

16 **Abstract**

17 Quantification of evapotranspiration (ET) is crucial for understanding the water balance
18 and for efficient water resources planning. Agricultural settings have received much
19 attention regarding ET measurements while there is less knowledge regarding actual ET
20 (ET_A) in natural ecosystems. This study is focused on modelling ET_A from stony soil,
21 particularly in montane ecosystems where we estimate the contribution of stone content on
22 water retention properties in soil. We employed a numerical model (HYDRUS-1D) to
23 simulate ET_A in natural settings in northern Utah and southern Idaho during the 2015 and
24 2016 growing seasons based on meteorological and soil moisture measurements at a range
25 of depths. We simulated ET_A under three different scenarios, considering soil with (i) no
26 stones, (ii) highly porous stones, and (iii) negligibly porous stones. The simulation results
27 showed significant overestimation of modeled ET_A when neglecting stones in comparison
28 to ET_A measured by eddy covariance. Modeled ET_A estimates with negligibly porous
29 stones were much lower for all cases due to the substantial decrease in soil water storage
30 compared with estimates made considering highly porous stones. Assumptions of highly
31 porous or negligibly porous stones lead to reductions in simulated ET_A of between 10%
32 and 30%, respectively, compared with no stones. These results reveal the important role
33 played by soil stones, which can impact the water balance by altering available soil
34 moisture and thus ET_A in montane ecosystems.

35 **Keywords:** Evapotranspiration, Forest soil, HYDRUS-1D, Stony-soil, Montane
36 ecosystems

37 **1. Introduction**

38 Evapotranspiration (ET) is the largest outward flux of water and a key component of the
39 hydrological cycle and is therefore essential in quantifying the water budget and planning
40 water resources (Baldocchi and Ryu, 2011; Mu et al., 2007; Schelde et al., 2011; Sheffield
41 et al., 2010). Water flux to the atmosphere by the process of ET constitutes up to 95% of
42 the water balance in arid regions (Kool et al., 2014; Wilcox et al., 2003). However, ET
43 remains a major source of uncertainty in eco-hydrological systems, and this uncertainty
44 motivates research on more accurate quantification of ET within large-scale irrigated
45 projects and natural ecosystems. Forests have been recognized as a fundamental part of
46 ecosystems that play a key part in regulating hydrological balance by altering streamflow
47 and ET (Andreassia 2004; Ice and Stednick, 2004; Parajuli et al., 2019; Sun et al., 2008).
48 Despite the fact that many studies have been conducted on ET estimation across different
49 spatial scales ranging from point- to basin-scale (Parajuli 2015; Senay et al., 2011; Schelde
50 et al., 2011), very few focused on natural ecosystems as compared to agricultural settings.
51 Accurate quantification of ET in natural ecosystems is essential to evaluate the effects of
52 land management and global change on availability of water, streamflow, and ecosystem
53 productivity (Andreassia 2004; Parajuli 2018; Sun et al., 2008; Zhou et al., 2008).

54 Correct information about temporal and spatial variations in ET is critical for better
55 understanding of the interactions between land surfaces and the atmosphere and solving
56 the water and energy balances used in hydrological and climate models (Kumar et al., 2006;
57 Mu et al., 2007; Niu et al., 2011; Yang et al., 2011). Better estimates of ET are furthermore
58 important to improve management of water resources and agricultural systems by assisting
59 in decision making processes related to water allocations (Allen et al., 1998; Kumar et al.,

60 2006; Mu et al., 2007, Raziei and Pereira, 2013). However, it is challenging to calculate
61 ET over land surfaces characterized by heterogeneity in soil and vegetation type and in
62 other parameters affecting the ET (Mu et al., 2007; Senay et al., 2011; Sheffield et al.,
63 2010; Sun et al., 2008).

64 A number of techniques to estimate ET have been developed, such as the catchment water
65 budget method using soil and plant weighing lysimeters as well as the Bowen ratio and
66 eddy covariance methods, which have been developed and applied at different scales
67 (Prueger et al., 1997; Wilson et al., 2001). Watershed ET measurements using a catchment
68 scale water budget approach, where ET is calculated as the residual of the water balance
69 (Baldocchi and Ryu, 2011), depend on the reliability and accuracy of other observations
70 such as precipitation, runoff, drainage and infiltration. Lysimeters on the other hand can
71 provide actual ET (ET_A) by measuring weight change, though their installation and
72 maintenance costs are high. The surface energy balance approach and eddy covariance
73 technique provide alternatives to measure ET_A at spatial- and point-scales, while their
74 applications are limited due to the requirement of intensive measurements and information
75 about energy balance components (Law et al., 2002; Wilson et al., 2001). The latent heat
76 flux data collected at eddy covariance towers are considered as validation of the results
77 from hydrologic models at point- as well as regional-scales (Baldocchi et al., 1988; Wilson
78 et al., 2001).

79 Various analytical models have been developed to estimate ET where there are no direct
80 measurements. A widely used model is the Penman-Monteith (PM) equation that calculates
81 ET for a leaf or complete cover canopy based on observed meteorological parameters such
82 as net radiation, wind speed and saturation deficit. The equation also includes turbulence

83 characteristics by considering aerodynamic resistance and plant physiology via stomatal
84 resistance, both of which are difficult to determine. The PM equation can be used to
85 estimate reference ET (ET_o), which represents the hypothetical ET of a short green crop
86 (grass) that fully covers the ground with unlimited water availability, and has arbitrarily
87 low stomatal resistance (Allen et al., 1998). The ET_o is estimated based on meteorological
88 parameters and does not depend on soil water and vegetation. The actual ET (ET_A) will
89 differ and is usually less, due to limited soil moisture or stomatal response to the natural
90 ecosystem environment. As available soil moisture affects many ecological and
91 environmental processes including ET, in principle, ET can be quantified by studying the
92 soil moisture dynamics (Cai et al., 2017; Koster et al., 2004; Lv et al., 2014; Miyazawa et
93 al., 2013; Wilson et al., 2001).

94 There are numerical modeling approaches that can estimate ET_A by accounting for soil
95 moisture dynamics in the simulation of plant root water uptake and surface evaporation.
96 HYDRUS-1D is one such model that has been widely used for simulating ET_A (Hilten et
97 al., 2008; Hlaváčiková and Novák 2013; Ries et al 2015; Sadeghi et al., 2019; Solyu et al.,
98 2011; Sutanto et al., 2012). HYDRUS-1D is a physically based finite-element model for
99 simulating one dimensional flow of heat and water in variably saturated media that
100 numerically solves the modified Richards equation (Richards, 1931) accounting for root
101 water uptake as a sink term (Simunek et al., 2016). The model is able to simulate water
102 flow in and out of the soil when adequate soil and vegetation parameters are provided. Both
103 soil and vegetation are however, extremely diverse in montane ecosystems. Soil hydraulic
104 properties vary horizontally and vertically due to non-uniformity in soil properties,
105 representation of which requires detailed information on soil parameters to simulate the

106 soil water flow and root water uptake (Mohanty 2013). An advantage of the HYDRUS-1D
107 model is that it can inversely fit the soil hydraulic parameters when the measured soil water
108 content, matric potential or other relevant information is provided (Simunek et al., 2016).

109 Apart from the variation in soil texture, non-arable soils contain significant quantities of
110 stone fragments (particles with diameter >2 mm) that may modify the water storage
111 capacity of soil. Stones furthermore alter the soil hydraulic transport properties, which in
112 turn affect the available water for root uptake (Cousin et al., 2003; Novak and Knava,
113 2012). Higher stone content is expected to reduce the soil water storage capacity of stony
114 soils in comparison to the fine soil matrix (soil constituents below 2 mm in diameter;
115 Hlaváčiková et al. 2016; Novak et al., 2011; Parajuli et al., 2017a) when the stone porosity
116 is lower. Stones reduce the available water for root uptake and hence limit the rate of ET
117 (Novak and Knava, 2012; Parajuli et al., 2017; Tetegan et al. 2011). Many studies in the
118 past have neglected the presence of soil stone fragments when simulating soil moisture
119 dynamics. Two different approaches are common while dealing with stony soils. One
120 assumes the stones as a non-porous system, hence any water held by the stones is not
121 accounted for. This leads to reduced water estimation per unit volume as pointed out by
122 Cousin et al. (2003) and Ugolini et al. (1998). Plant available soil water in such cases may
123 be underestimated by up to 34% according to Cousin et al. (2003). By contrast, the second
124 approach essentially considers the stones as behaving similar to the fine soil matrix, which
125 typically has a higher water holding capacity than stones. In Cousin et al. (2003), plant
126 available water was overestimated by 39% using this second approach. It may therefore be
127 important to consider the contribution of stone fragments to soil water storage when

128 simulating soil moisture dynamics involving ET estimation, especially when soil stone
129 content is significant.

130 The objectives of this research involved: (1) Modelling ET_A using the physically based
131 numerical model, HYDRUS-1D, and validating its output against eddy covariance
132 measurements. (2) Examining the effect of stone content on estimation of ET_A from natural
133 vegetation in stony soils. (3) Comparing simulated ET_A for cases; i) neglecting the presence
134 of stones, ii) considering highly porous soil stone content and iii) considering negligibly
135 porous stone content.

136 **2. Site Description**

137 In this study, we selected four climate stations in northern Utah and one in southern Idaho
138 as shown in Figure 1. The location and general vegetation around the stations are presented
139 in Table 1. The stations in Utah are part of the innovative Urban Transitions and Arid
140 region Hydro-sustainability (iUTAH) project. The iUTAH project has developed and
141 installed several weather- and aquatic-stations to monitor and understand Utah's water
142 resources. These are referred to as GAMUT sites as they are intended to quantify processes
143 on a Gradient Along Mountain to Urban Transition (GAMUT). These stations measure
144 different aspects of climate, hydrology, and water quality in three watersheds (Logan
145 River-, Red Butte Creek- and Provo River-Watersheds; iUTAH 2014; Jones et al., 2018).

146 The climate of northern Utah and southern Idaho is typical of the montane semi-arid
147 intermountain west and varies widely with four distinct seasons: cold snowy winter, hot
148 dry summer and transition periods of spring and autumn. The majority of precipitation
149 occurs as snowfall. The higher elevation weather stations are covered with snow until May

150 or June whereas early snowmelt occurs at weather stations in lower elevations. Patches of
151 sagebrush surround the observation sites at Tony Grove, Beaver Divide and Soapstone,
152 while the Knowlton Fork station is located in a sloping meadow surrounded by tall ferns.
153 The meteorological parameters required for calculating ET_0 (reference ET), such as air
154 temperature, saturation deficit, net radiation and wind speed were recorded every fifteen
155 minutes. In addition, the soil moisture and temperature were measured at depths of 5-, 10-,
156 20-, 50-, and 100- cm using time-domain-transmissometry (TDT) at the same time step as
157 the meteorological parameters (iUTAH 2014). Blonquist et al., (2005) and Jones et al.,
158 (2005) provide detailed description of the measurement principles of TDT, where the
159 permittivity - soil moisture calibration is based on the Topp et al. (1980) equation.

160 The Low Sage site is part of the Critical Zone Observatory (CZO) located in Reynolds
161 Creek Experimental Watershed of southwestern Idaho, approximately 80 km southwest of
162 Boise, Idaho, USA. The site was equipped with sensors to collect meteorological and soil
163 data along with an eddy covariance tower to quantify water and carbon fluxes in a
164 sagebrush ecosystem. Short and long wave radiation, air temperature and humidity were
165 collected at the eddy covariance station every 30 minutes using a four-component net
166 radiometer (CNR-1, Kipp and Zonen, Delft, The Netherlands), and a temperature/humidity
167 probe (HMP155C, Vaisala, Helsinki, Finland). Ground heat flux was measured with six
168 heat flux sensors (HFT3, REBS, Seattle, WA) installed 0.08-m deep within the soil and
169 three sets of self-averaging thermocouples installed at 0.02 and 0.06-m deep (Fellows et
170 al., 2017). The meteorological station near the EC tower includes measurements of air
171 temperature, humidity, wind speed and direction and solar radiation. Weather and soil data
172 were processed at 30-minute intervals. Precipitation was measured and aggregated hourly

173 using a dual-gauge system especially designed for windy and snow dominated conditions.
174 Volumetric soil water content was recorded every hour at mean depths of 5-, 15-, 30-, 60-
175 , and 90-cm.

176 During installation of soil moisture sensors at each station, the excavated soil was analyzed
177 in order to determine the soil texture, root distribution and stone content (Parajuli et al.,
178 2017b; Patton et al., 2018). The soil description for the selected stations exhibited a high
179 degree of heterogeneity along the depth with significant volumetric stone content (v).
180 Information on vertical distribution of stone content and root density derived from the soil
181 pit description at each site is presented in Figure 2.

182 Soil pit descriptions extended from the surface to 100 cm deep in most of the stations.
183 Stone content in the bottommost layer was assumed to extend down to 200 cm, the bottom
184 boundary for numerical simulations. As shown in Figure 2, Low Sage, Tony Grove,
185 Knowlton Fork and Soapstone exhibited around $0.45 \text{ m}^3 \text{ m}^{-3}$ volumetric stone content
186 between the depth of 40- to 80-cm. Average stone content within a one-meter soil profile
187 ranged from $0.07 \text{ m}^3 \text{ m}^{-3}$ at Knowlton Fork to $0.38 \text{ m}^3 \text{ m}^{-3}$ at Tony Grove. The majority of
188 stones collected from soil pits in the iUTAH stations were sandstone with variation in their
189 individual porosities. Sandstones with coarser grains had higher porosities, close to thirty
190 percent and exhibited water retention properties similar to sandy soil. However, fine
191 grained sandstones were negligibly porous with porosities between three to five percent.
192 The water retention properties of the stones were measured by Parajuli et al. (2017a) and
193 are presented in Table 2.

194 **3. Theoretical Considerations**

195 **3.1 HYDRUS-1D Numerical Modeling**

196 In this study we used HYDRUS-1D software (Version 4.17, Simunek et al., 2013), which
197 simulates variably-saturated water flow in soil using the modified Richards equation
198 expressed as:

199
$$\frac{\partial \theta(h)}{\partial t} = \frac{\partial}{\partial z} \left[K(h) \left\{ \frac{\partial h}{\partial z} + 1 \right\} \right] - S \quad (1)$$

200 where θ is volumetric water content [$L^3 L^{-3}$], z is the vertical coordinate [L], t is time [T],
201 h is the soil matric potential [L], $K(h)$ is the unsaturated hydraulic conductivity function [L
202 T^{-1}] and S is a sink term [$L^3 L^{-3} T^{-1}$].

203 The variable boundary condition in HYDRUS-1D was governed by the effective
204 precipitation, and actual flux exchange at the soil-atmosphere interface was driven by the
205 atmospheric demand and controlled by the near-surface soil moisture described further in
206 Simunek et al. (2013). The reference evapotranspiration (ET_o) was calculated using the
207 FAO-recommended Penman-Monteith combination equation using meteorological
208 parameters (Allen et al., 1998; FAO, 1990; Monteith and Unsworth, 1990) and partitioned
209 into potential evaporation (E_p) and potential transpiration (T_p) fluxes using Beer's Law
210 (Ritchie 1972):

211
$$T_p = ET_o \cdot (1 - e^{-k \cdot LAI}) = ET_o \cdot SCF \quad (2)$$

212
$$E_p = ET_o \cdot (e^{-k \cdot LAI}) = ET_o \cdot (1 - SCF) \quad (3)$$

213 where the soil cover fraction, $SCF = 1 - \exp(-k \cdot LAI)$, k is the radiation extinction coefficient
214 (set to 0.463 for this study) and LAI is leaf area index (Simunek et al., 2013).

215 The sink term, S in Equation (1) represents the volume of water lost from the soil in unit
216 time due to root water uptake (Feddes et al., 1978) and calculated as (Simunek et al., 2013):

$$217 \quad S(h, z) = \alpha(h, z)b(z) \cdot S_p \quad (4)$$

218 where $\alpha(h, z)$ is the root-water uptake stress response function (Feddes et al., 1974, 1978).
219 S_p is the potential water uptake rate [T^{-1}]. The normalized root-water uptake distribution
220 function, $b(z)$, describes the relationship between root-water uptake and root density
221 distribution. The root distribution based on root counts from the soil pit description exhibits
222 substantial variability from site to site and is unlikely to redevelop similarly given the
223 disturbed soil being returned to the pit, thus root distribution from pit descriptions are not
224 an ideal representation (Figure 2). Hence we used the Hoffman and van Genuchten (1983)
225 method estimates as described in Simunek et al. (2013) in this study. Most of the selected
226 sites were mixed grass and sagebrush at all weather stations as indicated in Table 1. The
227 maximum crop height was considered to be 1 m with albedo 0.17 and surface roughness
228 values of 0.001 m as suggested by Simunek et al. (2013).

229 The lower boundary condition was set as a free drainage boundary, assuming an infinitely
230 deep soil profile with no effect of ground water table. The initial conditions were described
231 by the measured initial moisture content along the soil profile at time $t = 0$. The surface
232 boundary condition of the soil domain was set to the atmospheric boundary condition with
233 surface runoff. The soil parameters for the van Genuchten-Maulem water retention model
234 (Maulem 1976; van Genuchten 1980) were calibrated for each layer using inverse
235 modelling in HYDRUS-1D. The van Genuchten (1980) model is expressed as;

$$236 \quad S_e = \frac{\theta - \theta_r}{\theta_s - \theta_r} = \left[1 + (\alpha |h|)^n \right]^{-m} \quad (5)$$

237 where S_e is the effective degree of saturation [-], θ_r and θ_s are the residual and saturated
238 volumetric water contents [$\text{m}^3 \text{m}^{-3}$], α is a factor related to the inverse of the air entry
239 pressure [m^{-1}], and n and m are empirical fitting parameters related to the soil pore-size
240 distribution.

241 The HYDRUS-1D numerical model was initialized using the soil hydraulic parameters
242 obtained from field estimates. The soil profile was divided into five layers with one soil
243 moisture sensor in each layer. The first step was to calibrate the model without the effect
244 of stone content assuming the total soil profile was comprised of fine soil alone. The initial
245 soil hydraulic parameters (θ_r , θ_s , α , n and K_s) were estimated using Rosetta Lite v1.1
246 software in HYDRUS-1D, based on the sand, silt and clay fractions of fine soil obtained
247 from soil pit descriptions (Parajuli et al., 2017b; Patton et al., 2018). If the Rosetta Lite
248 predictions of θ_r and θ_s values were above the lowest or below the highest measured soil
249 moisture values in each layer, the minimum or maximum measured values were set as θ_r
250 or θ_s , respectively. Model calibration was achieved primarily by inversely fitting the soil
251 hydraulic parameters (α , n and K_s) for each of the 5 soil layers.

252 **3.2. Accounting for Stone Content in the HYDRUS-1D Simulation**

253 In order to address the impact of stone content on soil hydraulic properties and thus
254 estimation of ET_A , the stony soil was assumed to be a binary porous medium allowing two
255 different water retention properties for stone and fine soil in each layer. The dual porosity
256 water retention model (Durner 1994), which assumes equilibrium conditions, was applied
257 to satisfy the algorithm suggested by Parajuli et al., (2017a) to account for the effect of
258 stone fragments in the soil.

$$259 \quad \frac{\theta_{mix} - \theta_{r_{mix}}}{\theta_{s_{mix}} - \theta_{r_{mix}}} = w_{so} \left[1 + (\alpha_{so} h)^{n_{so}} \right]^{-m_{so}} + w_{st} \left[1 + (\alpha_{st} h)^{n_{st}} \right]^{-m_{st}} \quad (6)$$

260 where the parameters with subscript *so*, *st* and *mix* are van Genuchten parameters for fine
 261 soil fraction, stone inclusion and soil-stone mixture, respectively. The weighting factors
 262 for soil and stone fractions, w_{so} and w_{st} , at saturation are defined as:

$$263 \quad w_{so} = \frac{(1-\nu)\theta_{s,so}}{(1-\nu)\theta_{s,so} + \nu\theta_{s,st}} \quad (7)$$

$$264 \quad w_{st} = \frac{\nu\theta_{s,st}}{(1-\nu)\theta_{s,so} + \nu\theta_{s,st}} \quad (8)$$

265 where ν is the ratio of the stone fragment volume to the total soil volume (or volume
 266 fraction of stone content).

267 In order to understand the impact of variably porous stones in simulation of ET_A, two
 268 scenarios were studied where all the stones were considered as either coarse sandstones
 269 (highly porous) or fine sandstones (negligibly porous) with water retention properties
 270 expressed in Table 2.

271 The unsaturated hydraulic conductivity as a function of the stony soil effective saturation
 272 is defined by combining Eq. (6) with Mualem's (1976) pore-size distribution model as
 273 suggested by Durner et al. (1999):

$$274 \quad K(S_{e,mix}) = K_s \frac{(w_{so} S_{e_{so}} + w_{st} S_{e_{st}})^l (w_{so} \alpha_{so} [1 - (1 - S_{e_{so}}^{1/m_{so}})^{m_{so}}] + w_{st} \alpha_{st} [1 - (1 - S_{e_{st}}^{1/m_{st}})^{m_{st}}])^{st}}{(w_{so} \alpha_{so} + w_{st} \alpha_{st})^2} \quad (9)$$

275 where l is empirical parameter of the hydraulic function.

276 4. Results

277 4.1 Calibration of the HYDRUS-1D model

278 The soil hydraulic parameters were optimized for different soil layers as described in
279 Section 3.1 without considering the effect of stone content at each monitoring station. The
280 initial as well as optimized soil hydraulic parameters at different depths are provided as
281 supplementary material. The simulation period started following snowmelt, when the soil
282 moisture was near field capacity. The Low Sage station in Idaho had early snowmelt
283 allowing us to initialize the model on DOY 100 (10 April 2015), while iUTAH stations in
284 Northern Utah were snow covered until about the middle to the latter part of May. In order
285 to compare the same time period, simulations started on DOY 148 (28 May 2015) at all
286 iUTAH stations running until the end of September (DOY 274). The same period was
287 selected for both years to have better comparison of ET estimates under different
288 conditions. Daily precipitation plotted in Figure 3 shows that 2016 experienced much less
289 rainfall than 2015. The four iUTAH stations illustrated in Fig. (1) have recorded similar
290 rainfall patterns over the period. There were several rain events during the simulation
291 period in 2015, but 2016 remained relatively dry with one major precipitation event
292 towards the end of September (DOY 268).

293 Measured volumetric water content and HYDRUS-1D simulations of water content at soil
294 profile depths of 5-, 15-, 30-, 60-, and 90-cm from the Low Sage station are presented in
295 Figure 4. Variation in rainfall is expected to alter the soil moisture dynamics in both years.
296 The volumetric water content approached the saturation level during spring snowmelt, but
297 these montane soils drain quickly to field capacity once snowmelt ceases. Rain events
298 during the summer of 2015 recharged the soil profile to a depth of 30 cm as shown in

299 Figure 4. There was no significant rain event during the simulation period in 2016, and the
300 soil dried down towards the end of the growing season.

301 Simulation results for the four iUTAH sites using HYDRUS-1D are compared with TDT
302 measured soil moisture contents at 5-, 10-, 20-, 50-, and 100-cm in Figure 5. Soil moisture
303 dropped rapidly from a near-saturated condition at the beginning of the growing
304 season/simulation period. Similar to Figure 4, the sensors at depths 5-, 10- and 20-cm
305 reflected the effect of rainfall with rapid rise in moisture content readings during 2015;
306 however, the amount of precipitation was not enough to wet the sensors below 20 cm
307 throughout the growing season.

308 The goodness of fit to the measured soil moisture values with the HYDRUS-1D simulation
309 are expressed in terms of coefficients of determination (R^2) and root mean squared errors
310 (RMSE) shown in Table 3. The calibrated HYDRUS-1D simulation results compared well
311 with measured soil moisture at each depth for both years. The coefficients of determination
312 (R^2) were greater than 0.8 for most depths, while a few of the simulation depths had R^2 as
313 low as 0.65 (Table 3). The RMSE remained less than $0.04 \text{ m}^3 \text{ m}^{-3}$ on average for all the
314 stations. The few R^2 values below 0.8 and RMSE values greater than $0.03 \text{ m}^3 \text{ m}^{-3}$ for
315 individual depths are bolded for clarity in Table 3. The match between simulated and
316 observed water contents at different depths in all stations suggests the HYDRUS-1D model
317 hydraulic parameters were well calibrated to represent the soil hydrodynamics.

318 **4.2 Simulation of Actual Evapotranspiration**

319 At first the root water uptake and evaporative fluxes from soil and plants were simulated
320 by HYDRUS-1D to provide an estimate of the ET_A without considering the effect of stones.
321 Daily ET_A estimates simulated by HYDRUS-1D were compared with eddy covariance

322 measurements of ET_A at the Low Sage station as illustrated in Figure 6. The daily ET_A
323 simulated by the HYDRUS-1D model followed the seasonal patterns of eddy covariance
324 measured ET_A very well (Figure 6). The correlation between the eddy covariance
325 measurements and the HYDRUS-1D simulation of ET_A without stone content effects was
326 found to have an R^2 of 0.78 and 0.76 for years 2015 and 2016, respectively (Figure 7, Table
327 4). Similarly, the RMSE values for 2015 and 2016 were 0.64 mm/day and 0.51 mm/day,
328 respectively (Table 4). The HYDRUS-1D model periodically overestimated ET_A compared
329 to the eddy covariance measurements, mostly around rain events. The cumulative ET_A
330 measured by eddy covariance for the period DOY 101 (10 April) to DOY 273 (30
331 September) was 305 mm and 221 mm in 2015 and 2016, whereas the HYDRUS-1D
332 simulation estimated 332 mm and 198 mm in 2015 and 2016, respectively. This
333 overestimation of ET_A simulated by HYDRUS-1D in 2015 and the underestimation in 2016
334 is also evident from the scatter plot for the no stones condition shown in Figure 7. However,
335 the seasonal total ET_A values from HYDRUS-1D were in good agreement with the eddy
336 covariance results.

337

338 **4.3. Effect of Stone Content on Evapotranspiration**

339 With the aim of analyzing the impact of stone content on ET_A , we simulated three different
340 scenarios assuming soil for all five sites with: no stones; highly porous stones (Coarse
341 Sandstone); and negligibly porous stones (Fine Sandstone). The average stone content for
342 each layer was estimated based on the soil pit description also presented in Figure 2. The
343 water retention parameters for the highly and negligibly porous stone considered for this
344 study were measured in the laboratory (Parajuli et al., 2017a) and are presented in Table 2.

345 The simulation in the Low Sage site where the average stone content was $0.18 \text{ m}^3 \text{ m}^{-3}$
346 showed substantial improvement in estimation of ET_A , when the stones were considered
347 as negligibly porous stones. The R^2 values increased slightly while RMSE values were
348 lower under the negligibly porous stone scenario for both years (Table 4). The result
349 supported our assumption, namely, that if we could quantify the stone content in the soil
350 properly and include that in the soil moisture simulation, the ET_A from stony soil would be
351 estimated more accurately.

352 Figure 8 shows the cumulative ET_A simulated by HYDRUS-1D under the three different
353 scenarios considering soil with no stone, highly porous stone and negligibly porous stone
354 at each station. With the purpose of comparing ET_A over the same period for each site, the
355 cumulative ET is presented from DOY 148 (28 May) to DOY 273 (30 September) for all
356 stations. In general, the cumulative ET_A over the same period in 2016 is much less than
357 that from 2015 for all stations providing us with the impression that the available soil
358 moisture limited the ET_A . The year 2016 was considerably drier than 2015, resulting in
359 reduced soil water storage, which is also implicit in Figure 4 and 5.

360 The simulations under different conditions revealed significant reductions in cumulative
361 ET_A at the Tony Grove and Soapstone stations. The percent changes in simulated actual
362 transpiration (T_A), evaporation (E_A) and ET_A for conditions with highly porous stones and
363 negligibly porous stones with reference to soil without stones, is presented in Table 5. The
364 cumulative ET_A was reduced by 10% and 21% at Tony Grove and 1% and 17% at
365 Soapstone for assumptions of highly- and negligibly-porous stones, respectively (Table 5).
366 However, there was not any noticeable change in cumulative ET_A at the Knowlton Fork
367 station where the average stone content was $0.07 \text{ m}^3 \text{ m}^{-3}$. The Low Sage station that has

368 average stone contents of $0.16 \text{ m}^3 \text{ m}^{-3}$, exhibited a slight reduction in cumulative ET_A , about
369 4% and 10% when considering stony soil with negligibly porous and highly porous stones.
370 Similarly, the Beaver Divide station with average stone content of $0.18 \text{ m}^3 \text{ m}^{-3}$ showed
371 reduction in ET_A by nearly 3% while assuming highly porous stone and by 7% assuming
372 negligibly porous stones for both years. In contrast, the ET_A simulations for Beaver Divide
373 in 2016 showed incremental changes when considering either stone type.

374 **5. Discussion**

375 **5.1 Soil Moisture Dynamics and Model Calibration**

376 The inverse simulation was executed based on the goodness of fit between the measured
377 and simulated soil moisture, however the measured soil moisture may not directly include
378 and therefore represent stone content within the sensing volume. The ability of soil
379 moisture sensors to account for the stone content is limited by their sensing volume (Vaz
380 et al., 2013) and by the size of the surrounding stones (Coppola et al., 2013). In our study,
381 soil moisture sensors were generally installed as to intentionally avoid stones around
382 sensors. Hence measurements directly report soil moisture content of the soil matrix
383 without stone content and therefore, calibration of the soil hydraulic parameters in the
384 HYDRUS-1D numerical model was performed without directly accounting for the stone
385 content. The HYDRUS-1D model was able to simulate the soil moisture remarkably well
386 in all five stations with significant correlation of R^2 greater than 0.8 and RMSE less than
387 $0.04 \text{ m}^3 \text{ m}^{-3}$. These estimates were averaged over depths at all five stations for both years
388 (Table 3). Some discrepancies were observed such as at the 20 cm depth in Beaver Divide
389 and Soapstone, which showed relatively low R^2 of 0.651 and high RMSE of $0.05 \text{ m}^3 \text{ m}^{-3}$
390 and $0.04 \text{ m}^3 \text{ m}^{-3}$, respectively. The source of discrepancies between measured and

391 simulated soil moisture is likely due to the limited information available to the HYDRUS-
392 1D model to account for the complexity caused by soil heterogeneity, stone content or
393 preferential flow, which is quite common in forest soil (Flinn and Marks, 2007; Hawley et
394 al., 1983). Although the soil texture and stone content varied considerably within the
395 examined soil profiles, the simulation domains (2m deep) were clustered into five distinct
396 layers based on textural information obtained from the soil pit description. This
397 simplification of soil representation is a likely source of increased simulation error for soil
398 moisture.

399 **5.2 Simulation of Actual Evapotranspiration**

400 The HYDRUS-1D simulation for 2015 and 2016 suggested that the ET_A was strongly
401 correlated to the soil moisture availability during the growing season as 2016 showed lower
402 cumulative ET_A corresponding to the drier soil profile (Figure 4; 5; 8). The ET_A measured
403 by the eddy covariance system at the Low Sage station and simulated by HYDRUS-1D
404 followed the same trend (Figure 6). However, the model overestimated the peak values
405 noticeably, usually after the rain events in 2015. Despite the difference between spatial
406 scales of the eddy covariance footprint and the point scale simulation of HYDRUS-1D, the
407 results validate the potential of quantifying ET_A using soil moisture dynamics in natural
408 settings.

409 Slight differences between modeled daily ET_A and values measured by eddy covariance
410 were expected. The eddy covariance method does not always provide energy balance
411 closure consistently, which may lead to underestimation of latent heat flux or ET_A (Wilson
412 et al., 2002). When comparing the sum of latent heat flux and sensible heat with available
413 energy ($R_n - G$), Wilson et al. (2002) reported an average error of 20% from 22 FLUXNET

414 (an eddy covariance network) sites. Although the energy budget ratio at the Low Sage site
415 over the two years during snow-free, non-freezing periods was 0.96, weekly values over
416 the simulation period in Figure 6 were as low as 0.80. Moreover, error in HYDRUS-1D
417 simulation may result from inaccuracy of model parameterization of soil hydraulics. Soils
418 in natural settings are highly heterogeneous within the profile with extremely variable
419 hydraulic properties. Limitations in the information representing soil and vegetation
420 complexity might have resulted in incorrect estimations of water balance leading to
421 erroneous ET_A estimates in some cases.

422

423 **5.3 Accounting for Stone Content**

424 The magnitude of the effects of stone content on the ET_A simulation was dependent upon
425 the types of stone and their hydraulic properties. As presented in Durner (1994), prediction
426 of both the water retention and hydraulic conductivity function near saturation may be
427 highly unreliable and subject to large estimation error with even the best quality
428 measurements. Acknowledging this, we assumed the saturated hydraulic conductivity of
429 the stony soil was similar to that of the fine soil matrix while the unsaturated hydraulic
430 conductivity for stony soil was defined by Eq. (14) as a function of effective saturation.
431 Several studies suggest reduction in hydraulic conductivity due to increase in stone content,
432 while conversely, the hydraulic conductivity has also been shown to increase in stony soil
433 near saturation (Beckers et al., 2016; Sauer and Logsdon, 2002). Our simulation for low
434 porosity stone tended to simulate ET_A that matched well with the eddy covariance estimates
435 (Figure 6). Simulation of stony soil with negligibly porous stone reduced the total
436 cumulative ET_A considerably at all five stations for both years except for Knowlton Fork,

437 which exhibited the lowest average stone content (Figure 2). However, the high porosity
438 stone, with water retention behavior similar to coarse sandstone, had the least effect on
439 ET_A simulation in comparison to the ET_A estimated without accounting for the stone
440 content. The cumulative ET_A over the simulation period was reduced by up to 30% for the
441 Soapstone site in 2016 when assuming negligibly porous stones (Table 5). This correlates
442 well with results in Cousin et al. (2003) that showed overestimation of available water
443 content by 39% when the presence of stones were not accounted for in soil.

444 **6. Conclusion**

445 In this study we demonstrated the influence of soil stone content on the uptake of water as
446 evapotranspiration (ET) from a mixture of grass and sagebrush using stony-soil moisture
447 dynamics. The soil moisture and ET_A simulated by HYDRUS-1D were found to be in good
448 agreement with directly measured soil moisture and ET_A using the eddy covariance system
449 indicating that the model is efficient in simulating the boundary fluxes including ET_A . The
450 simulated root water uptake from stony soil was found to be sensitive to stone content.
451 Simulation results revealed a significant reduction in cumulative ET_A of up to 30% percent
452 of total ET_A computed without accounting for the stone content. The simulated ET_A values
453 were least affected when considering soil with highly porous stones, while estimates were
454 reduced significantly for the stations with higher average stone content, when considering
455 soil with negligibly porous stones. Numerical simulations revealed that lower- and higher-
456 porosity stones reduced ET_A by 30% and 10%, respectively, highlighting the potential for
457 overestimation of ET_A when stone content is neglected in modeling. It is hence important
458 to incorporate hydraulic properties of stones to more accurately estimate ET_A by
459 accounting for stone impact on soil moisture dynamics in stony soil. This study provides

460 guidelines and tools for numerical simulation of soil moisture dynamics for improved
461 estimation of ET_A from stony soils such as are commonly found in montane forest
462 ecosystems.

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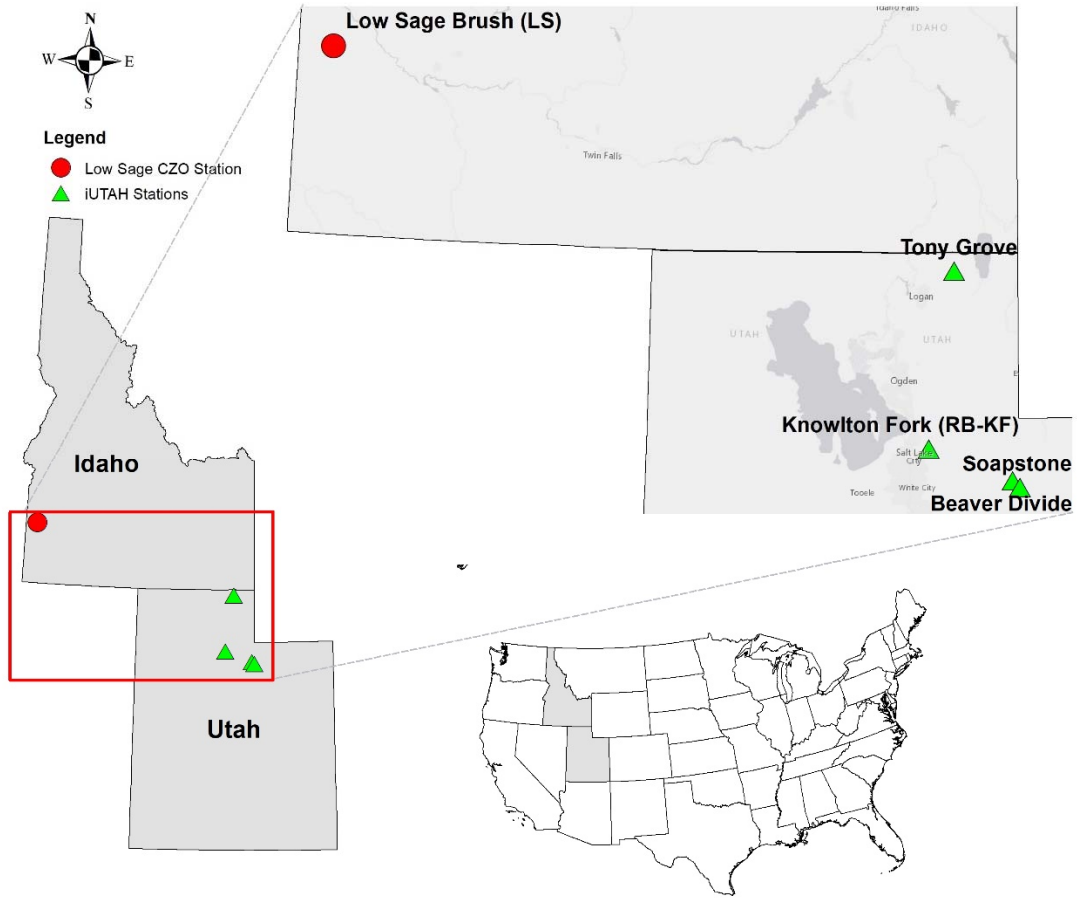
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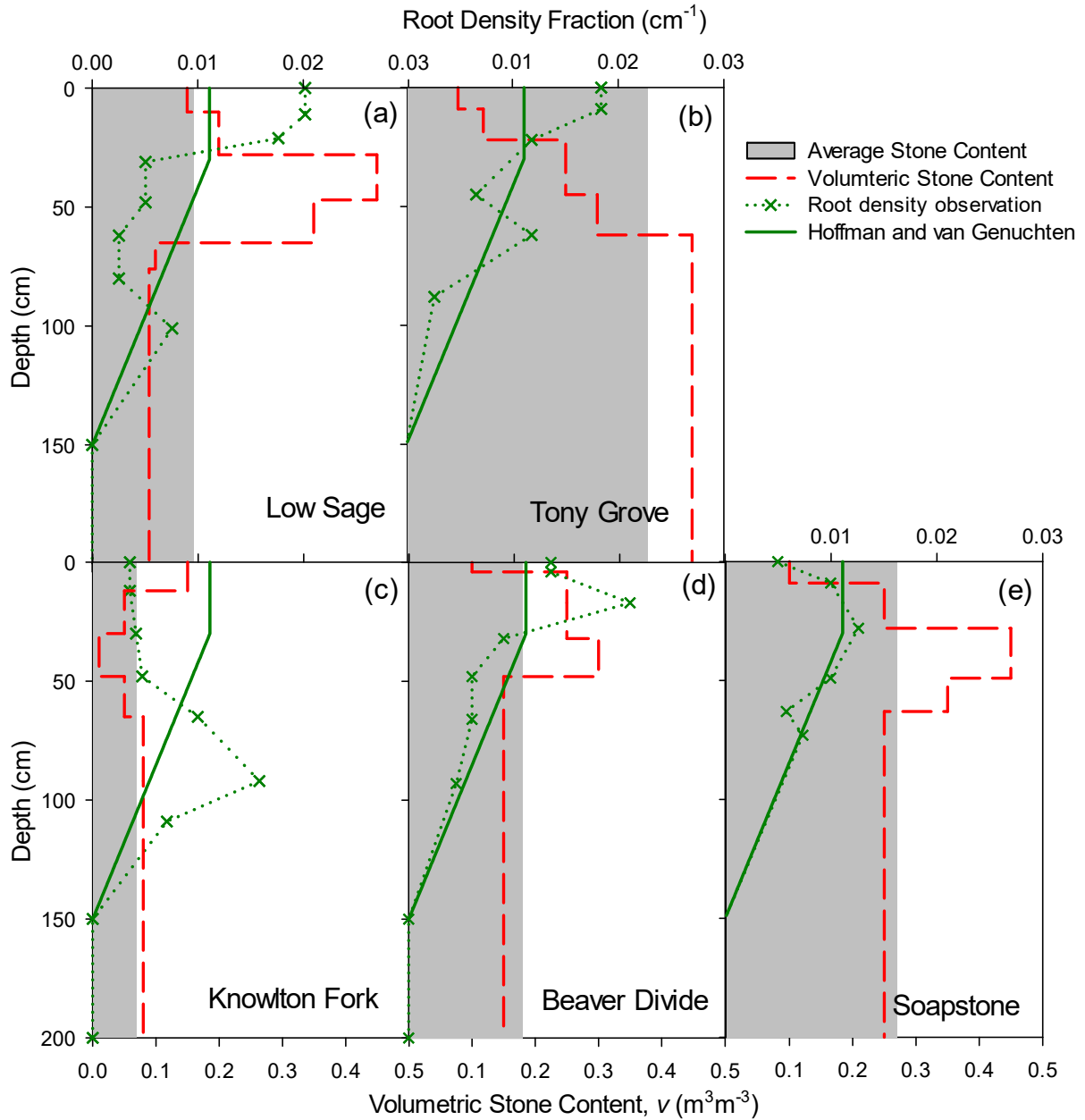
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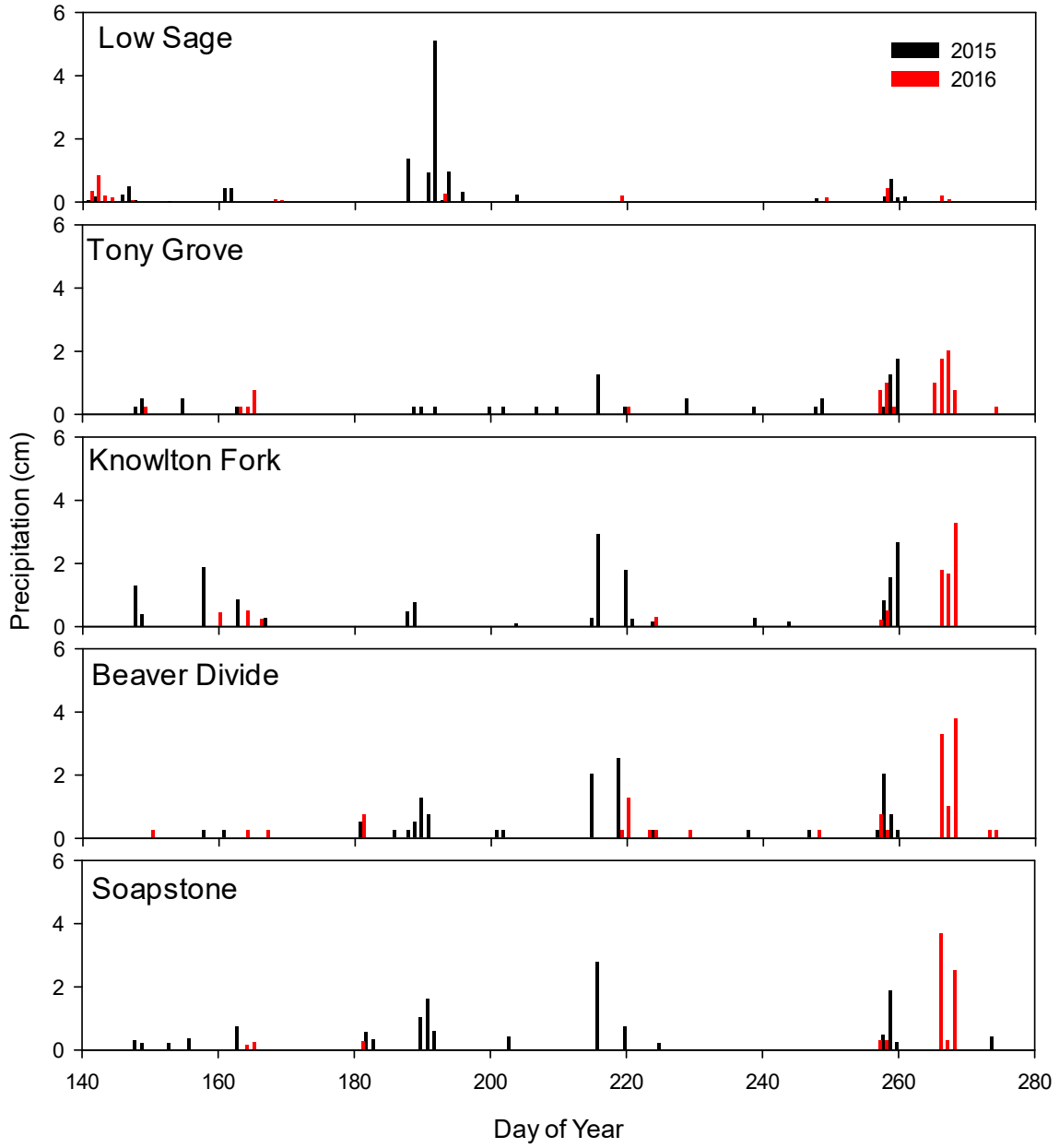


678

679 Figure 1. Selected climate stations in Northern Utah and Reynolds Creek, Idaho installed
 680 by iUTAH and the Critical Zone Observatory (CZO) respectively. All stations have
 681 measurements of meteorological parameters including volumetric soil water content. The
 682 Low Sage station is furthermore equipped with an eddy covariance tower.

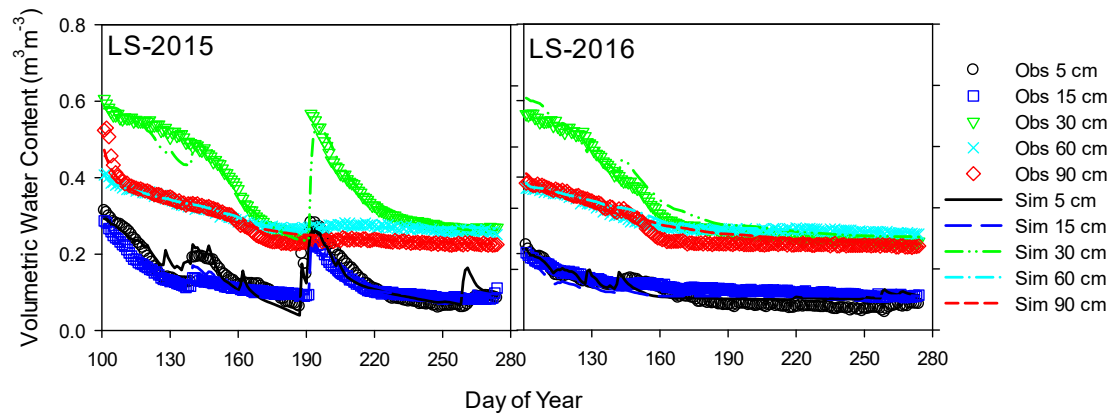


685 Figure 2. Root density distribution and volumetric stone content along the soil profile at
 686 (a) Low Sage, (b) Tony Grove, (c) Knowlton Fork, (d) Beaver Divide and (e) Soapstone
 687 weather stations. The root density distribution was estimated based on root counts from
 688 soil pit description and compared with Hoffman and van Genuchten (1983) method. The
 689 stone content were obtained from the soil pit description during the installation of climate
 690 stations. Information on stone content was available to the depth of around 100 cm.
 691 Below that depth the stone content is considered similar to the stone content in the bottom
 692 most layer from the soil pit description. The average stone content is taken from stone
 693 distribution in the entire 200 cm soil profile.



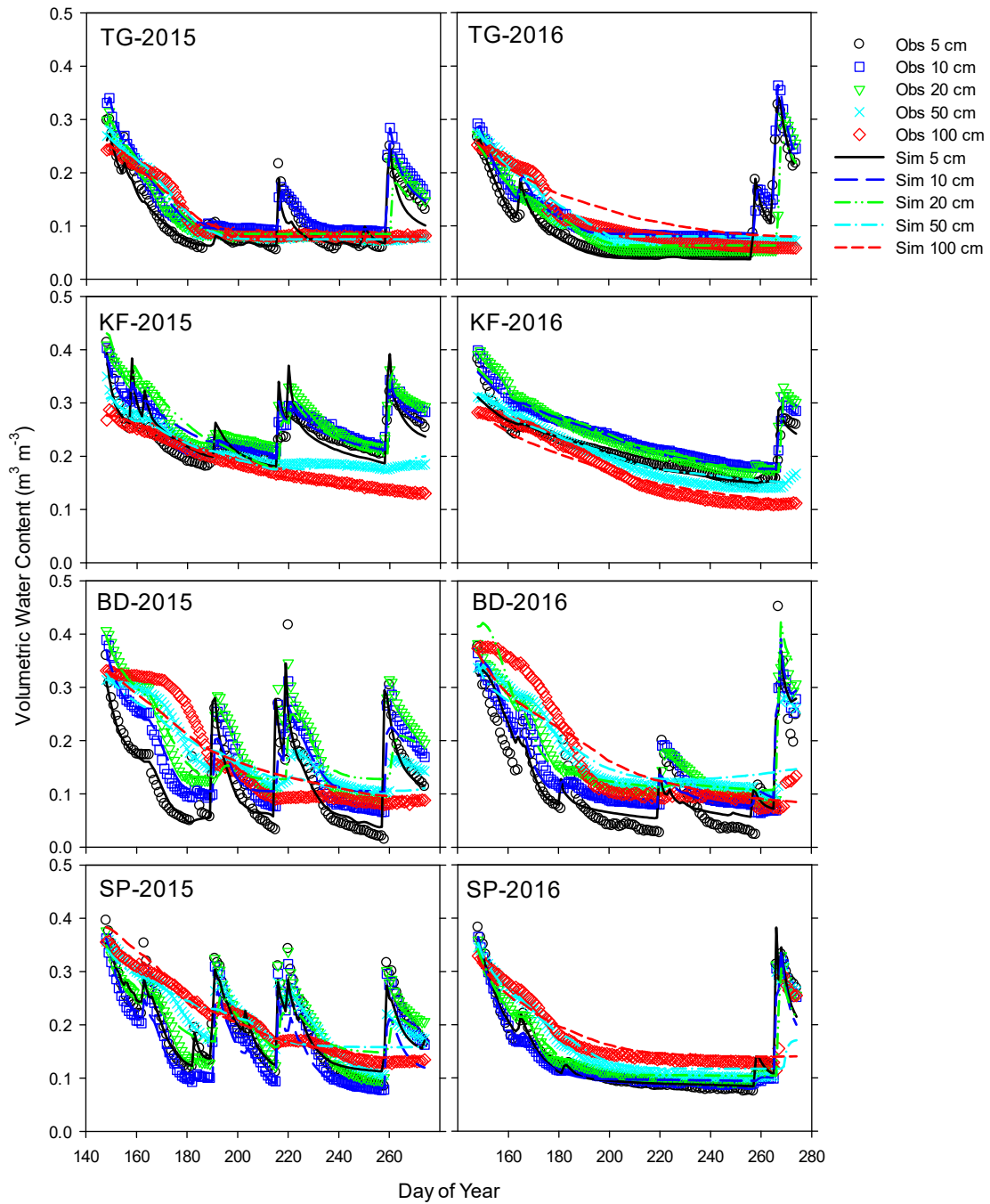
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695 Figure 3. Daily precipitation during the HYDRUS-1D simulation period in the selected
 696 sites for 2015 and 2016.



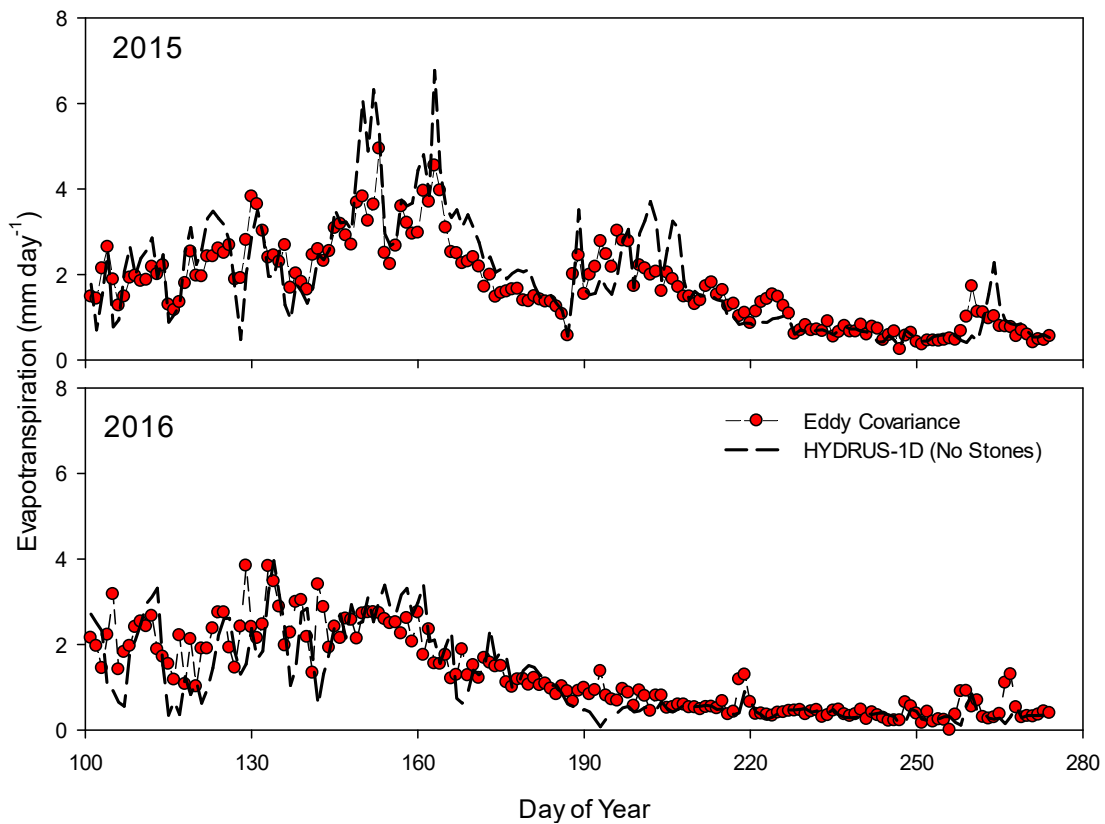
698

699 Figure 4. Volumetric water content reported by Hydraprobe sensors (points) at different
 700 depths and as simulated by HYDRUS-1D (lines) after calibration for the growing seasons
 701 of 2015 and 2016 at the low sage station. The simulation period was between DOY 100
 702 (10 April) and DOY 273 (30 September).



703

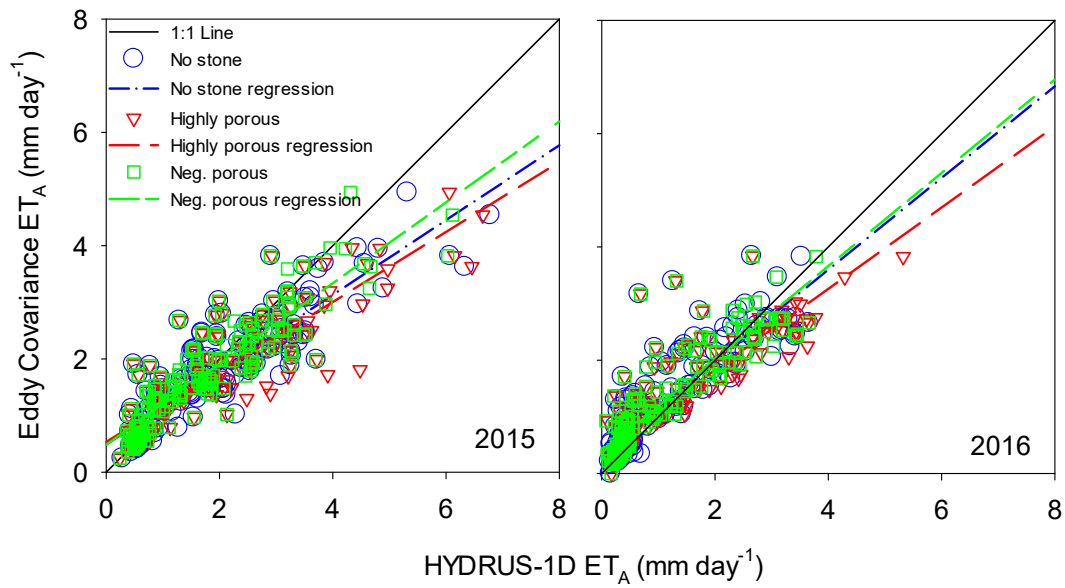
704 Figure 5. Volumetric water content reported by TDT sensor (points) at different depths
 705 and as simulated by HYDRUS-1D (lines) after calibration for the growing season of 2015
 706 and 2016 at Tony Grove (TG), Knowlton Fork (KF), Beaver Divide (BD) and Soapstone
 707 (SP). The simulation period was between DOY 147 (27 May) and DOY 273 (30
 708 September).



709
 710 Figure 6. Actual evapotranspiration measurements from the eddy covariance system
 711 compared with actual evapotranspiration simulated using HYDRUS-1D without
 712 accounting for stone content at the Low Sage station in Reynolds Creek Experimental
 713 Watershed for the year 2015 and 2016.

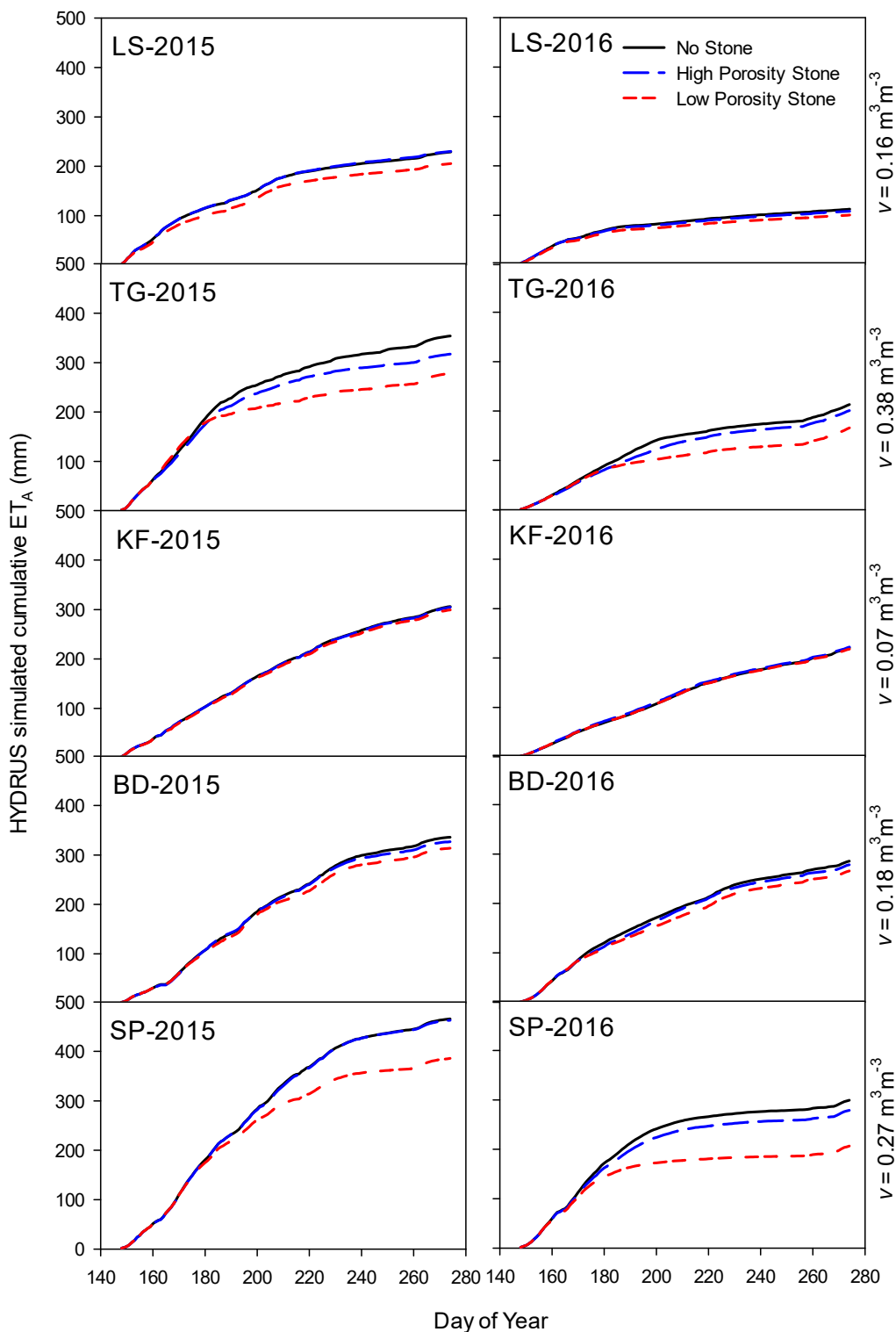
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717 Figure 7. Scatter plot between the evapotranspiration measured by the Eddy Covariance
 718 tower at the low sage station and the HYDRUS-1D simulations of actual
 719 evapotranspiration assuming no stones, highly porous and negligibly porous stones along
 720 with their regression line for 2015 and 2016.



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Figure 8. Cumulative evapotranspiration simulated by HYDRUS-1D under three different scenarios considering soil with -no stone, -highly porous stone and -negligibly porous stone at the Low Sage (LS), Tony Grove (TG), Knowlton Fork (KF), Beaver Divide (BD) and Soapstone (SP) stations for 2015 and 2016. The ET is cumulative from DOY 148 (28 May) to DOY 273 (30 September). The stone content along the soil profile is presented in Figure 2. Average stone content (v) for each site is presented on the right side of each plot.

729 Table 1. Location and description of weather stations with major vegetation types and
730 maximum LAI used in this study. The maximum LAI value for Low Sage weather station
731 was taken from Finzel et al. (2012) while at the iUTAH stations LAI was determined
732 from measurements of a Line Quantum Meter (MQ-301, Apogee).
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Station	Latitude	Longitude	Elevation (m)	Vegetation	LAI _{Max}
Low Sage (LS)	43.14	-116.74	1608	Sagebrush	2.30
Tony Grove (TG)	41.89	-111.57	1928	Sagebrush, Grass	2.20
Knowlton Fork (KF)	40.81	-111.77	2178	Grass, Fern	4.50
Beaver Divide (BD)	40.61	-111.10	2508	Sagebrush, Grass	1.20
Soapstone (SP)	40.57	-111.04	2388	Sagebrush, Grass	2.30

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736 Table 2. Measured water retention parameters: saturated water content (θ_s), residual water
737 content (θ_r), shape parameters α and n for the stone fragments obtained from Parajuli et
738 al., (2017).
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Parameters	Highly Porous Stone (Coarse Sandstone)	Negligibly Porous Stones (Fine Sandstone)
θ_s [$\text{m}^3 \text{m}^{-3}$]	0.28	0.036
θ_r [$\text{m}^3 \text{m}^{-3}$]	0.012	0
α [m^{-1}]	0.032	0.084
n	2.115	1.219

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741 Table 3. Goodness of fit for measured soil moisture content with the HYDRUS-1D simulation, expressed in terms of the coefficients of
 742 determination (R^2) and root mean squared errors (RMSE)
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Year	Sensor Depth	Low Sage		Sensor Depth	Tony Grove		Knowlton Fork		Beaver Divide		Soapstone	
		R^2	RMSE ($\text{m}^3 \text{m}^{-3}$)		R^2	RMSE ($\text{m}^3 \text{m}^{-3}$)	R^2	RMSE ($\text{m}^3 \text{m}^{-3}$)	R^2	RMSE ($\text{m}^3 \text{m}^{-3}$)	R^2	RMSE ($\text{m}^3 \text{m}^{-3}$)
2015	5 cm	0.853	0.025	5 cm	0.927	0.021	0.667	0.028	0.671	0.047	0.927	0.025
	15 cm	0.931	0.013	10 cm	0.951	0.014	0.853	0.017	0.889	0.032	0.873	0.035
	30 cm	0.957	0.028	20 cm	0.903	0.019	0.839	0.025	0.651	0.052	0.651	0.042
	60 cm	0.975	0.006	50 cm	0.989	0.006	0.962	0.008	0.866	0.026	0.638	0.039
	90 cm	0.967	0.019	100 cm	0.976	0.009	0.994	0.005	0.936	0.033	0.976	0.014
	Average	0.937	0.018		0.949	0.014	0.863	0.017	0.803	0.038	0.813	0.031
2016	5 cm	0.817	0.016	5 cm	0.989	0.011	0.893	0.017	0.771	0.044	0.966	0.015
	15 cm	0.837	0.022	10 cm	0.990	0.007	0.974	0.010	0.875	0.030	0.978	0.012
	30 cm	0.984	0.026	20 cm	0.989	0.014	0.942	0.016	0.919	0.029	0.913	0.022
	60 cm	0.957	0.012	50 cm	0.985	0.012	0.986	0.012	0.807	0.036	0.705	0.041
	90 cm	0.935	0.022	100 cm	0.947	0.027	0.980	0.015	0.904	0.040	0.707	0.034
	Average	0.906	0.020		0.980	0.014	0.955	0.014	0.855	0.036	0.854	0.024

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749 Table 4. Goodness of fit for evapotranspiration measured by eddy covariance with HYDRUS-
 750 1D simulation considering soil with: (1) no stones, (2) highly porous stones, and (3) negligibly
 751 porous stones, expressed in terms of coefficients of determination (R^2) and root mean squared
 752 errors (RMSE)
 753

	2015		2016	
	R^2	RMSE (mm/day)	R^2	RMSE (mm/day)
No Stone	0.78	0.64	0.76	0.51
Highly Porous Stone	0.76	0.73	0.78	0.54
Negligibly Porous Stone	0.79	0.55	0.79	0.49

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755 Table 5. HYDRUS-1D simulated actual-Transpiration (T_A), -Evaporation (E_A) and -Evapotranspiration (ET_A) reported as mm of water
 756 loss at different sites in years 2015 and 2016 under three different scenarios considering soil with no stones, highly porous stones and
 757 negligibly porous stones. The numbers on right hand side are percent change while considering the highly- and negligibly-porous stones
 758 as compared to no stone condition.
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Year	Scenario	Component	Low Sage		Tony Grove		Knowlton Fork		Beaver Divide		Soapstone	
			(mm)	Change (%)	(mm)	Change (%)	(mm)	Change (%)	(mm)	Change (%)	(mm)	Change (%)
2015	No Stone	T_A	134		262		228		267		384	
		E_A	95		92		78		69		81	
		ET_A	229		354		306		336		466	
	Highly Porous Stone	T_A	130	-3.06	258	-1.61	226	-0.84	265	-0.54	384	-0.22
		E_A	101	5.97	59	-35.27	79	0.84	62	-11.14	80	-2.36
		ET_A	231	0.70	317	-10.35	305	-0.41	327	-2.72	463	-0.60
	Negligibly Porous Stone	T_A	124	-6.97	180	-31.46	228	-0.12	247	-7.40	307	-20.22
		E_A	81	-14.57	99	7.25	72	-8.02	67	-3.62	79	-2.85
		ET_A	206	-10.13	278	-21.41	299	-2.14	314	-6.62	386	-17.19
2016	No Stone	T_A	103		156		165		172		245	
		E_A	9		57		56		114		54	
		ET_A	112		213		221		286		299	
	Highly Porous Stone	T_A	99	-4.56	148	-5.07	163	-1.44	196	14.02	226	-7.64
		E_A	10	10.17	54	-6.41	60	7.48	83	-27.56	52	-3.30
		ET_A	109	-3.38	202	-5.43	222	0.81	278	-2.58	279	-6.85
	Negligibly Porous Stone	T_A	92	-11.31	111	-28.76	165	-0.16	180	5.07	160	-34.74
		E_A	9	-0.52	55	-3.80	54	-3.45	86	-25.00	47	-13.80
		ET_A	101	-10.44	166	-22.05	218	-0.99	266	-6.94	207	-30.95