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An Empirical Test of Regulatory Effects

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An empirical test of regulatory effects

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Averch and Johnson have provided analytical support for the assertion that rate of return regulation causes inefficient production because of the overuse of capital. Empirical evidence in support or refutation of their thesis is just beginning to appear. This paper provides additional evidence. The regulated firm's objective is stated in terms of cost minimization subject to a regulatory constraint. The effect of changes in the allowed rate of return on capital are evaluated. It is shown that as the allowed return approaches the cost of capital, costs increase and the percentage of total costs paid to capital also increases. These are testable implications of the revised A-J model. Data on costs, input prices, and output are collected for electric power production. Three measures of regulatory policy with regard to the allowed return are formulated. Econometric analysis suggests that lower allowed rates of return are significantly associated with higher costs and larger proportions of cost going to capital. These findings are consistent with the revised A-J model and with those of other recent investigators.

Price regulation of electric power in the United States is accomplished by using a rate of return on capital criterion. The individual firm is allowed to charge prices which will allow it to recover its expenses while also earning a fair rate of return on its capital base.

Price changes to be allowed by a commission are determined in a rate case. The rate case is a quasi-judicial proceeding which determines the firm's present revenues, expenses, capital or rate base, and rate of return in relation to a test period (usually the latest twelve-month period for which data are available). The rate case also determines the appropriate or fair rate of return. If the rate of return earned by the firm in the test period is less than the fair rate of return, then the firm will be allowed to raise prices. If the return is greater than the fair return, a reduction in prices may be ordered. The new prices which the commission will allow are set such that they generate sufficient revenues to allow the firm to pay its expenses plus earn the fair rate of return on its rate base. Thus, regulation can be considered as a cost plus profit process.

H. Craig Petersen received the B.S. in economics and computer science from Utah State University in 1968 and the Ph.D. in economics from Stanford University in 1973. Currently he is studying the impact of particular regulatory policies on the operations of utilities and the economic, institutional, and legal aspects of solar energy.
There are significant differences among the states regarding the particulars of their regulatory procedures. Some states have large, active regulatory commissions, while others have small, poorly staffed commissions which have rarely required rate adjustments. In some states the regulation of electric power rates is done on a local rather than a statewide basis. At the present time Texas, South Dakota, and Minnesota do not have statewide commissions. Until 1966, Iowa also regulated electric power on a local basis. The record of local commission regulation is rather poor; its demise attests to that fact. It is a maintained hypothesis of this paper that local regulation is less effective than that done on a statewide basis.

For many years students of regulation have argued that the cost-plus type of regulation used in the United States does not provide utilities with much incentive to be efficient in their provision of service. In their 1962 article, Averch and Johnson (A-J) give analytical support for the proposition that such regulation tends to result in inefficient production. Starting with the assumptions of no regulatory lag, profit maximization, and an allowed rate of return greater than the cost of capital, they demonstrate that the firm has an incentive to use more capital in production than would be dictated by strict cost minimization. A substantial literature has accumulated which extends and refines the basic A-J idea.

Intuitively, what occurs is that the firm is constrained as to the amount of total profits it may earn, and seeks means of circumventing the regulatory constraint. This is accomplished by overutilizing capital. Since the firm is assumed to be allowed to earn more on each additional unit of capital employed than the cost of that capital to the firm, up to some point profits are increased by substitution of capital for the other input, labor.

Another way of looking at the result is to view the excess return, $s-P_K$, where $s$ is the allowed return and $P_K$ is the cost of capital, as a subsidy granted to the use of capital. The firm in its decision making maximizes profits by using each input until its value in production equals its cost, but because each unit of capital is subsidized, the firm does not use the market cost of capital in the decision process, but some shadow price of capital less than $P_K$. Capital is used until the value of its marginal product is driven down to this shadow price. In this view, the firm behaves in the same manner as any profit-maximizing firm, but uses a different capital price.

In spite of the potential importance of the Averch and Johnson result, empirical support or refutation has been slow in coming. First to be published were articles by Spann and by

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2 See Reschenthaler [16] for one of the few published discussions on the nature of municipal regulation. The ineffectiveness of local regulation is considered in most texts on the economics of regulation. See Phillips [15], for example.
3 In [11].
4 The most comprehensive of the A-J publications are those by Bailey [2] and by Baumol and Klevorick [4].
In this section the Averch-Johnson analysis is reformulated in terms of cost minimization subject to technology and regulatory constraints. The effect of changes in the allowed return on capital on costs and input choice is investigated. It is shown that costs increase for the production of any given level of output as the allowed return approaches the cost of capital. It is also demonstrated that the use of capital and the proportion of total costs paid to capital increase as regulation becomes more stringent.

For the unconstrained firm, a necessary condition for profit-maximization is that the cost of producing the chosen level of output be minimized subject to the constraint imposed by existing technology. A similar requirement holds for the regulated profit-maximizing firm, but with the additional qualification that, in minimizing costs, the profit limitation must not be violated. That is, the firm must choose inputs such that the difference between production costs and revenues generated from the chosen output does not exceed the allowed rate of return per unit of capital employed. The regulated firm attempts to circumvent the regulatory constraint by incorporating into its costs a higher expenditure on capital than would be used on a strict cost minimization criterion.

Formally stated, the problem of the firm is to minimize

\[ C = P_L L + P_K K + P_F F \]

subject to the production technology constraint,

\[ Q(K, F, L) = \bar{Q}, \]

and the regulatory constraint,

\[ \bar{R} - P_L L - P_F F \leq sK \]

where \( L, K, \) and \( F \) are labor, capital, and fuel inputs, the \( P_i \) are input prices, \( \bar{Q} \) is the chosen level of output, \( s \) is the allowed return on capital, and \( \bar{R} \) is total revenue, \( \bar{PQ} \).

The production function, \( Q(K, F, L) \) is taken to be quasi-concave with \( Q_L \geq 0, Q_K \geq 0, \) and \( Q_F \geq 0. \) It is assumed that each input is required for production: \( Q(0, F, L) = Q(K, 0, L) = Q(K, F, 0) = 0. \) Also, the A-J assumption of \( s-P_K > 0 \) is adopted. The author has considered the strength of this assumption in an earlier paper. Both the regulatory constraint and the production function constraint are assumed binding for the remainder of the discussion. Thus, the relationships (2) and (3) hold as equalities.

The problem is solved by using the Lagrangian multiplier method. The Lagrangian is

\[ \mathcal{L} = -P_L L - P_F F - P_K K + \nu[-\bar{Q} + Q(K, F, L)] + \lambda(sK + P_L L + P_F F - \bar{R}), \]

where

\[ \nu \geq 0, \lambda \geq 0, \]
where \( \nu \) and \( \lambda \) are Lagrangian multipliers, and are interpreted as the change in the optimum value of the objective function for a change in the constant of the associated constraint.

The first-order conditions are:

\[
\begin{align*}
-P_L + \lambda P_L + \nu Q_L &= 0 \quad (5) \\
-P_L + \lambda P_F + \nu Q_F &= 0 \quad (6) \\
-P_K + \lambda s + \nu Q_K &= 0 \quad (7) \\
\bar{R} - P_F F - P_L L - sK &= 0 \quad (8) \\
\bar{Q} - Q(K, F, L) &= 0 \quad (9) \\
K > 0, L > 0, F > 0, \nu > 0, \lambda > 0. \quad (10)
\end{align*}
\]

Consider equation (5), which can be written as

\[
1 - \lambda = \nu Q_L / P_L. \quad (11)
\]

Since \( \nu, Q_L, \) and \( P_L \) are all nonnegative, then \( 1 - \lambda \geq 0 \) and \( \lambda \leq 1. \) If \( \lambda = 1, \) that implies [by equation (7)] that \( P_K - s = \nu Q_K \geq 0. \) But this in turn requires \( P_K \geq s, \) which contradicts the assumption that \( s > P_K. \) Thus, \( 0 < \lambda < 1. \)

Since \( s > P_K, \) then \( \lambda s > \lambda P_K \) and \( -\lambda s < -\lambda P_K. \) Adding \( P_K \) to each side, \( P_K - \lambda s < P_K - \lambda P_K. \) Dividing by \( 1 - \lambda \) gives:

\[
(P_K - \lambda s)/(1 - \lambda) < P_K. \quad (12)
\]

Equations (5), (6), and (7) imply the following relationships:

\[
\begin{align*}
Q_F/Q_K &= P_F/(P_K - \lambda s)/(1 - \lambda) \quad (13) \\
Q_L/Q_K &= P_L/(P_K - \lambda s)/(1 - \lambda) \quad (14) \\
P_L/P_F &= Q_L/Q_F. \quad (15)
\end{align*}
\]

The term \( (P_K - \lambda s)/(1 - \lambda) \) can be interpreted as the implicit or shadow price of capital used by the constrained firm in its decision process. In that this price is less than the market price, \( P_K, \) capital is used more intensively in production of \( Q \) than would be the case if the firm were allowed unconstrained cost minimization. Intuitively, what occurs is that the firm must increase its allowable profits \( (sK) \) if the regulatory constraint is not to be violated. By substituting capital for other inputs, total allowable profits are increased because the base to which \( s \) is applied is expanded. Thus, while costs, \( P_K K + P_F F + \lambda L, \) do increase, the constraint is in a sense relaxed, and the opportunity set of the firm in terms of total allowable profits is expanded.

Equations (8), (13), (14), and (15) form a system of four equations in four unknowns, \( K^*, L^*, F^*, \lambda^* \), where the asterisks denote the optimum values of the variables. These equations can be solved, at least conceptually, in terms of the parameters of the system; \( \bar{Q}, P_K, P_L, P_F, \) and \( s. \) The optimum input bundle for the constrained firm is given by:

\[
\begin{align*}
K^* &= K(\bar{Q}, P_L, P_F, P_K, s) \quad (16) \\
L^* &= L(\bar{Q}, P_L, P_F, P_K, s) \quad (17) \\
F^* &= F(\bar{Q}, P_L, P_F, P_K, s). \quad (18)
\end{align*}
\]
Since \( C^* = P_lL^* + P_FF^* + P_KK^* \), equations (16), (17), and (18) imply
\[
C^* = C(\tilde{Q}, P_L, P_F, P_K, s).
\] (19)
Equation (19) is the general relationship from which the statistical models of Section 3 are derived.

The effect of changes in \( s \) on the cost which the firm incurs to produce the output \( \tilde{Q} \) can be determined by differentiating the Lagrangian expression (4) with respect to \( s \):
\[
\frac{\partial \mathcal{L}}{\partial s} = \lambda K.
\] (20)
The first-order conditions for an optimum guarantee that the value of the Lagrangian, \( \mathcal{L} \), at \( K^*, L^*, F^* \), and \( \lambda^* \) is always equal to the value of the objective function, \(-C\), for all \( s \). Thus
\[
\frac{\partial \mathcal{L}}{\partial s} = \frac{\partial (-C)}{\partial s} = \lambda K
\] (21)
and
\[
\frac{\partial C}{\partial s} = -\lambda K.
\] (22)
Since \( \lambda > 0 \) and \( K > 0 \), it follows that \( \frac{\partial C}{\partial s} < 0 \).

The result is a testable hypothesis of the Averch-Johnson model. If quantity and input prices are held constant, then the cost of production increases as regulation becomes tighter, that is, as \( s \) approaches \( P_K \).

It is possible that the inverse relationship between costs and the allowed rate of return may exist for reasons other than that proposed by Averch and Johnson. For instance, it has been asserted that regulation reduces the incentive to be efficient. It is possible that costs may increase in tightly regulated jurisdictions because of an input neutral shift of the cost function as management becomes more lax. Additional implications of the model are derived to differentiate neutral upward shifts of the cost function stemming from managerial indifference from cost increases resulting from profit-maximizing management’s attempts to circumvent the regulatory constraint.

Consider first the model’s implications regarding \( d(P_K/C)/ds \), or the change in the percent of total cost going to capital for a change in the allowed rate of return, with output held constant. Note that
\[
d(P_K/C)/ds = \frac{P_K}{C} \left( -\frac{dK}{ds} \cdot \frac{1}{K} - \frac{dC}{ds} \cdot \frac{1}{C} \right),
\] (23)
which indicates that the percent spent on capital increases if the percentage change in capital used in production is greater than the percentage change in total cost.

Since \( C = P_KK + P_LL + P_FF \), then
\[
dC/ds = P_l dL/ds + P_F dF/ds + P_K dK/ds.
\] (24)
Substituting (24) into (25) gives
\[
\frac{d(P_K/C)}{ds} = \frac{P_K}{C} \left[ \left( \frac{dK}{ds} \right) \left( \frac{C - P_KK}{CK} \right) \right. \\
- \left. \left( \frac{P_l dL/ds + P_F dF/ds}{C} \right) \right].
\] (25)
Since $C = P_hK > 0$, if it can be shown that $dK/ds < 0$ and $P_LdL/ds + P_FdF/ds > 0$, then it is also true that $d(P_hK/C)/ds < 0$. These relationships are investigated using comparative statics procedures.

Differentiating the first-order conditions of the model completely with respect to $K$, $F$, $L$, $s$, $\lambda$, and $v$ generates the following system of equations:

$$
\begin{bmatrix}
P_L & Q_L & v_{QL} & v_{QLK} & v_{QLF} \\
P_F & Q_F & v_{QFL} & v_{QFK} & v_{QFF} \\
F & Q_K & v_{QKL} & v_{QFK} & v_{QKF} \\
0 & 0 & P_L & s & P_F \\
0 & 0 & Q_L & Q_K & Q_F
\end{bmatrix}
\begin{bmatrix}
dK/ds \\
dL/ds \\
dF/ds \\
0 \\
0
\end{bmatrix}
= 
\begin{bmatrix}
0 \\
0 \\
0 \\
-\lambda \\
-K
\end{bmatrix}
$$

(26)

Solving by Cramer’s rule gives

$$
dK/ds = KQ_L/(Q_K/s - Q_L/P_L)P_Ls.
$$

(27)

But $Q_K/s - Q_L/P_L$ is negative by (14), hence $dK/ds < 0$. As regulation tightens, the firm uses more and more capital to produce the output $\bar{Q}$.

The expressions for $dL/ds$ and $dF/ds$ can be derived in a similar manner. Their signs, however, cannot be specified without additional assumptions. Fortunately, equation (25) requires only that the sign of $P_LdL/ds + P_FdF/ds$ be determined. A tedious number of algebraic operations results in

$$
P_h dL/ds + P_F dF/ds = -KQ_L/(Q_K/s - Q_L/P_L),
$$

(28)

which is positive by (14). Thus $P_LdL/ds + P_FdF/ds > 0$ and $dK/ds < 0$. Hence, by equation (25), it is known that $d(P_hK/C)/ds$ is negative.

By way of review, it is asserted that if the A-J analysis is a meaningful description of the behavior of the constrained firm, then the following relationships hold for production of the level of output $\bar{Q}$:

$$
dC/ds < 0
$$

(29)

and

$$
d(P_hK/C)/ds < 0.
$$

(30)

3. Statistical model

Previous empirical researchers have investigated the electric power industry.\(^7\) These studies, taken together, provide a framework for the choice of a functional form for this analysis. The basic properties which will be required of the chosen form are that it allow for increasing (and changing) returns to scale, that it be amenable to estimation using three factors (capital, labor, and fuel), that it be augmentable by a technological change parameter, and that it not impose \textit{a priori} restrictions on elasticities of substitution between factors. Also, as a statistical convenience, it should be estimable by standard linear methods.

The three common functional forms used in the estimation of cost and production functions are the linear form, the Cobb-
Douglas form, and the constant elasticity of substitution (CES) form. Each of these is deficient with respect to at least one of the above criteria.

In this analysis, rather than begin with a definite functional form, we consider the general cost function

\[ \ln C = \delta_T + C(\ln X_1, \ln X_2, \ldots, \ln X_n), \quad (31) \]

where the \( X_i \) are the arguments of the cost function (the input prices, output levels, and regulatory variables), and \( \delta_T \) allows for input neutral technological change. That is, it is allowed that the log of cost of producing a given output may shift by some factor \( \delta_T \) over time.

The exact functional form of equation (31) is not known, but, following the procedure adopted by Jorgenson, Christensen, and Lau, we assume that the true functional form can be approximated sufficiently accurately for the purpose at hand by a second-order Taylor series approximation of (31) about \( \ln X = [0] \), where \( X \) is a column vector of the \( X_i \), and \( [0] \) is an \( n \)-element column vector of zeros:

\[
\ln C = \delta_T + C(\ln X = [0]) + \sum_{i=1}^{n} \frac{\partial C}{\partial \ln X_i} \bigg|_{\ln X = [0]} \cdot \ln X_i \\
+ \frac{1}{2} \sum_{i=1}^{n} \sum_{j=i}^{n} \frac{\partial^2 C}{\partial \ln X_i \partial \ln X_j} \bigg|_{\ln X = [0]} \cdot \ln X_i \ln X_j,
\]

where \(|\ln X = [0]\) indicates that the derivatives are to be evaluated at \( \ln X_i = 0 \) for all \( i \) and \( j \).

Denote the constant terms as

\[
C(\ln X = [0]) = \alpha' \quad (33)
\]

\[
\left. \frac{\partial C}{\partial \ln X_i} \right|_{\ln X = [0]} = \alpha' i \quad \text{for all } i \quad (34)
\]

\[
\left. \frac{\partial^2 C}{\partial \ln X_i \partial \ln X_j} \right|_{\ln X = [0]} = \gamma_{ij} \quad \text{for all } i \text{ and } j. \quad (35)
\]

Hence, the cost function can be written as

\[
\ln C = \alpha' + \delta_T + \sum_{i=1}^{n} \alpha' i \ln X_i + \frac{1}{2} \sum_{i=1}^{n} \sum_{j=i}^{n} \gamma_{ij} \ln X_i \ln X_j. \quad (36)
\]

In that the expansion is about zero, the accuracy of the approximation depends on how closely each \( \ln X_i \) approaches zero. The approximation error can be minimized by setting the mean of each \( X_i \) to unity. This is done using the normalization,

\[
X'_{ik} = \frac{X_{ik}}{\frac{1}{m} \sum_{j=1}^{m} X_{ij}} \quad \text{for each } i, \quad (37)
\]

where \( X_{ik} \) is the \( k \)-th observation of the \( i \)-th variable, and \( m \) is the number of observations. For the logs of \( X'_i \) to be well defined, it is necessary that each \( X_{ik} \) be positive.

The functional form of (36) has \( 2 + (n/2)(n + 3) \) coefficients to be estimated. It imposes few \textit{a priori} restrictions on the
parameters. Returns to scale cannot only be increasing, but can vary for different levels of output. The elasticity of substitution varies between inputs and for different levels of input usage. Technological change has been incorporated, and the model is easily estimable by simple linear methods. Thus, all of the requirements of functional form indicated by previous studies are satisfied.\(^9\)

In terms of the variables of Section 2, equation (36) becomes

\[
\ln C' = \alpha_0 + \delta T + \alpha_0 \ln Q' + \alpha_0 \ln P'_L + \alpha_0 \ln P'_F + \alpha_0 \ln P'_K
+ \alpha_0 \ln ((s - P_K)') + \gamma_{QQ}(\ln Q')^2 + \gamma_{LL}(\ln P'_L)^2
+ \gamma_{RR}(\ln P'_R)^2 + \gamma_{RF}(\ln P'_F)^2 + \gamma_{QF}(\ln Q' \ln P'_F)
+ \gamma_{QL}(\ln Q' \ln P'_L) + \gamma_{QP}(\ln Q' \ln P'_P) + \gamma_{QP}(\ln Q' \ln P'_P)
+ \gamma_{QR}(\ln Q' \ln P'_R) + \gamma_{LR}(\ln P'_L \ln P'_R)
+ \gamma_{LF}(\ln P'_L \ln P'_F) + \gamma_{RF}(\ln P'_F \ln P'_R)
+ \gamma_{QF}(\ln Q' \ln P'_F) + \gamma_{RF}(\ln Q' \ln P'_F)
+ \gamma_{FR}(\ln P'_F \ln P'_R) + \gamma_{FR}(\ln P'_F \ln P'_R),
\]  

(38)

where the primes denote the normalized variables as given by equation (37), \(T\) is an index of technology, the \(P_i\) are input prices, \(Q\) is quantity, and \(s - P_K\) is the difference between the allowed rate of return and the cost of capital, or “regulatory tightness.” Equation (38) is the basic equation for determining the effect of regulation on unit costs.

Next we consider the percentage of total expenditure going to capital. The estimating equation chosen is

\[
P_{K/C} = b_0 + b_0 \ln Q' + b_0 (\ln Q')^2 + b_k \ln P'_K
+ b_f \ln P'_F + b_L \ln P'_L + b_R \ln ((s - P_K)'),
\]  

(39)

The theoretical model of Section 2 predicts that \(b_R\) should be negative if an A-J effect is operative.

The statistical analysis is carried out using ordinary least squares (OLS). Behind the OLS methodology is the assumption that all variables on the right-hand side of equations (38) and (39) are either exogenous or predetermined. The presence of endogenous variables generates estimates of the coefficients which are biased. The \(P_i\) are exogenous as is \(s\) if the political influence of the firm on the commission is taken to be negligible. The quantity terms require some discussion. If there is no A-J effect, that is if the firm does not manipulate costs in the attempt to circumvent the regulatory constraint, then technology dictates costs and the price set by the commission is determined by technology and the allowed rate of return. Quantity as a function of price is, thus, exogenous to the firm. On the other hand, if tighter regulation results in higher costs, then the firm may be able to manipulate price and, hence, quantity. Note that as \(s\) decreases, costs increase. It is assumed that, if an A-J effect is operative, the two are offsetting, and the price fixed by the commission remains unchanged in equilibrium. Thus, quantity is exogenous to the firm. Such a result is a possible explanation for Stigler-Friedland’s finding\(^10\) that regulation had no effect on

\(^9\) The properties of functional forms such as (38) are discussed in Jorgenson, Christensen, and Lau [11].

\(^{10}\) In [18].
prices. In a related study the author has relaxed the assumption of quantity being exogenous and, using a simultaneous equation model and a different data set, tested for the A-J effect. The results are consistent with those of this analysis.

The sample consists of fifty-six steam generating plants which experienced at least a fifty-percent expansion during the period 1960 to 1965. These are observed over the three-year period, 1966 to 1968. The selection of plants which significantly expanded capacity is dictated by the theoretical model which is derived in marginal terms. The analysis suggests that regulation causes planners to choose excessively capital-intensive production. Only in plants where capacity is being added is there much possibility for capital-other input substitution. Ex post substitution in the industry is probably very limited.

The dependent variable used in estimation of (38) is the log of cost of production per unit of output in terms of dollars per thousand KWH. The dependent variable associated with (39) is the percent of total cost going to capital.

Output is in terms of millions of KWH of power. Fuel price is given as cost per million British Thermal Units of energy. The wage rate is expressed as dollars per year per employee. The capital price is formulated in terms of the annual rental price of capital as suggested by Jorgenson. That is,

\[ P_K = q(r + \delta - \dot{q}), \]

where \( q \) is the price of equipment, \( r \) is the interest rate, \( \delta \) is the rate of depreciation, and \( \dot{q} \) the rate of price change for equipment. An index of technology is constructed by determining the computed average time that capital had been in service. A dummy variable is included to distinguish plants which are owned by firms which are part of interstate holding companies. Participation in holding companies may be considered to be an additional scale variable.

Tightness of regulation proved difficult to quantify. Three measures are used in the analysis. First, as has been noted, four states during the study period did not have statewide regulatory commissions. Regulation is assumed to be less effective in these states. Thus, the model suggests that cost per unit of output should be lower in plants which operate in these states. Actual data consist of a dummy variable which takes on a value of one in states with commissions and zero in the states without commissions.

Second, state commissions can be characterized as determining the rate base on an original cost basis or on a fair value basis. The former method uses the value of the firm’s capital as it appears on the firm’s books, while the latter gives recognition to increased capital costs over time and may be five to fifty percent higher than original cost. Eiteman and Stuart found that when the rate base was adjusted so as to be comparable in
these two types of jurisdictions, a higher rate of return was, on average, allowed in fair value states. The differential was statistically significant. Thus, a second measure of "regulatory tightness" adopted is division of plants which operate in fair value states from those which operate in original cost jurisdictions. It is assumed that fair value regulation is more liberal in terms of allowed profits. The theoretical model predicts that average cost and percentage of cost going to capital should be lower in plants operating in these states. Data assume the form of a dummy variable taking on a value of one in states with original cost commissions and zero for states with fair value commissions or no state commission.

A third method of measuring regulatory stringency examines the return to equity capital. Because of the residual nature of the return to common stockholders, it is here that liberal or conservative commission policies are most dramatic. In a rate case an overall return on the capital base is allowed. Out of this total the firm must meet its debt, preferred stock, and common stock obligation; and its legal priorities are in that order. Fixed debt and preferred stock interest and dividends must be paid before common stockholders can receive dividends. Because of this legal priority, a one-percent change in the overall rate of return has a multiplied effect on the return to equity. If the firm has fifty-percent common stock in its capitalization, a one-percent change in the allowed rate of return has a two-percent effect on the return to equity. Thus, it is on the common stockholder that "tightness of regulation" is really felt.

The relationship between \( s - P_K \), the average allowed return minus the average cost of capital, and \( s_e - P_e \), the average return to equity minus the cost of equity, is just \( s - P_K = (s_e - P_e)(1 - \beta) \), where \( \beta \) is the percent of debt capital in the rate base. An index of \( s_e - P_e \) can be derived based on the assumption that capital markets are efficient in their evaluation of a firm's relative profitability.

The value of a utility's stock at time 0 is given by the discounted value of the expected dividend stream,

\[
MV_0 = \sum_{t=1}^{\infty} \frac{D_t}{(1 + P_e)^t},
\]

where \( MV_0 \) is the price of the firm's common stock at time 0, \( D_t \) is the dividend at time \( t \) and is given by the relationship \( D_t = D_0(1 + g)^t \), where \( g \) is a constant rate of dividend growth.\(^{14}\)

If the rate of dividend growth is less than the cost of capital, then (41) becomes

\[
MV_0 = \frac{D_0}{P_e - g},
\]

which can be solved for \( P_e \):

\[
P_e = \frac{D_0}{MV_0} + g.
\]

To return to equation (42), the dividend paid at time \( t \) is just the dividend pay-out ratio, \( d \), times earnings per share for the

\(^{14}\) This model of stock price valuation is found in most introductory finance texts such as Van Horne [20].
period, \( EPS_t \). Earnings per share for the regulated firm are constrained to be less than or equal to the allowed return on equity capital, \( s_e \), times the total of equity capital, \( X_t \), divided by the number of common shares outstanding, \( n \). Hence

\[
MV_0 = d(s_eX_t/n)(P_e - g).
\]  
(44)

But \( X_t/n \) is just book value of common equity per share, \( BV_0 \). Substituting and solving for \( s_e \) gives

\[
s_e = MV_0(P_e - g)/dBV_0.
\]  
(45)

Substituting in the expression for \( P_e \) of equation (43) gives

\[
s_e = MV_0(D_t/MV_0)/dBV_0 = D_t/dMV_0.
\]  
(46)

Thus, the difference between \( s_e \) and \( P_e \) is given by

\[
s_e - P_e = D_t\left[\frac{1}{dBV_0} - \frac{1}{MV_0}\right] - g
\]  
(47)

Equation (47) suggests that a continuous variable measuring regulatory stringency can be derived by using the firm’s dividend, dividend pay-out ratio, book value of equity, stock price, and expected growth rate in dividends. It was previously noted that \( s_e - P_e \) should be adjusted for capitalization differences. The notation \( SS \) is used to denote \( s_e - P_e \) adjusted for capitalization. The data used in determining \( SS \) are those for the firm owning the plant under observation. Firms which are part of interstate holding companies had to be eliminated when using this measure because the financial data necessary were not always available on a firm basis. Nine plants were excluded from the original sample for this reason.

In the actual use of the data, the continuous variables were normalized to meet the specifications of Section 3. An exception is that of \( SS \) with several negative values for which the log is not defined. \( SS \) is used in linear form with mean equal to zero. The data are further discussed by Petersen in an earlier work.\(^{15}\)

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\(^{15}\) The notation used in this section and the criteria for statistical significance of the coefficients are given in the Appendix. The numbers in parentheses beneath the coefficients are the associated \( t \)-values.

The unit cost regressions using \( REG \) and \( FAIR \) are carried out using a modified Cobb-Douglas functional form. Only the continuous variable, \( SS \), is used to estimate the generalized cost function of Section 3.\(^{16}\)

\( REG \) is significant at 0.01, but the \( FAIR \) variable is not significant. However, both coefficients are positive as predicted by the theoretical model. Firms in jurisdictions with state commissions and those in states with commissions setting the rate base on an original cost basis have higher unit costs. Unit costs

\(^{16}\) \( SS \) as developed in Section 4 is not used simultaneously with \( REG \) and \( FAIR \) because they are designed to measure the same dimensions of regulatory policy.
in states with commissions are, on average, seven percent higher.

Signs of other coefficients are consistent with *a priori* expectations. Fuel, labor, and capital price coefficients are all positive and significant. Newer vintage plants have significantly lower costs. The coefficients of the quantity variables imply that average costs decrease with quantity out to a minimum of 4447 million KWH. Only seven plants in the sample exceeded that level of production.

**Regression A**

\[
LCOST' = -0.1717 + 0.0880NH - 0.1008LQ' + 0.0590LQ'\,LQ' \\
(3.85) \quad (-8.11) \quad (8.42)
\]

\[+ 0.6237LF' + 0.1784LL' + 0.2680LK' - 0.0189TC - 0.0006Y \\
(15.26) \quad (2.75) \quad (2.18) \quad (-4.45) \quad (-0.06)
\]

\[+ 0.0701REG + 0.0013FAIR \\
(3.04) \quad (0.08)
\]

Number of observations: 168

\[R^2 = 0.82.
\]

Regression B uses the generalized cost function, but without the interaction terms of SS with LQ, LF, LL, and LK. The joint hypothesis that the coefficients of these terms are all zero cannot be rejected. The computed *F*-statistic is 0.759. The critical value at 0.05 is 2.45. The hypothesis that the appropriate functional form (when using SS) is a modified Cobb-Douglas, such as was used in Regression A, is, however, rejected.

The effect of changes in SS on the log of costs is given by:

\[
\frac{d\ln C'}{dSS'} = -3.627 - 550.2(\text{SS'}).  \quad (48)
\]

Equation (48) has a maximum at SS' = -0.0066. In accordance with the requirements of Section 3, SS was normalized to have a mean equal to zero. In terms of the original data, the maximum occurs at SS' = 0.005. Less than fifteen percent of the observations on SS do not exceed that maximum point. The result suggests that the cost inflating effects of regulation can be reduced if the firm is regulated very tightly, but such an interpretation undoubtedly gives greater credit to the data and estimation procedures than their precision would justify. The estimates do suggest, however, that as regulation tightens, costs increase—although evidently at a decreasing rate.

For the other estimated coefficients of Regression B, all linear terms in input prices are positive and significant. Technology results in a decrease in costs, and the unit cost curve decreases to a minimum at 7358 million KWH. This level is greater than for all but three of the output observations.

**Regression B**

\[
LCOST' = -0.0185 - 0.1160LQ' + 0.0409LQ'\,LQ' - 0.0127TC \\
(-7.81) \quad (4.19) \quad (-3.20)
\]
Turning to the percent of cost paid to capital, the basic estimating equation is (39). In actual practice, the $Y$ and $TC$ variables are included to allow for year-to-year and technology effects, and the $NH$ variable to adjust for differences attributable to holding companies.

Using $REG$ and $FAIR$, it is found that their coefficients are both positive and that of $REG$ is significant at 0.01. Tighter regulation is associated with a greater proportion of cost going to capital. Looking at the other coefficients, both the linear and quadratic terms in quantity are significant. They suggest that there are savings on the use of capital in comparison to other inputs up to some point. The coefficient of the fuel price is negative and significant. The cost of fuel makes up a large component of total costs as found in the denominator of $PC$. The coefficient of the wage rate is positive and significant. This might be explained by substitution of capital for labor as wages increase, however previous studies such as that by Dhrymes and Kurz\textsuperscript{17} found little substitution between labor and capital. The capital price coefficient is negative but not significant. A possible explanation is that high rental rates on capital increase the cost of using a given amount of capital, but this is offset by substitution of other inputs (primarily fuel) as capital becomes more expensive. An interesting conclusion is that newer technology in a plant seems to have no effect on the share of cost going to capital. This suggests that technology has been neutral among inputs or at least for capital as compared to labor and fuel considered together.

Regression C

\[
P_C = -0.0502 - 0.0114LQ' + 0.0132LQ'LQ' - 0.1510LF' \\
(-2.40) (4.89) (-9.63)
+ 0.0675LL' - 0.0037LK' - 0.0003TC - 0.0083Y \\
(2.71) (-0.29) (-0.20) (-2.30)
+ 0.0223NH + 0.0267REG + 0.0026FAIR \\
(2.53) (3.02) (0.38)
\]

Number of observations: 168
$R^2 = 0.49$.

When the continuous variable $SS$ is used to determine the effect of regulation on the proportion paid to capital, the findings

\textsuperscript{17} In [7].
are similar to those of Regression C. The signs of the quantity and input price variables are the same. Their magnitudes and t-statistics change quantitatively, but the comments made for Regression C still hold. SS is negative and significant at 0.01. As regulation becomes more stringent, the firm spends a greater fraction of total cost on capital.

Regression D

\[
PC = -0.0036 - 0.0095LQ' + 0.0132LQ'LQ' - 0.1878LF' \\
\quad (-1.80) (4.62) (-9.09) \\
+ 0.1023LL' - 0.0253LK' + 0.0013TC - 0.0090Y - 1.336SS' \\
\quad (3.53) (-0.41) (0.70) (-2.20) (-2.96)
\]

Number of observations: 141
\[R^2 = 0.50.\]

6. Summary and conclusion

The Averch-Johnson model provides analytical support for the proposition that rate of return regulation may result in inefficient production. In this paper the A-J model is reformulated in terms of cost-minimization subject to the regulatory constraint. It is shown that as regulation tightens, that is, as the allowed return approaches the cost of capital, the firm has higher unit costs and spends a larger portion of total cost on capital. These two relationships are testable hypotheses of the revised A-J model.

A general functional form is adopted for empirical analysis. This form does not put a priori restrictions on the coefficients of the cost function. The sample consists of steam generating plants which experience a large addition to capacity just prior to the sample period, 1966 to 1968. Three measures of regulatory policy with regard to the allowed return are used. The first is the dichotomy between firms operating in states with state commissions and those without. The second is the separation of original cost from fair value rate base jurisdictions. It is assumed that regulation is more strict in states with state commissions and in original cost jurisdictions. The third measure is an attempt to measure the actual difference between the allowed return and the cost of capital.

The evidence supports the hypotheses. Using both a modified Cobb-Douglas and the more general form of the cost function, it is found that as regulation tightens, unit costs increase. The result is statistically significant using the state commission versus no state commission dichotomy and also using the continuous measure of the allowed return minus the cost of capital. It is also found that the percent of cost going to capital increases with more stringent regulation. This result is also statistically significant when the same two measures are used.

In summary, the findings of this analysis are that the empirical evidence does support the Averch-Johnson contention. The conclusions here are also generally consistent with those previously reported by Spann and by Courville. Additional results on
this topic and on other effects of regulation are presented in an earlier work of the author.\(^\text{18}\)

Appendix

The following notation is used in reporting the results of the econometric analysis:

\begin{itemize}
  \item \textbf{LCOST} Log of unit cost of production.
  \item \textbf{PC} Percent of total unit cost going to capital.
  \item \textbf{Y} Year of observation.
  \item \textbf{TC} Index of technological change.
  \item \textbf{LQ} Log of quantity produced.
  \item \textbf{LL} Log of annual wage rate.
  \item \textbf{LK} Log of capital rental rate.
  \item \textbf{LF} Log of fuel price.
  \item \textbf{REG} Dummy variable. Value equals one for firms under state commission.
  \item \textbf{FAIR} Dummy variable. Value equals one for firms regulated on an original cost basis.
  \item \textbf{SS} Allowed return on equity minus the cost of equity capital adjusted for capitalization differences.
  \item \textbf{NH} Dummy variable. Value equals one if firm is part of a holding company.
  \item \textbf{LQLQ} Log of quantity times log of quantity.
  \item \textbf{LQLL} Log of quantity times log of wage rate.
  \item \textbf{LQLF} Log of quantity times log of fuel price.
  \item \textbf{LQLK} Log of quantity times log of capital rental rate.
\end{itemize}

In general, products of two variables required by equation (38) are denoted by \(L_iL_j\) where \(L_i\) and \(L_j\) are the respective variable names. The last four entries in the column above are examples.

Standard tests of statistical significance are used. In most cases a coefficient will be considered significantly different from zero if it passes a two-tailed \(t\)-test at an alpha level of 0.05. If the sign of the coefficient is given by the theoretical model or a priori expectation, then a one-tail test at 0.05 will be the criteria.

References


\(^{18}\) In [14].


13. PETERSON, H. C. "The Allowed Rate of Return vs. the Marginal Cost of Capital in a Public Utility Rate Case." #74-2, Center Study Papers, Economics Research Center, Utah State University, January, 1974.


