Building an Affordable Helmholtz Magnetic Simulator for CubeSat Satellites

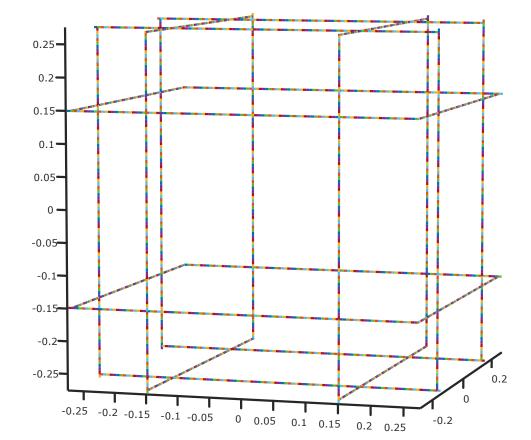
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Analysis

Numerical analysis of square Helmholtz coils

The task of numerical analysis was to obtain magnetic flux density vectors for a system of square Helmholtz coils Coils dimensions: 20 turns, side length a=0.54 m, spacing b=0.30 m (ratio between a and b is 0.55) Each coil represented with 400 current elements, Biot-Savart law used to determine field strength of each element Magnetic flux density was evaluated in 3-D polar coordinates by principle of superposition of all coils and elements Resulting magnetic flux density in the center of the coil pairs is 300 μ T at 100 A (\sim 10 % lower than with circular coils)

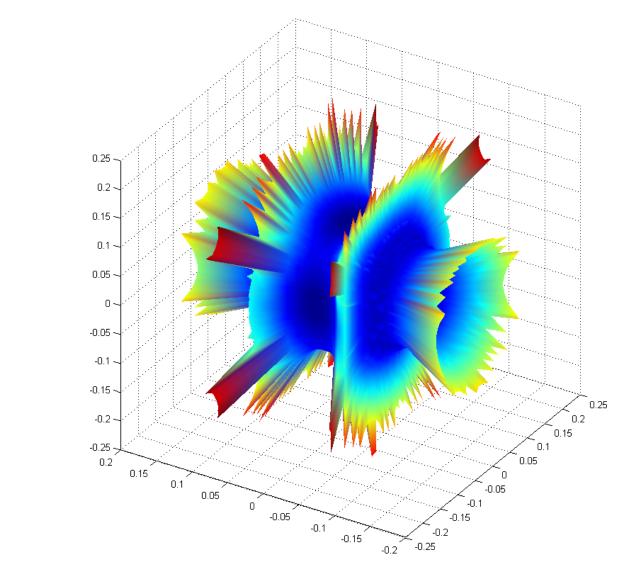


3-D representation of current elements (in total of 2400)

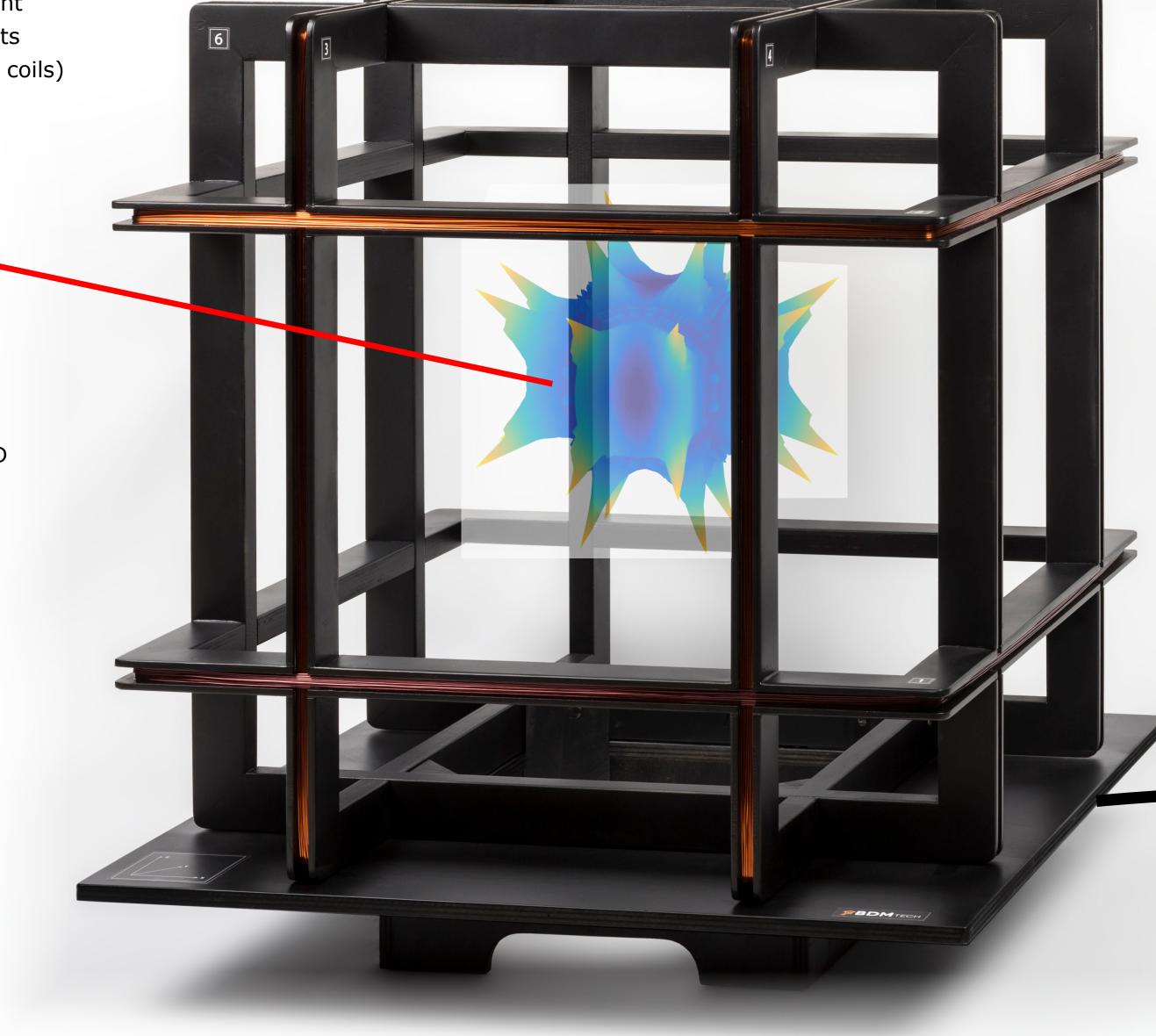
Homogenous field volume approx. 10 cm x 10 cm x 10 cm x 10 cm

Homogeneous volume boundaries visualization

Boundary of the 1 % homogeneity region was searched for in 3-D Arbitrary shaped homogeneous volume was determined Volume boundary parameterized in polar coordinates



Homogeneity border (1 %) in one axis



Outer cage dimensions 60 cm x 60 cm x 65 cm

Clean back of the unit

Construction

Lightweight wooden coils cage

The cage is made of wood parts, then painted in matte black Professional, clean look of the device

Coils wound using 1 mm copper wire

The coils are wound to achive \pm /- 200 μ T of magnetic flux density

Heavy-duty connector

Hassle-free connection between the driver and the coils
Allows the cage to be easily disconnected and moved or stored

Driver case suitable for use in 19" rack

Custom driver design

User-driven design (compact unit, easy to setup and use)
Microcontroller based driver, allowing digital closed-loop control
Multiple options of amplifier design evaluated,
MOSFET class AB closed-loop voltage-current amplifier implemented

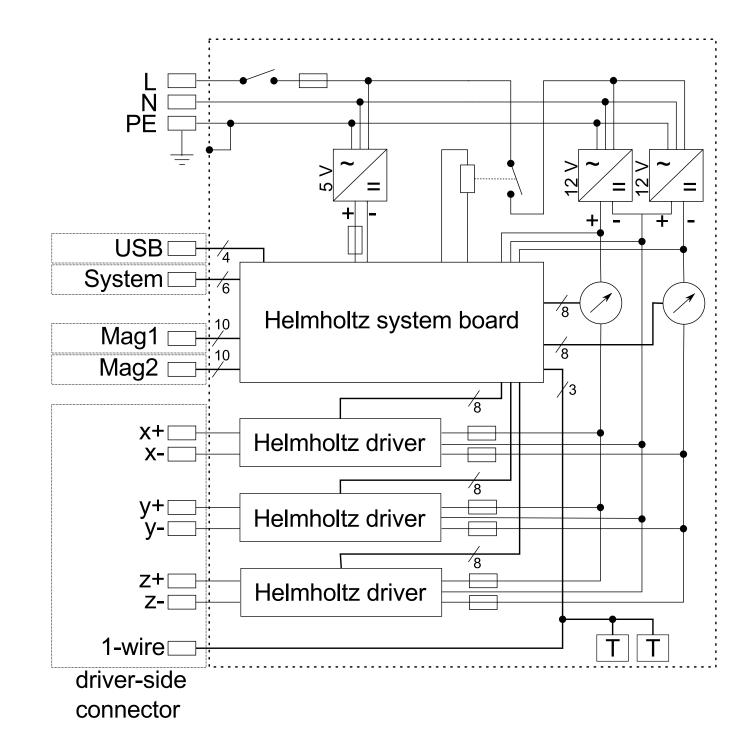
Integrated temperature sensors

Digital temperature sensors integrated into the cage frame to directly observe coil temperatures

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Device testing in the laboratory



Driver architecture

Interface

Big alphanumeric LCD on front panel of the driver with an encoder knob

Display of coil currents, magnetic flux densities (references and measurements)

Display of coil and driver temperatures

Encoder used to move between different menus, change parameters

Coil currents or reference magnetic flux densities can be altered manually

Easily-accessible on/off switch on the front

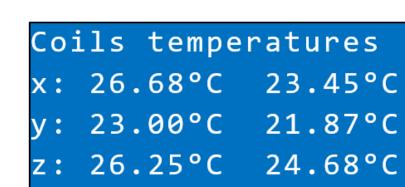
Built-in galvanically isolated USB connection or Ethernet

Cross-platform library for use in Windows, linux (including embedded systems)
Interface example for C and Matlab (Simulink S-function)

Remote access for monitoring and control

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Control

Optional reference FLC3-70 fluxgate magnetometers

Integrated 3-channel digital controller with closed-loop control

Unique controller freeze mode that allows the removal of the reference probe Dynamic control of magnetic field

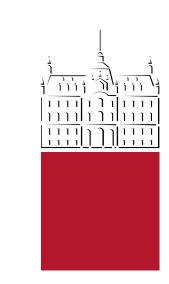
Built-in separate coil temperature sensors for failsafe operation







Developed for SPACE-SI in cooperation with BDM-Tech





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