



# The AeroAstro Fast-Angular-Rate Miniature Star Tracker: Algorithms and Simulation Results

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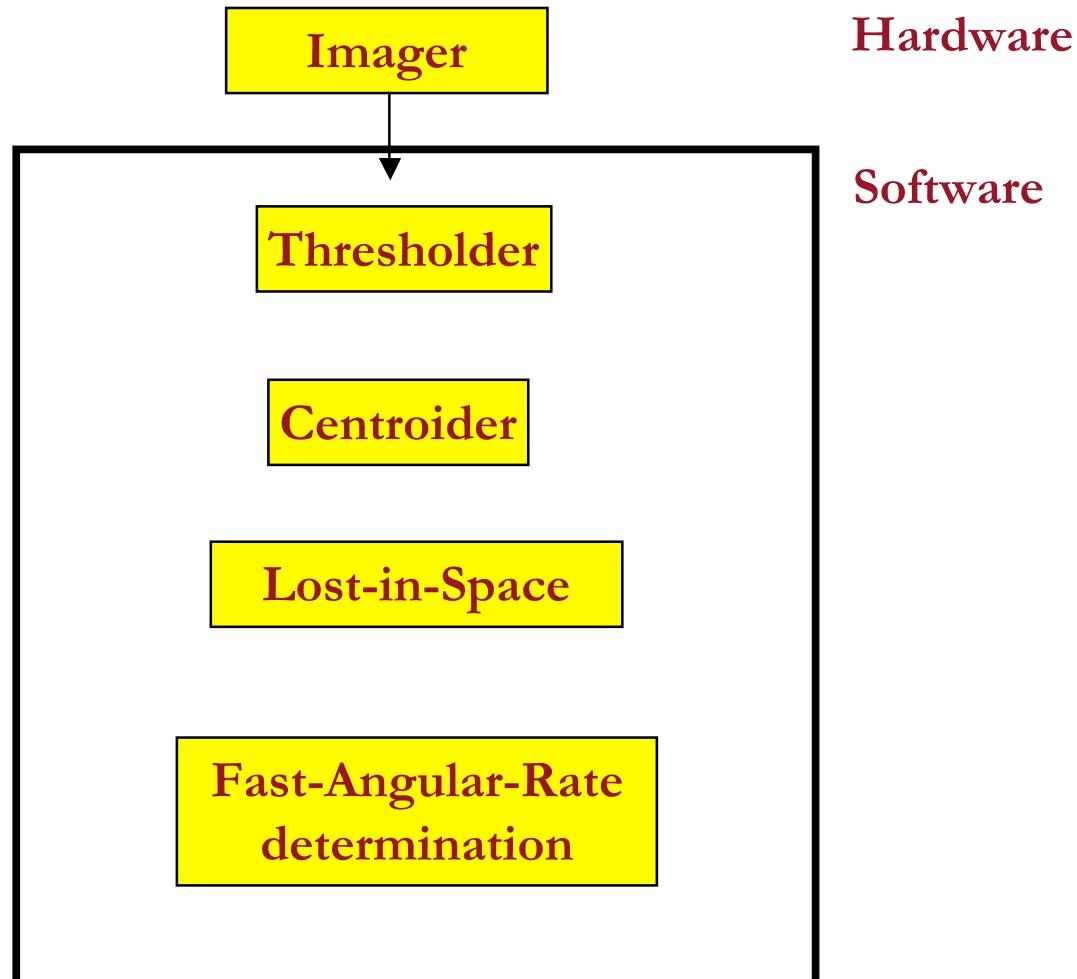
703.723.9800 x 158

**SSC05-XI-7**

# Block Architecture



❖ AA Star Tracker - all-optical!





# Simulation Environment

- ❖ **Simulate major Star Tracker components**

- CMOS imager
- Camera model
- Star Catalog
- Lost-In-Space algorithms
- Fast-Angular-Rate algorithms

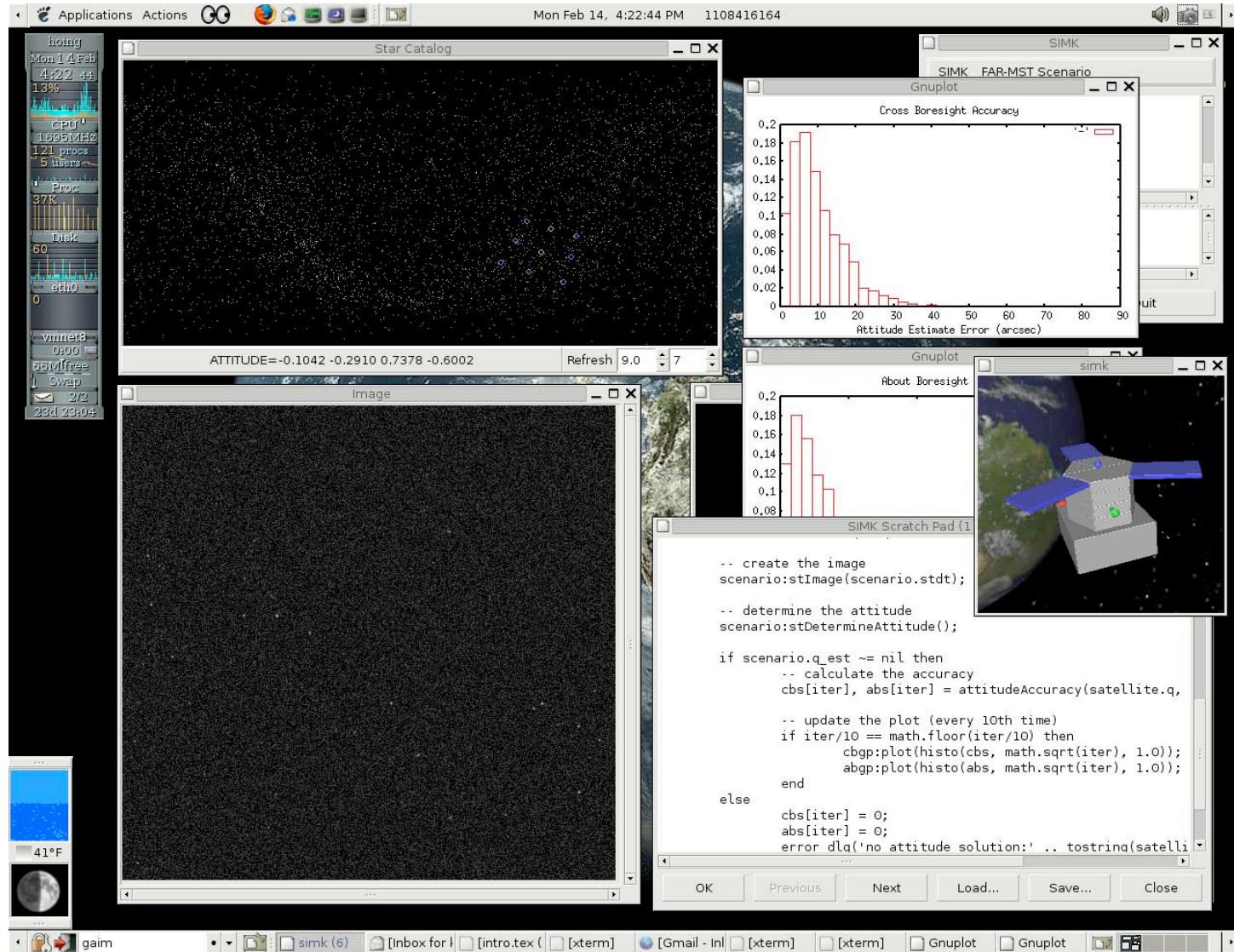
- ❖ **Simulates spacecraft dynamics affecting view**

- Attitude/Pointing
- Flight path

- ❖ **Neglect**

- Spectral nature of optics, stars

# Simulation Environment (cont'd)



# Lost-In-Space Algorithm (LIS)

## ❖ Choice:

- Inter-star, angular separation
- Grid-based
- Neural-networks based

## ❖ We chose:

- Inter-star, angular separation (more mature alg's)
- Specific implementation: Pyramid (Junkins, Mortari)

## ❖ Problem:

- How do you search the star catalog efficiently?

## ❖ Answer:

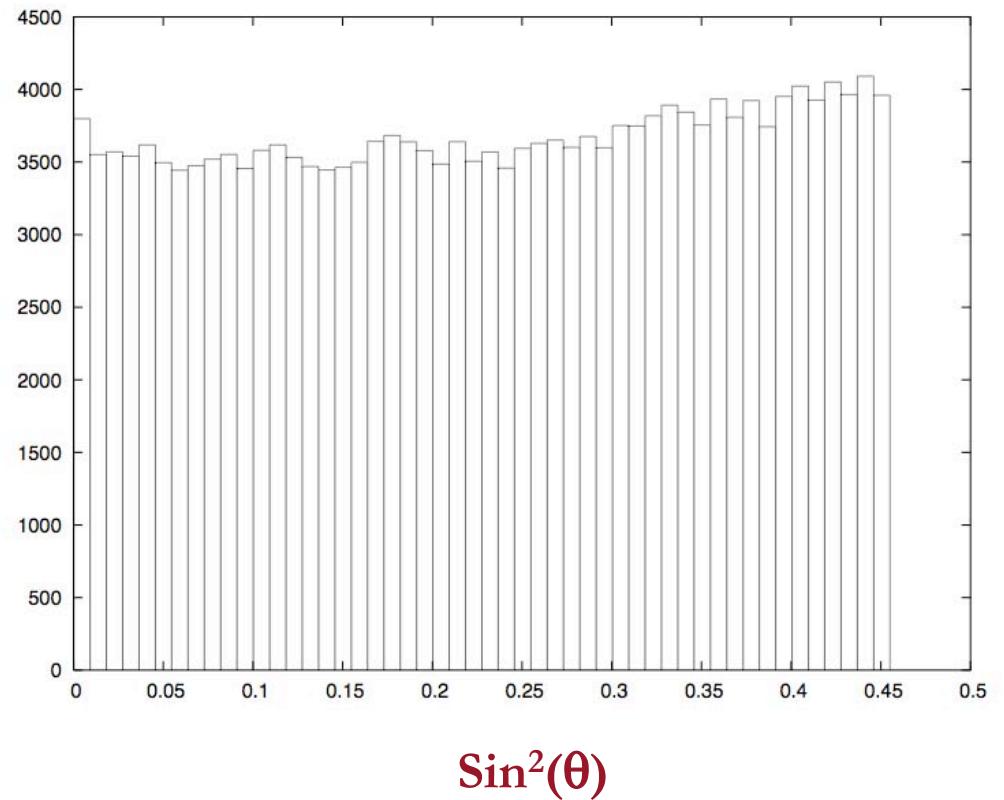
- Hash tables (k-vector approach)

# LIS (cont'd)

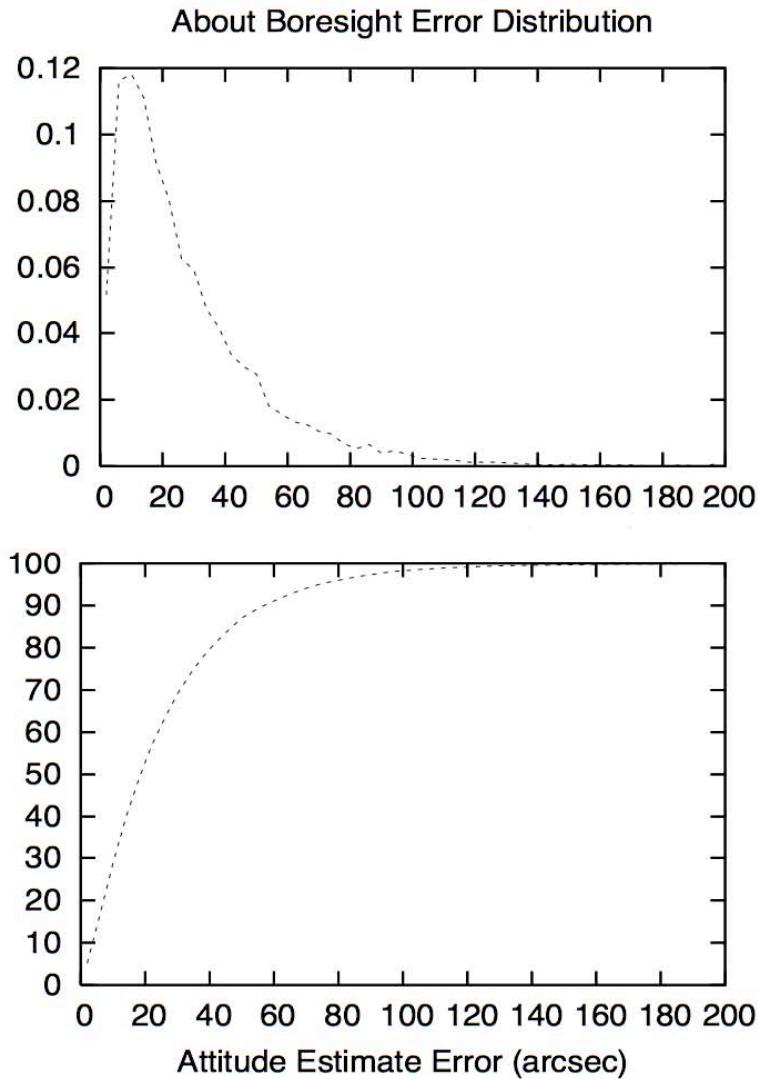
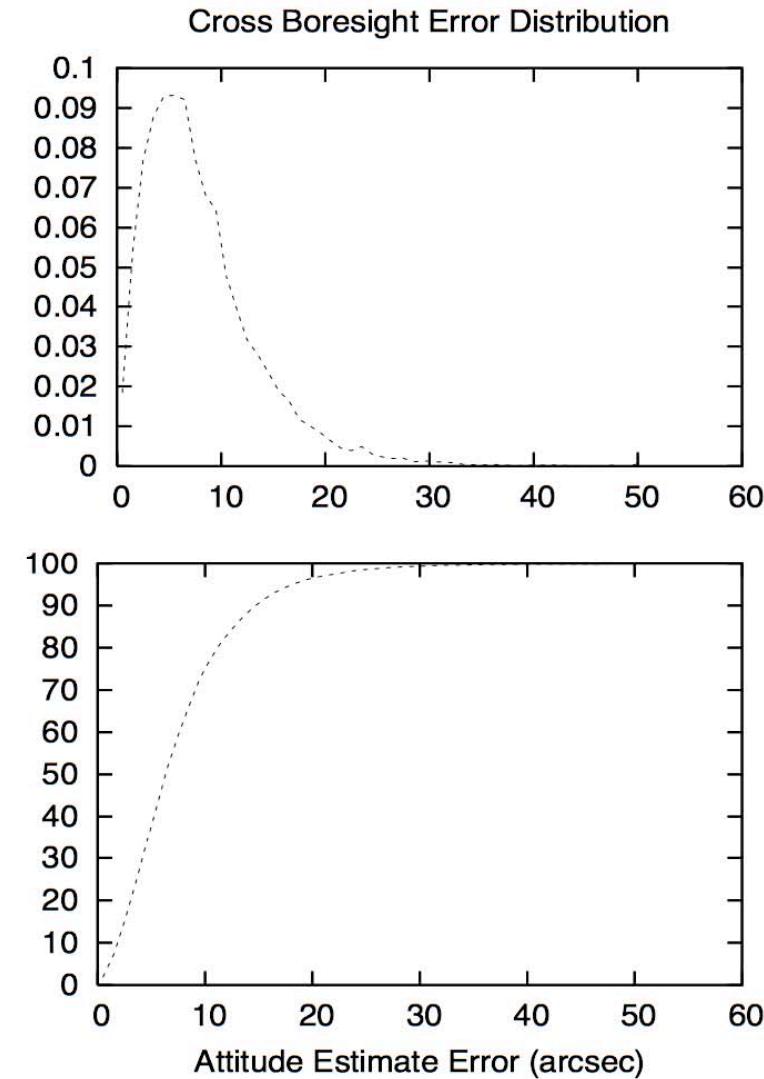


❖ Hash tables work  
because...

- Distribution of angular separation of stars is relatively flat



# LIS Performance

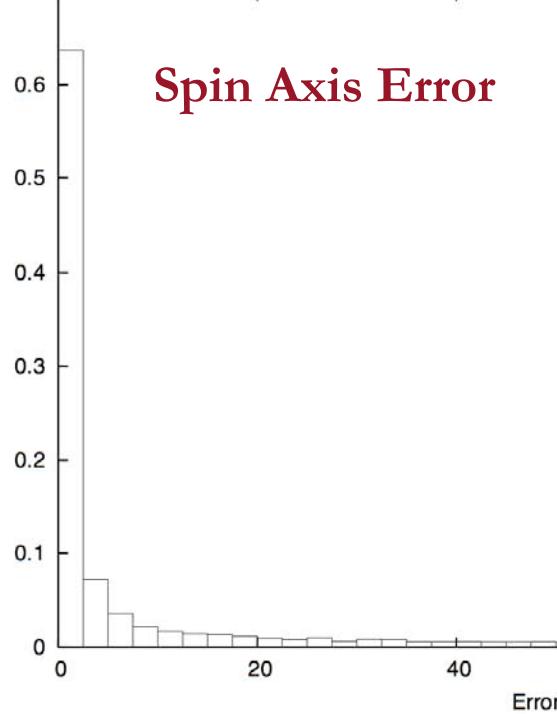




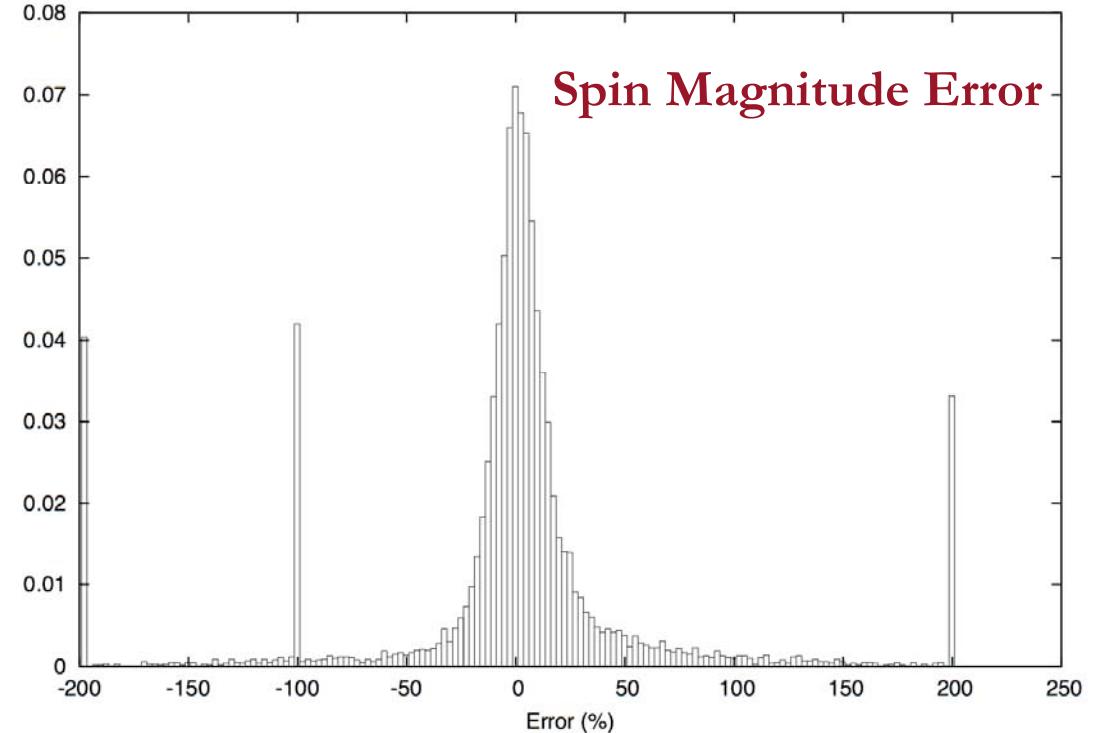
# FAR-MST Algorithm

- ❖ Estimate apparent star motion in the focal plane at several points
  - Magnitude
  - Direction
- ❖ How? - Use star streaks!
  - Gaussian steerable filter
    - Detect, get orientation
  - Determine direction of rotation (sign issue..)
  - Use sequence of images
    - Sign of direction
    - Speed
- ❖ Know spin axis = know spacecraft attitude

# FAR-MST Performance

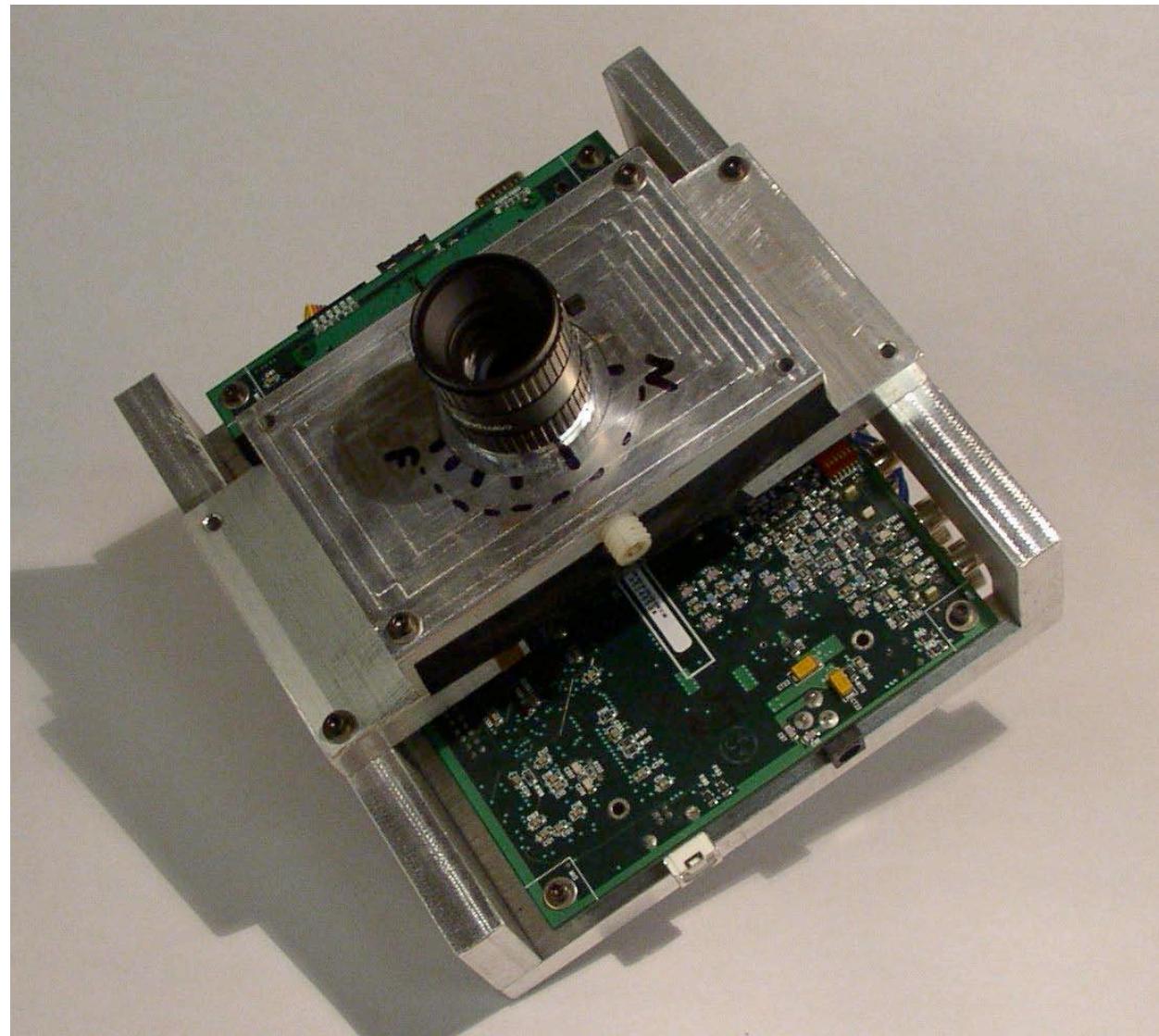


Spin Axis Error

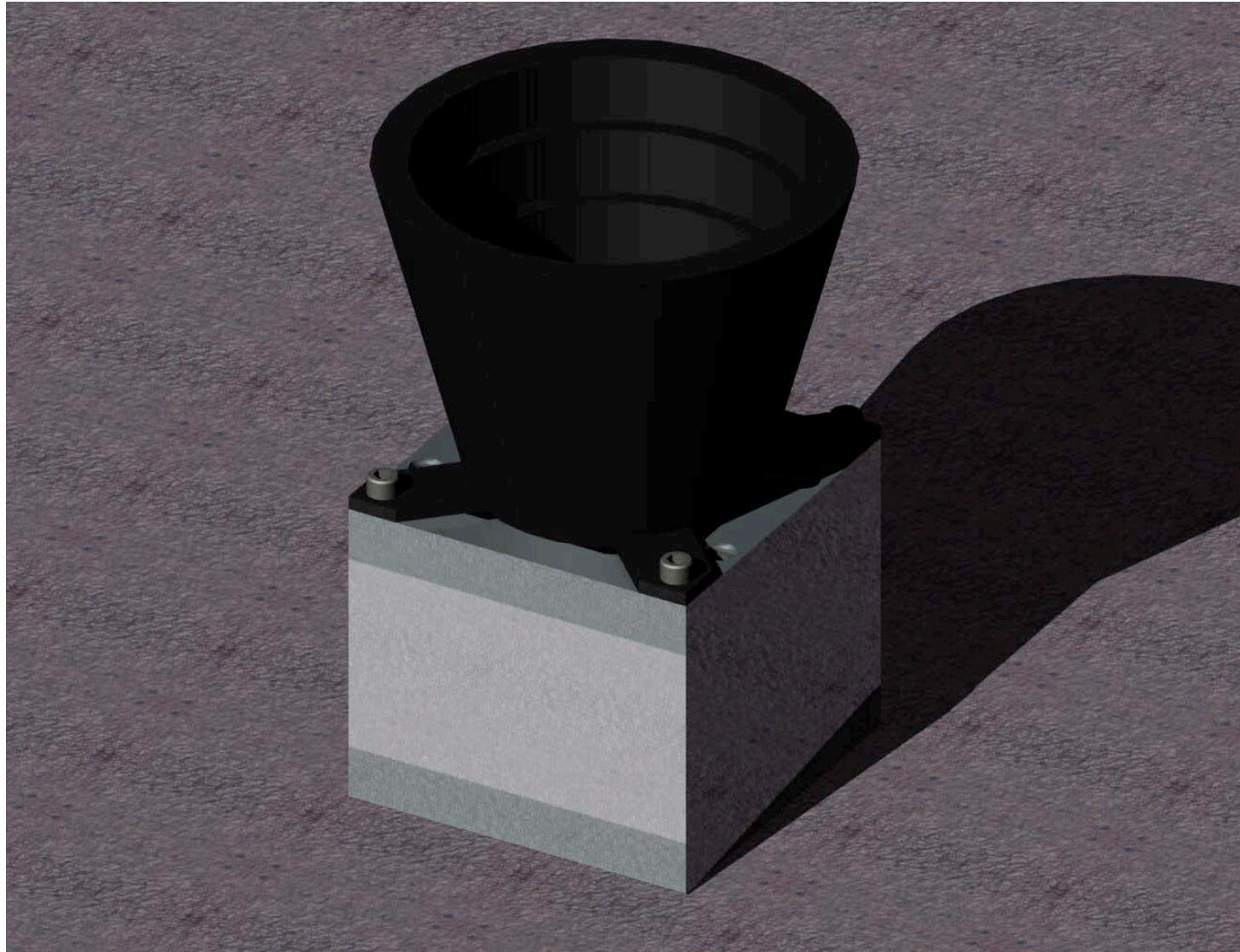


Spin Magnitude Error

# Current Hardware



# Future Hardware





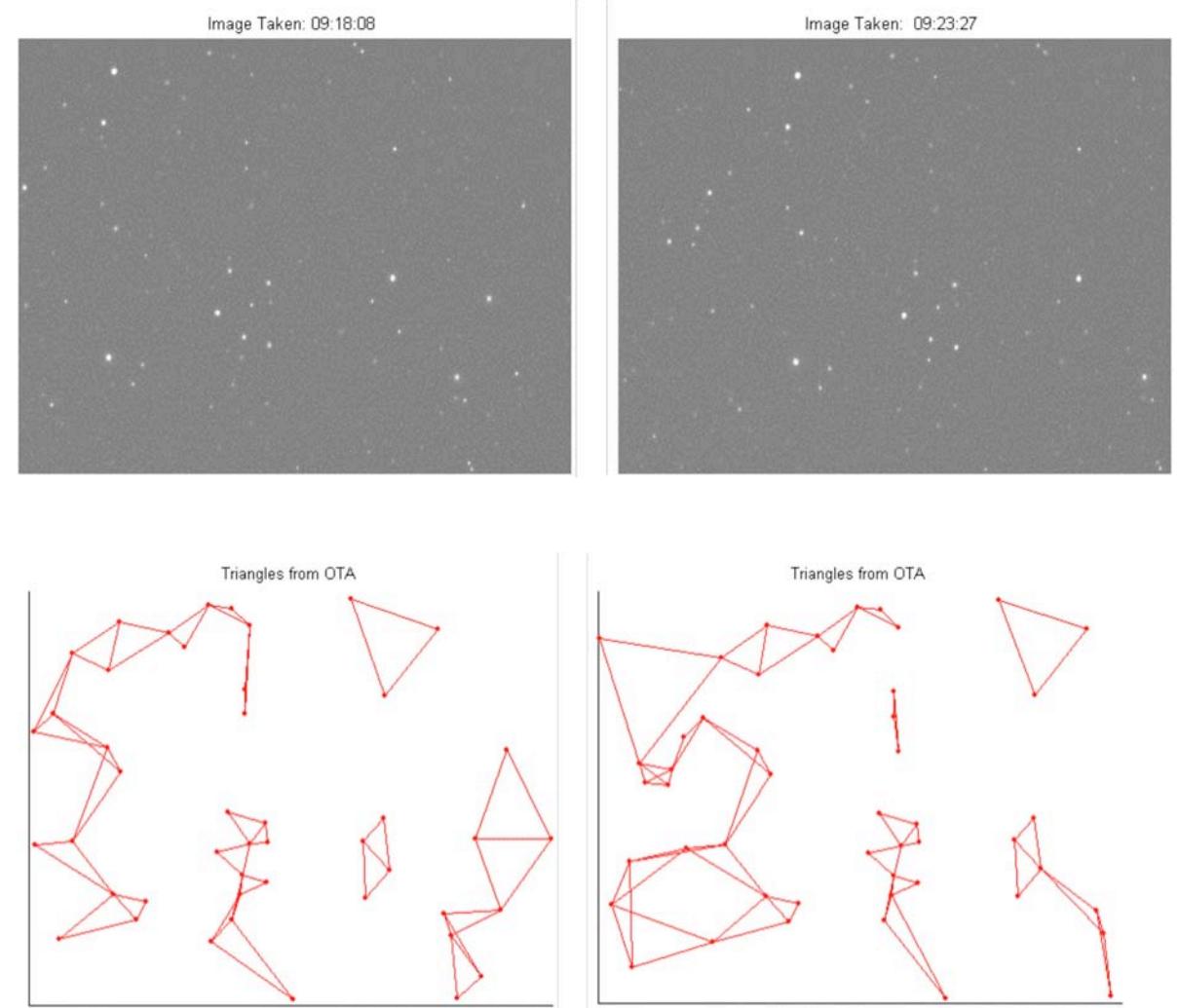
## FAR-MST specs

- ❖ Mass: < 1 kg,
- ❖ Power: < 3 W
- ❖ Functions:
  - LIS
  - Angular rates to 15 degrees/sec
- ❖ Accuracy ~ 75 arcsec
- ❖ Size : 15 x 8 x 8 cm
- ❖ Price < \$ 100K
- ❖ Interface
  - USB
  - RS-422

# Real Star images



❖ Picture sequence taken 319 sec apart  
❖ Quaternions generated, earth's rotation found to be 1.335 deg = 319.6 sec



CMOS image



# Conclusions



- ❖ Simulations show algorithms accurate
  - Better than the ~75 arcsec quoted
- ❖ All-optical system can provide
  - LIS
  - Fast-Angular-Rate Measurements
- ❖ Camera parameters currently being optimized
- ❖ Flight-ready prototype
  - 12-14 months