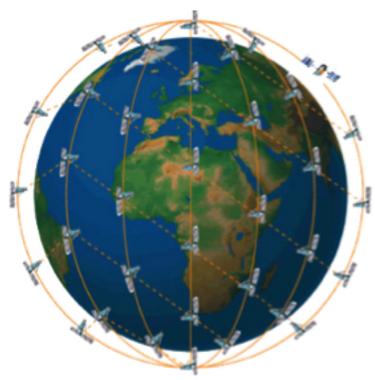


More and more interest in microsatellites

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- ☐ In the last years, the interest of University, Private Companies and government agencies in launching micro-satellites is growing up.

 CubeSats or smaller femto-satellite PocketQube.
- □ A few years ago this class of satellites were considered only for didactical or for in-orbit test purposes. Recently they are even more used in constellations made with high performance technologies.



Credit: APL/JHU



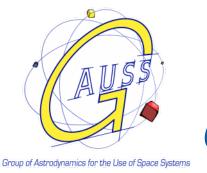
UniSat Satellites as Launcher Platforms:

☐ The complexity of the missions for these satellites, is quickly growing up. There is the need to offer fast, multiple and alternative

solutions to satisfy the customers' goals.

satellites having two primary purposes:

- ☐ G.A.U.S.S. Srl has innovated the idea of launch provider developing civil and scientific
- acting as Launch Platforms to carry and deploy in the Space other smaller satellites;
- hosting payloads on board for scientific missions, testing equipment in space condition, providing power, intelligent control and telecommunication services for the hosted payloads.



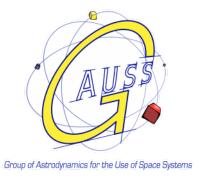
UniSat Satellites as Launcher Platforms:

☐ Some actual advantages:

- Payloads of the satellites UniSat, are not more tied directly to the scheduled mission of the rocket.
- It is possible to avoid the dangerous clouds of satellites at the separation time.
- More satellites of a constellation can be launched on the same cluster launch, but released at different times.

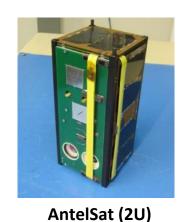
☐ Future goals for G.A.U.S.S.:

Make their platform satellites able to change orbits (**orbital and attitude control**) and release the payloads in a known attitude control status.

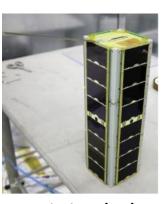


UniSat Satellites:

- ☐ In less than two years UniSat-5 and UniSat-6 have carried in to space 12 small satellites:
- 2013 UniSat-5 has released 7 satellites using 2 PEPPOD and 3 MRFOD deployers. It has been the first Spacecraft that has carried in to space the new standard of femto-satellites, the PocketQube.
- 2014 UniSat-6 has released 4 CubeSats using 2 PPOD deployers from CalPoly and 1 PEPPOD. One of the Cubesats has also split in 2 half units.









Lemur-1 (3U)

TigriSat (3U)

AeroCube-6 (two 1/2U)



Launch Service Collaboration: DNEPR LV



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- ☐ Since the year 2000, G.A.U.S.S. has launched satellites with the support of the International Space Company (ISC) Kosmotras.
- ☐ Taking advantages of this fruitful cooperation, G.A.U.S.S. Srl is actually able to offer launch services for microsatellites in general.
- **Reliability:** currently, the mission reliability factor for the rocket is 0.97





UniSat-6 Mission:

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UniSat-6 Mission:

- ☐ It was launched in June 19th 2014 from Dombarovsky Cosmodrome at Yasny (Russia).
- ☐ Cluster Mission of 32 satellites (37 considering the UniSat-6's payloads).





UniSat-6 Mission:

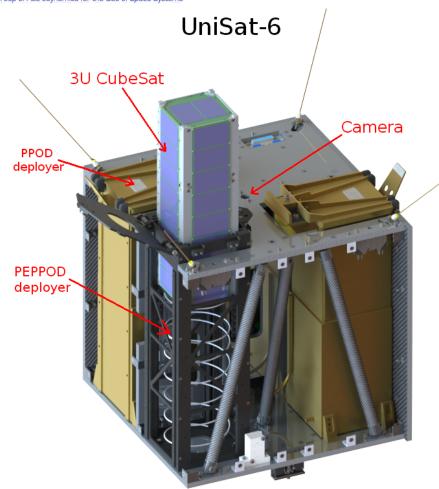
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Name	Class	Mission Purpose	Ownership	Country
UniSat-6	NanoSatellite	Educational Deployer of Cubesat using PPOD and Peppod No military purpose	GAUSS Srl	Italy
TigriSat	3U CubeSat	Deployed from UniSat-6 University student education No military purpose	University of Rome, Sapienza	Italy
AeroCube6	1U CubeSat	Deployed from UniSat-6 Reserch and Development No military purpose	CalPoly	USA
ANTELSAT	2U CubeSat	Deployed from UniSat-6 Educational No military purpose	Universidad de la Republica (UdelaR)	Uruguay
Lemur-1	3U CubeSat	Deployed from UniSat-6 Reserch and Development No military purpose	CalPoly	USA



UniSat-6: Deployment System

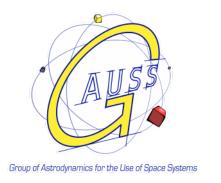
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Orbital Deployers:

- 1x PEPPOD (G.A.U.S.S. Srl)
- 2x PPOD (CalPoly)



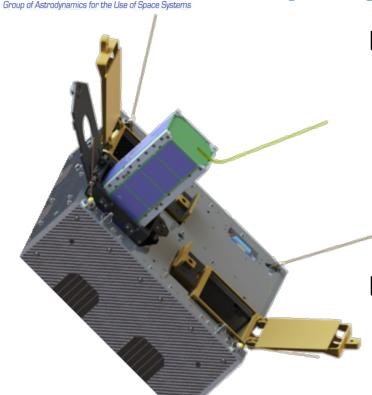
UniSat-6: PEPPOD Deployer

- ☐ It is **lighter** than other Orbital Deployers, it is well suitable to be installed on Spacecrafts.
- ☐ It was designed by G.A.U.S.S. Srl to be used with 1U, 2U and 3U CubeSats, it is also customizable on request.
- ☐ It uses the high reliable and space qualified **FRANGIBOLT** opening system (TiNi-Aerospace).
- ☐ It was **used with success** on UniSat-5.

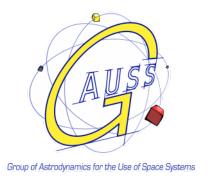




UniSat-6: Deployment Strategy



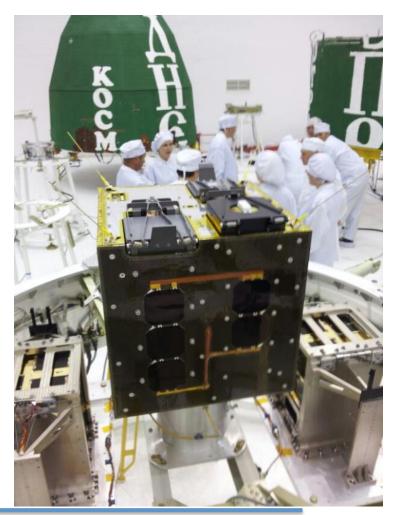
- □ Primary automatic release system:
 - completely autonomous
 - redundant activations
 - hardwired logic (no microcontrollers)
 - dedicated battery pack
- Release Time of CubeSats: 25h 38' after the separation of UniSat-6 from the Dnepr LV, following a precise scheduling
- ☐ Secondary redundant release system: by TT&C it is possible to override the automatic system to open the PODs



UniSat-6: the satellite

☐ Orbital parameters:

- quasi sun synchronous orbit
- Around 700km height
- period of revolution 5878s
- orbit inclination 97,98°
- ☐ Shape: A cube of 40cm side by side
- ☐ Weigh: 26 Kg with payloads inside
- ☐ Attitude control: passive with permanent magnet and histeresys rods



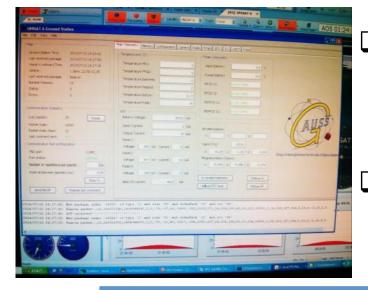


UniSat-6: Ground Segment & communications

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- ☐ UniSat-6 is clearly received at very low elevation (about 1°) by ground stations.
- ☐ It is also possible to receive the telemetry by **radio-amateur** handsets without any modifications.

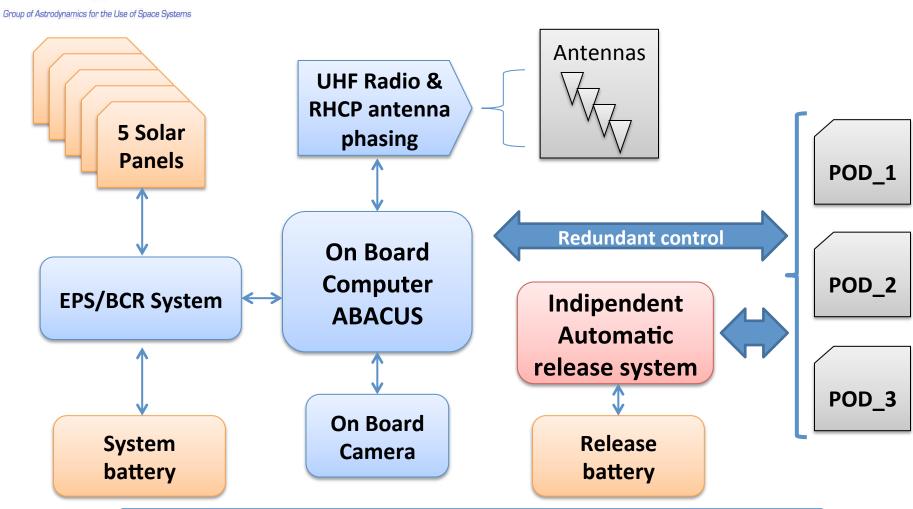




- □ A Dedicated software has been developed by G.A.U.S.S. SrI for uplink and downlink operations.
- Since the first day in orbit, up to 5 passes per day have been followed over Rome, downloading stored telemetry and pictures.



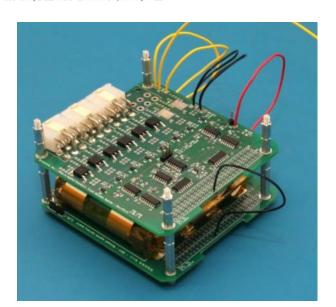
UniSat-6: Sub Systems





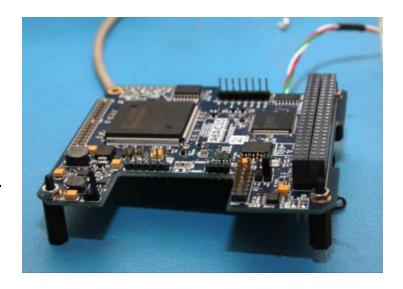
UniSat-6: Sub Systems

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Automatic Timed Release System for PPOD and PEPPOD deployers (G.A.U.S.S. Srl)

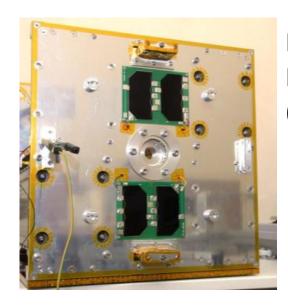
ABACUS On Board Computer (G.A.U.S.S. Srl and "Sapienza" University of Rome)





UniSat-6: Sub Systems

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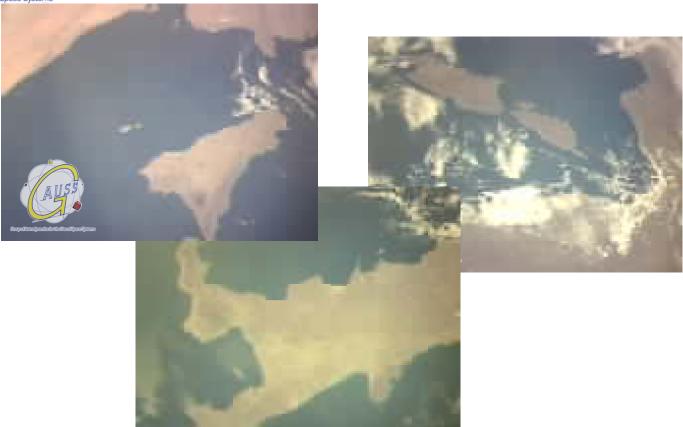
Bottom Solar Panel Power 5W (G.A.U.S.S. Srl)

> On Board Camera 3 Mpx Jpeg (LinkSprite)



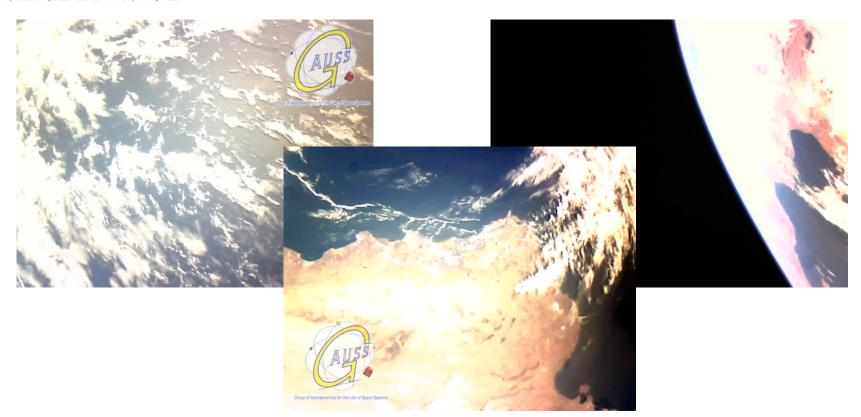


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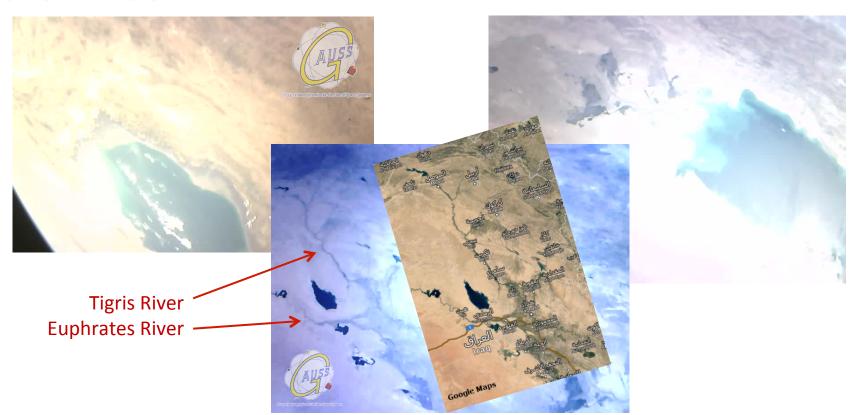
☐ Some pictures in low resolution (for video) in a pass over Italy





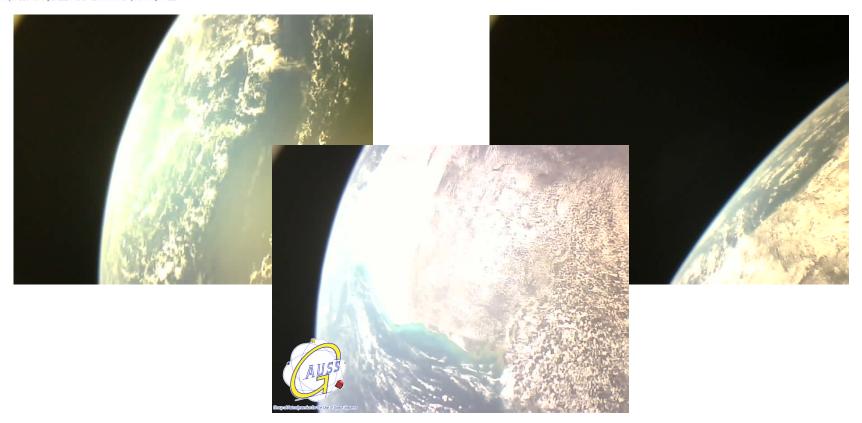
☐ Mid resolution pictures: clouds on Madagascar, Tunisia and Earth view





☐ Mid resolution pictures: Caspian Sea, Iraq and Persian Gulf





☐ Mid resolution pictures: clouds on Brazil



UniSat-6: Integration time

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In the pictures: P. Teofilatto - V. Kainov - F. Graziani - M. Truglio - C. Massimiani - S. Paiano - A. Conde

Rodriguez



Towards UniSat-7..... from the past to the future

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Towards UniSat-7: On-Going Projects

☐ Structure:

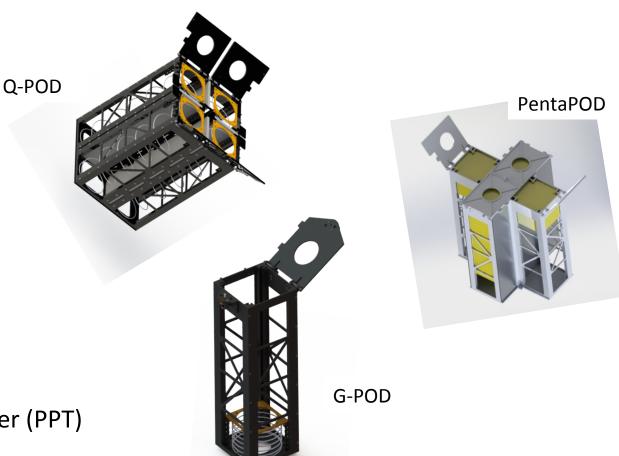
- G-POD
- Q-POD
- PentaPOD

☐ Attitude Control:

- Magnetic Torquers
- Reaction Wheels

☐ Electric Propulsion:

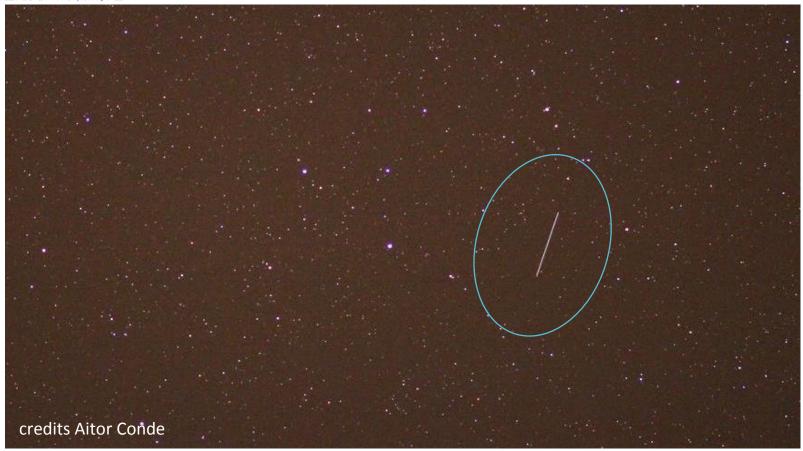
Pulsed Plasma Thruster (PPT)



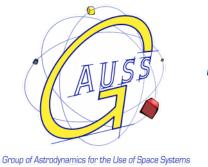


Proposals: the Point of View from the Earth

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☐ Picture of UNISAT-6 as seen over Bilbao (Spain)



Proposals: the Point of View from the Earth

☐ Space Debris Observations:

From the Earth - the Castelgrande Observatory is an optical space debris observation center in Italy.

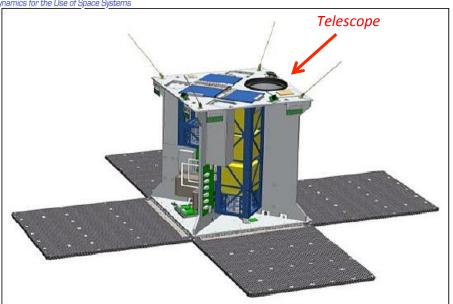


Castelgrande Observatory (Italy)



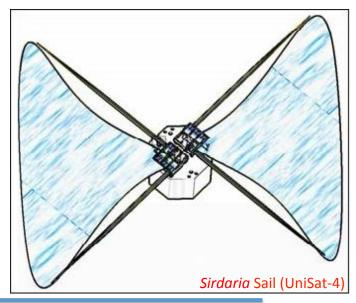
Proposals: the Point of View from the Space

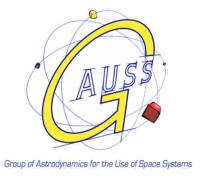
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Space Debris Observations: From the Space – the proposal is to use a telescope on board of a satellite

- **Deorbiting Systems:**
- **Sirdaria** Sail, a deployable sail with the purpose of increasing the aerodynamic drag reducing satellite mechanical lifetime.
- **Propulsion**





Thanks to...

