

Development of an Operating Strategy for On-Demand Earth Observation Missions of the Diwata-2 Microsatellite



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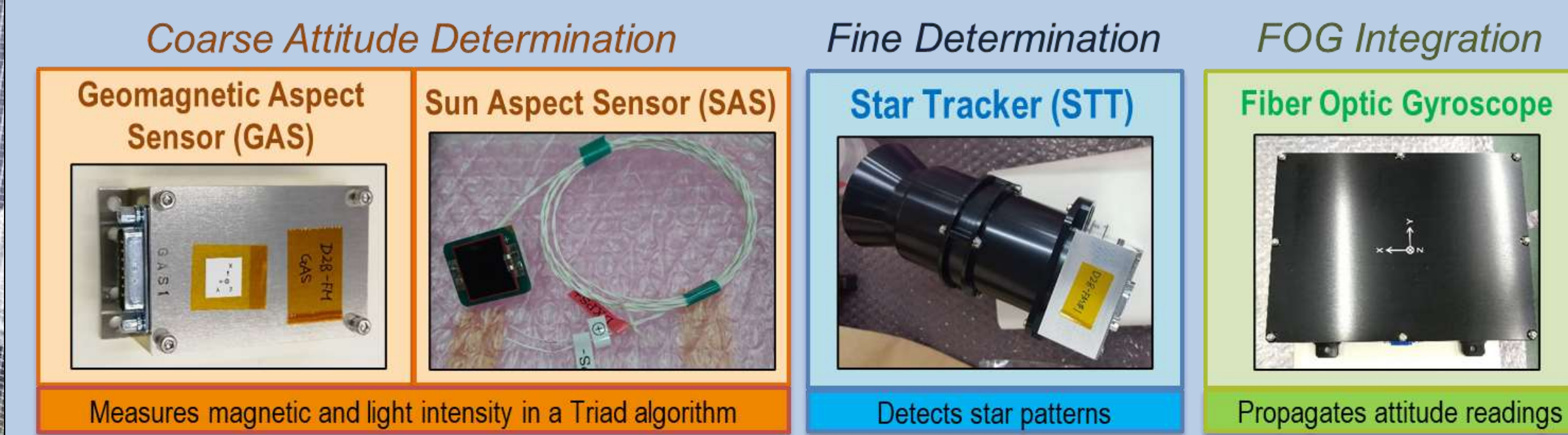
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I. The Diwata-2 Microsatellite



- The 2nd Philippine-made satellite in collaboration with Tohoku University and Hokkaido University in Japan.
- Primary mission: Gather remote sensing data for post-disaster assessment, environmental studies, and resource management.
- For on-demand operation, Diwata-2 uses its attitude components capable of off-nadir observations by its optical payloads.

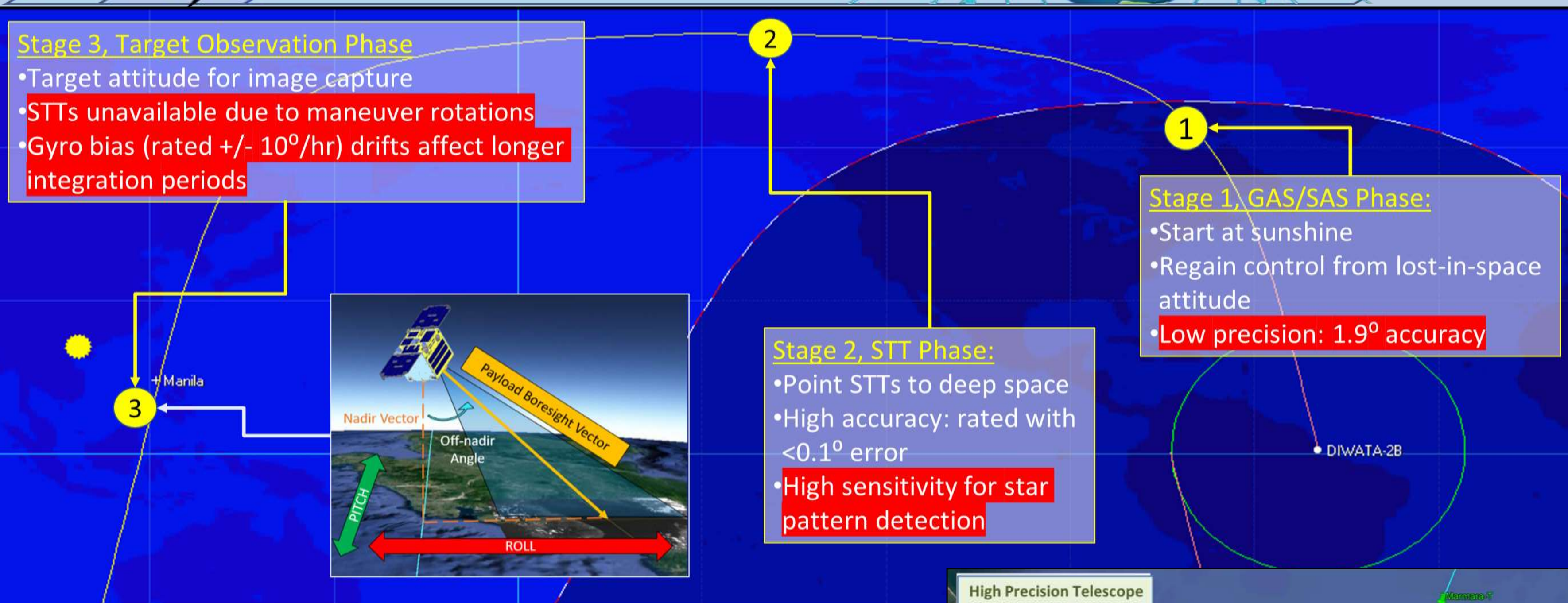
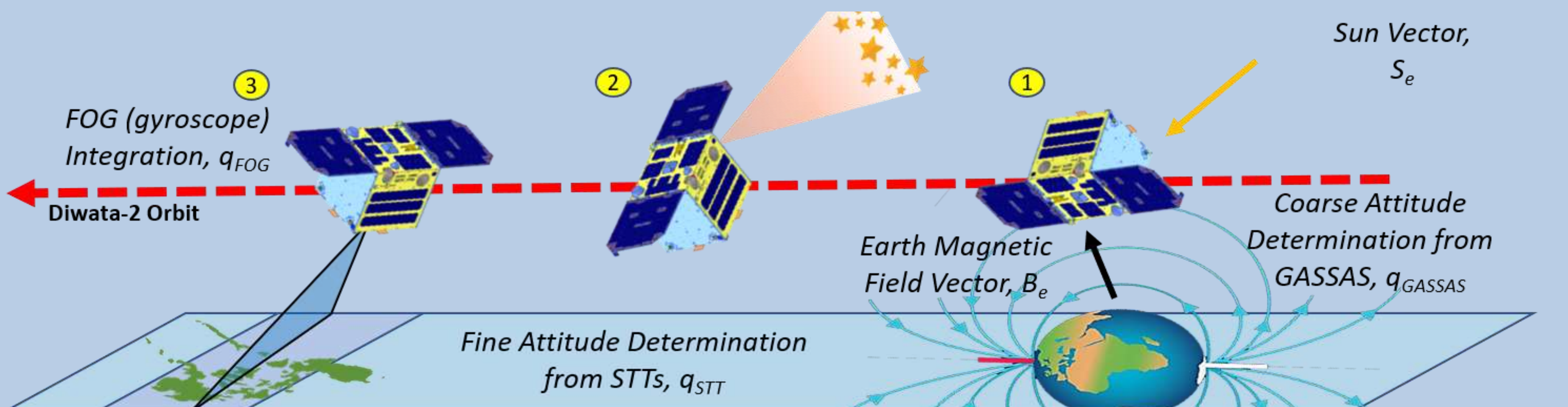


GOAL: It is aimed to achieve a 0.1° target pointing accuracy of on-demand Earth observation operation by Diwata-2.

Diwata-2 Operating Strategy

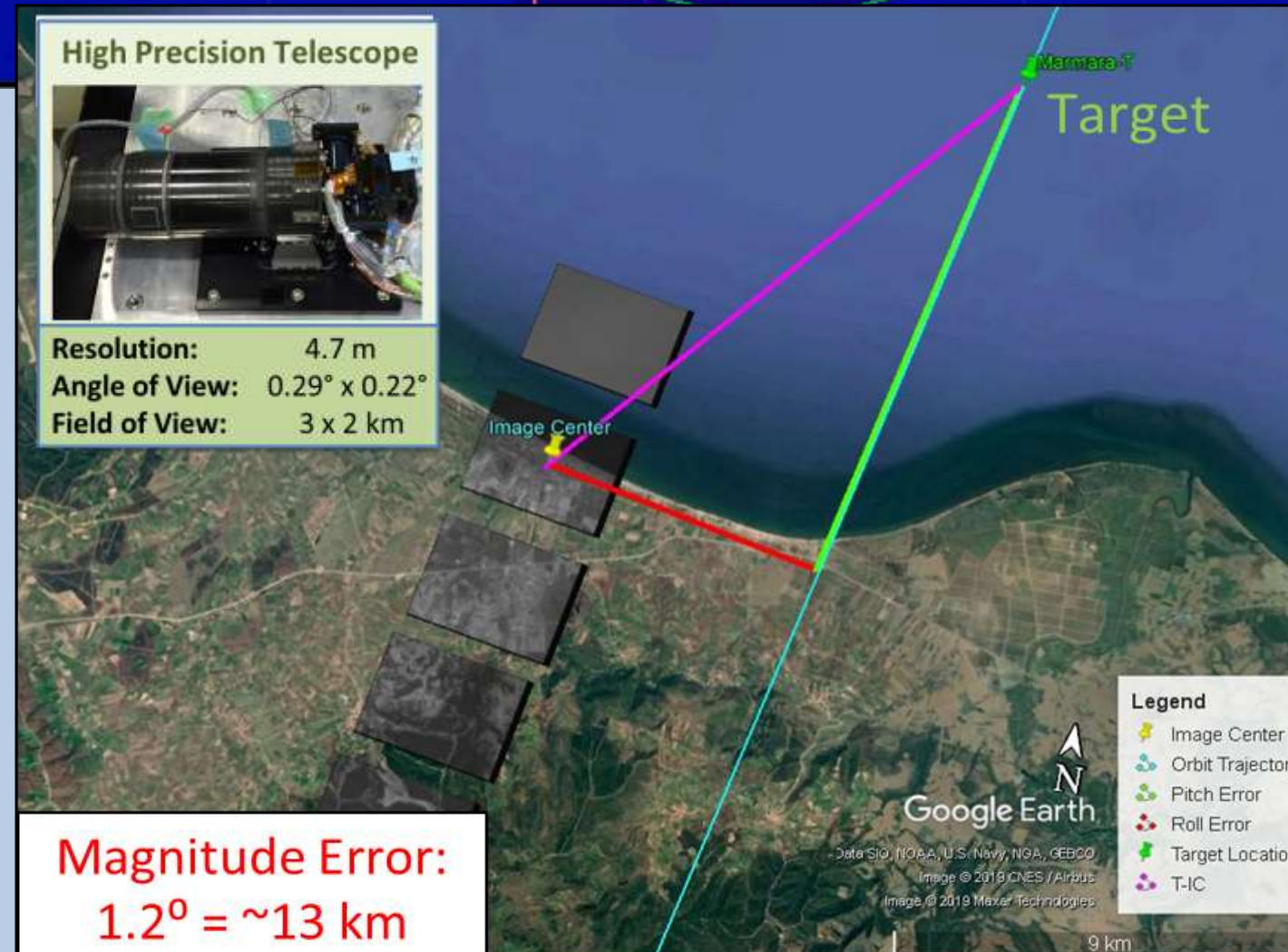
- Pointing Performance Analysis
- Star Tracker Sensor Calibration
- Target Pointing Calibration
- Scheduling of Components

II. Earth Observation Mission Sequence



Initial Pointing Performance

- Earth observation trials were carried out using the High Precision Telescope (HPT) payload.
- Both nadir and off-nadir observation modes were tested.
- The recorded initial trials resulted into an average and standard deviation of $2.88^\circ \pm 2.06^\circ$ RMS.
- The initial trial results may be acceptable for payloads with a large FOV, but does not satisfy the $< 0.1^\circ$ pointing requirement.



III. Star Tracker Sensor Calibration

- The initial STT images were analyzed using simulation ground software.
- An **invalid star pattern detection** caused failure in the Fine Attitude Determination.
- Initial poor precision may be caused by the lengthy propagation of the coarse GAS/SAS readings over an extended integration period.
- Possible causes and countermeasures are suggested:

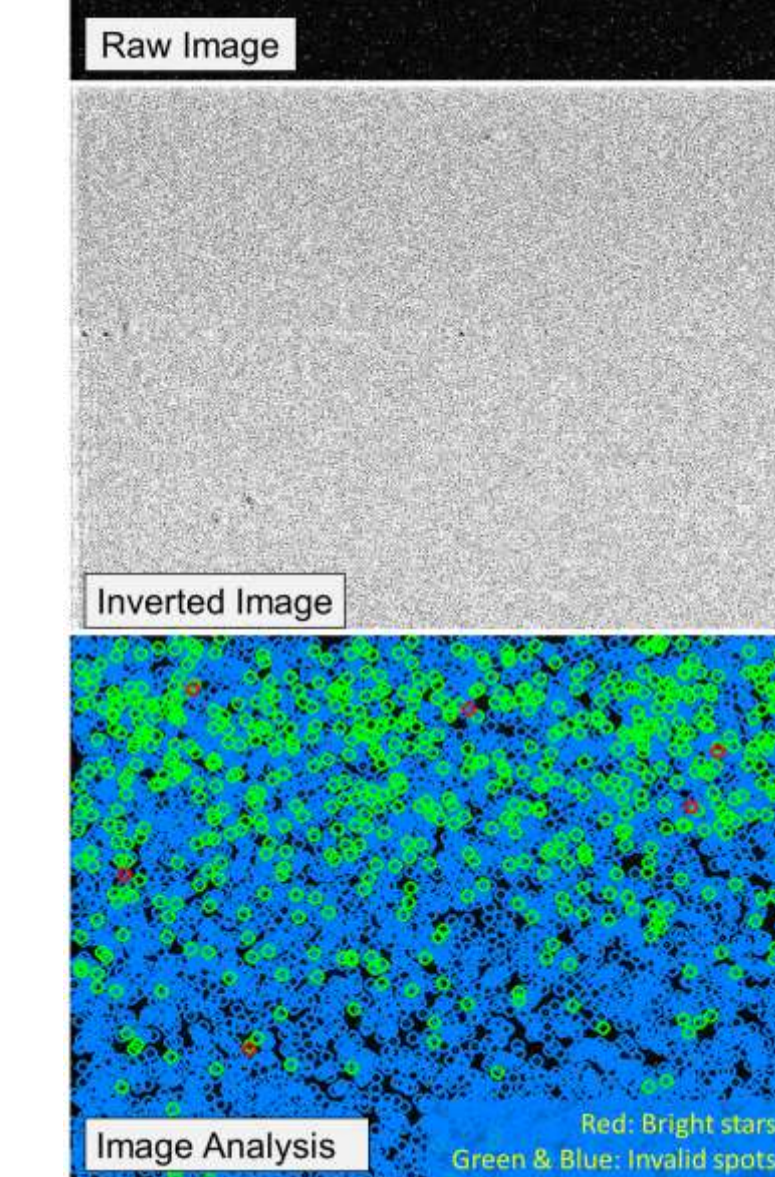


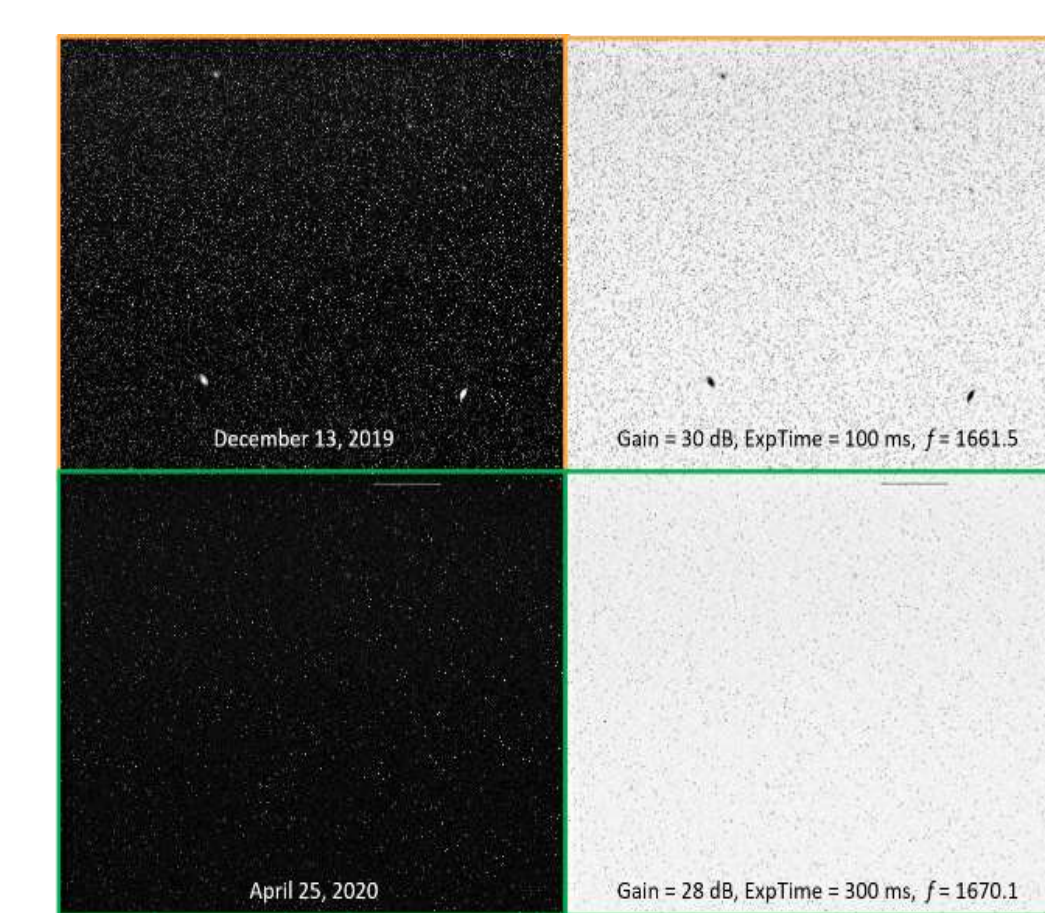
Image Noise – White spots, caused by radiation environment, may mask stars captured. The STT's sensor parameter settings may minimize this effect.

Light Interference – Stray light overexpose the star images. Satellite attitude should account for the sun, earth, and moon incident angles.

Insufficient Bright Stars – A certain number of bright stars are required. For practical purposes, STT detection duration would be extended.

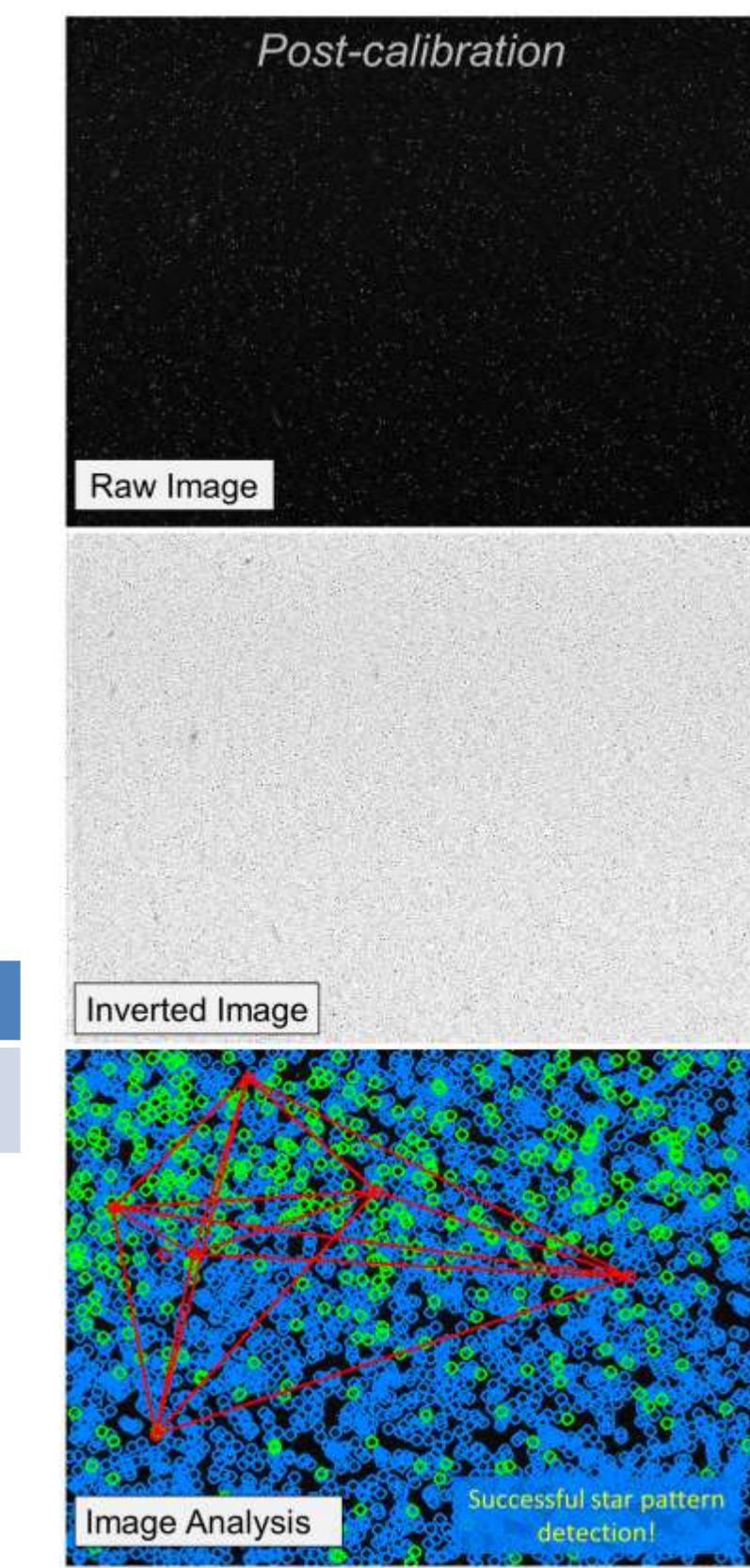
Functional Condition	Req't
Angular Velocity	$< 0.3^\circ/s$
Sun Incident Angle	$> 80^\circ$
Moon Incident Angle	$> 50^\circ$
Earth Incident Angle	$> 120^\circ$
Number of Stars	> 12

In-flight tuning experiments of the sensor parameter settings, duration, and attitude are performed to find the right mix for a successful star pattern detection by the STTs.



STT Parameter Settings to adjust image quality

- Gain** – Controls apparent light sensitivity; but also amplifies image noise.
- Exposure Time** – Controls the amount of light detected; but more vulnerable to movement distortion.
- Focal Length, f** – Adjusts the transformation of the image frame into the local frame by onboard software.

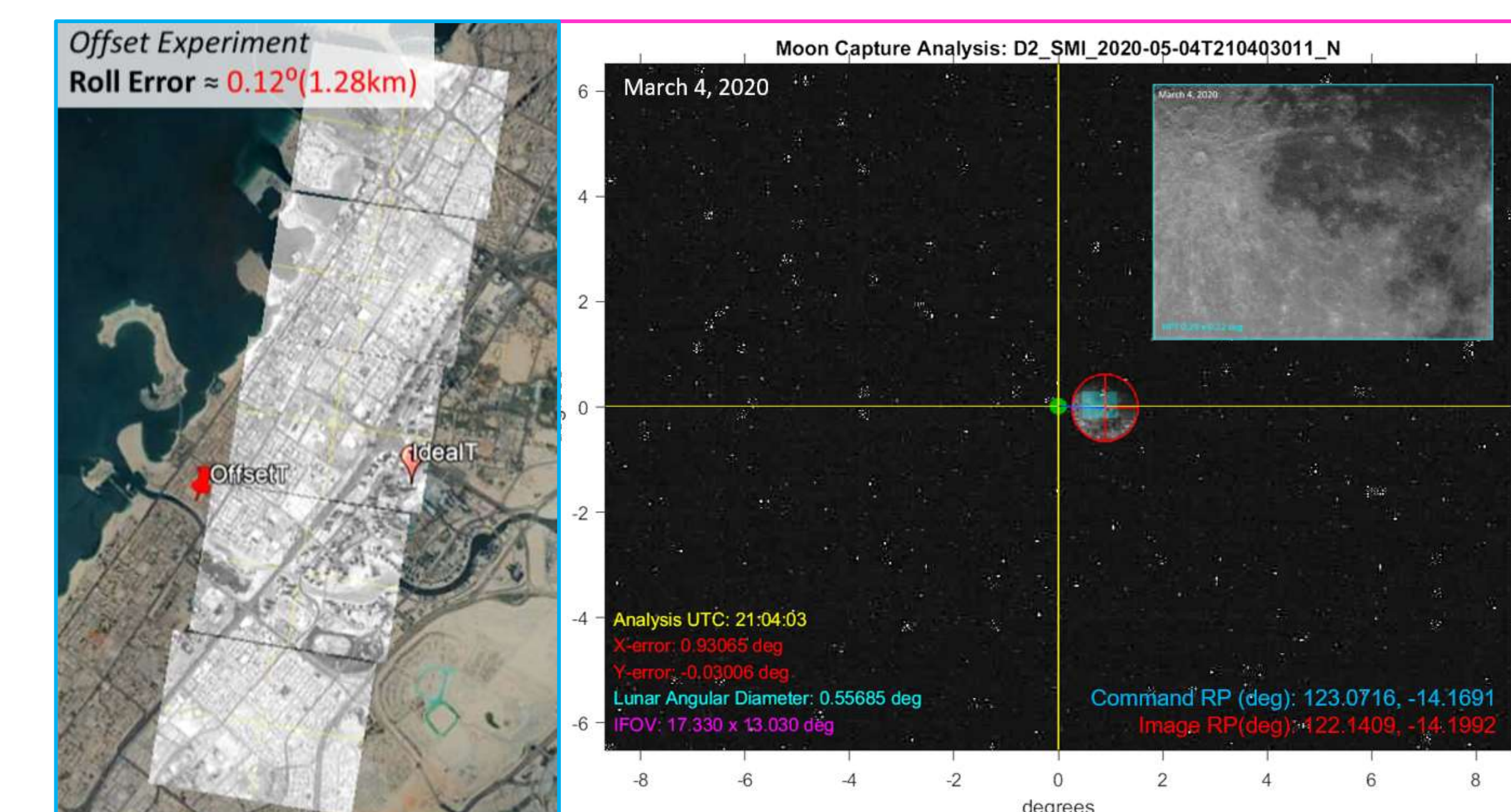


Duration	Attitude	STT Parameter Settings
> 15 minutes	$\varphi=30^\circ, \theta=0^\circ, \psi=180^\circ$	Exp. Time = 400ms, Gain= 28dB, f= 1670.1

- Shown above are the working set of conditions for STT operation
- Post-STT Calibration observation resulted in an accuracy of $1.79^\circ \pm 0.59^\circ$ RMS.
- Success of Fine Attitude Determination improved precision significantly.

IV. Target Pointing Calibration(1)

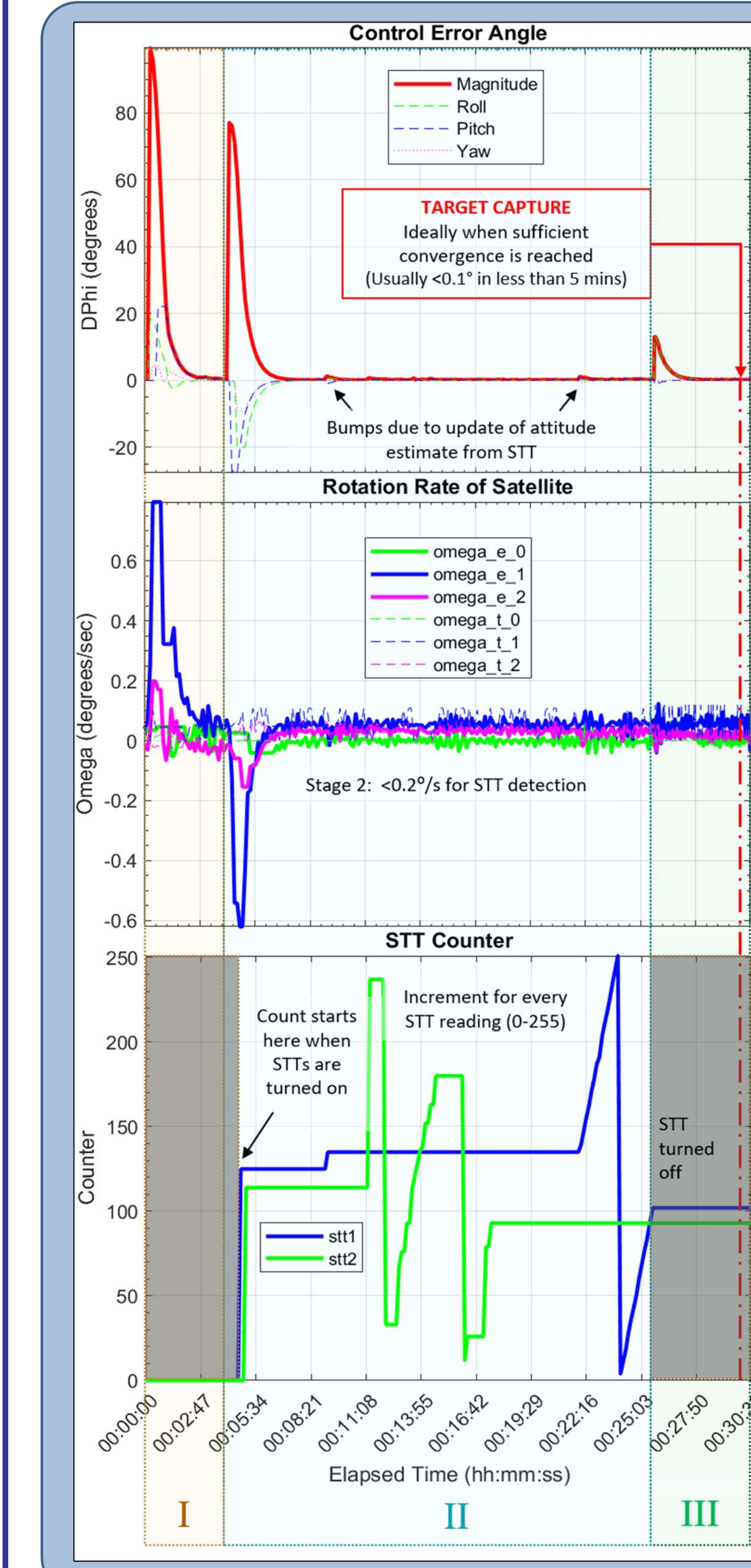
- The Target Pointing Calibration study presents further work on persisting systematic issues:
 - Lunar observation experiments to adjust for system misalignments
 - Deterministic satellite operation management for system latency and orbital model inaccuracies.
- Satisfactory results where achieved: $0.2^\circ \pm 0.12^\circ$ RMS pointing accuracy.



[1] E. P. Violan et al., "In-Flight Target Pointing Calibration of the Diwata-2 Earth Observation Microsatellite," 2021 IEEE Aerospace Conference (50100), 2021, pp. 1-15, doi: 10.1109/AERO50100.2021.9438197.

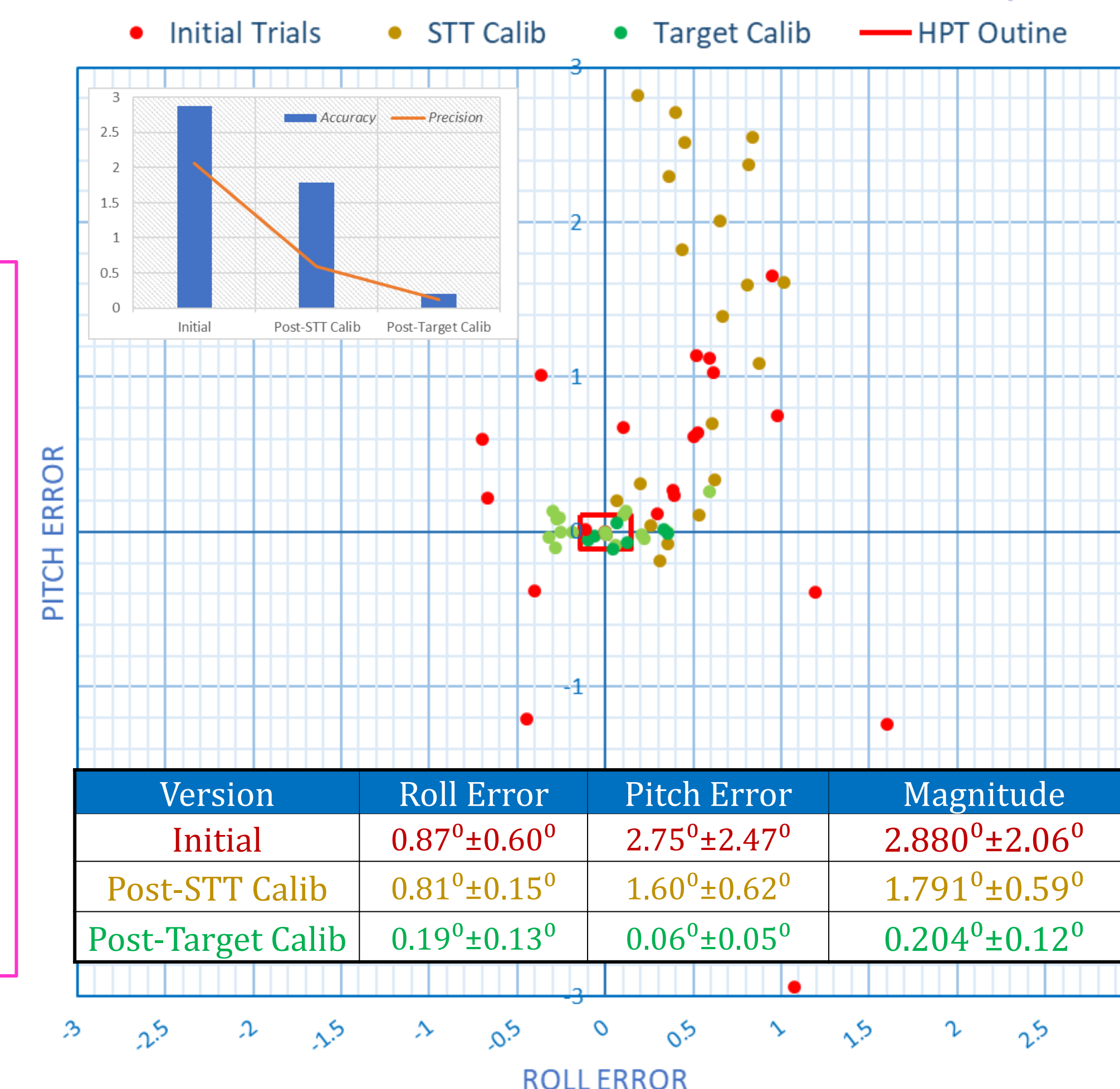
V. Recommended Operating Strategy

- Details of the command timing and the recommended conditions can now be prescribed.
- Attitude flight log data of an actual implementation of this mission procedure are also shown.



Duration (mm:ss)*	Operation
n/a (Plan prior to the nearest opportunity of target capture)	Target Attitude Calculation: Use latest TLE orbit model
	Synchronize and Update On-board Orbital Model
	Upload of Stored Commands
S + 0:00 (Begin at least 1 minute after satellite enters sunshine)	Resume ADCS operation: Initialize ACU
	Turn on Control System and actuators
S + 1:00	Coarse attitude determination is activated
S + 1:10	Set satellite for optimum SAS detection: $\varphi=-35^\circ, \theta=-45^\circ, \psi=-180^\circ$
S + 3:00	Turn On STT and initialize Parameter Settings: Gain = 400ms, Exp. Time = 28dB, f = 1670.1
S + 5:00	Fine attitude determination is activated
S + 5:10	Set satellite for optimum STT detection: $\varphi=30^\circ, \theta=0^\circ, \psi=180^\circ$
T - 5:10	Turn Off STT
	FOG attitude integration is activated
T - 5:00 (At least 5 minutes before mission capture)	Set satellite to target attitude: $[\varphi, \theta, \psi]_{target}$
T - 4:30	Initialize SHU and Optical Payloads
T - 3:00	Load capture control Settings for Payloads
T	Sequential Image Capture Of Target
T + 0:30	Save Images to Flash Memory
T + 1:00	Turn off SHU and Optical Payloads
T + 2:00	Release Active Attitude Control: Turn off sensors and actuators

Earth Observation Trials Summary



VI. Conclusion

- The study presented an operation strategy for successful on-demand earth observations by Diwata-2:
- Gradually improved the accuracy from 2.8° to 0.2°
- 0.1° accuracy in at least 24% of its post-target calibration trials
- Covered 82.8% of the Philippine's land area with over 400 successful Earth observation missions

