

# The Things You Can't Ignore: Evolving a Sub-Arcsecond Star Tracker

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- The S3S development project has produced the ST-16 star tracker.
- There is demand for a higher accuracy star tracker that has:
  - 1 arc-second ( $\sim 4.8 \mu\text{rad}$ ) accuracy, while slewing at
  - $1^\circ/\text{s}$  (track a target on the Earth's surface from LEO), with
  - 99% availability of an attitude fix
- This paper tries to answer the question: what modifications must be made to the ST-16 to meet these requirements?
- Can these modifications be achieved through an **evolutionary** approach to the ST-16 or do these changes drive a **revolutionary** approach where significant architecture changes are necessary?



S3S/ST-16 Star Tracker

**Availability** – the fraction of the sky where a good attitude fix is possible.

- Calculated using a sky survey, stellar detection threshold and FOV

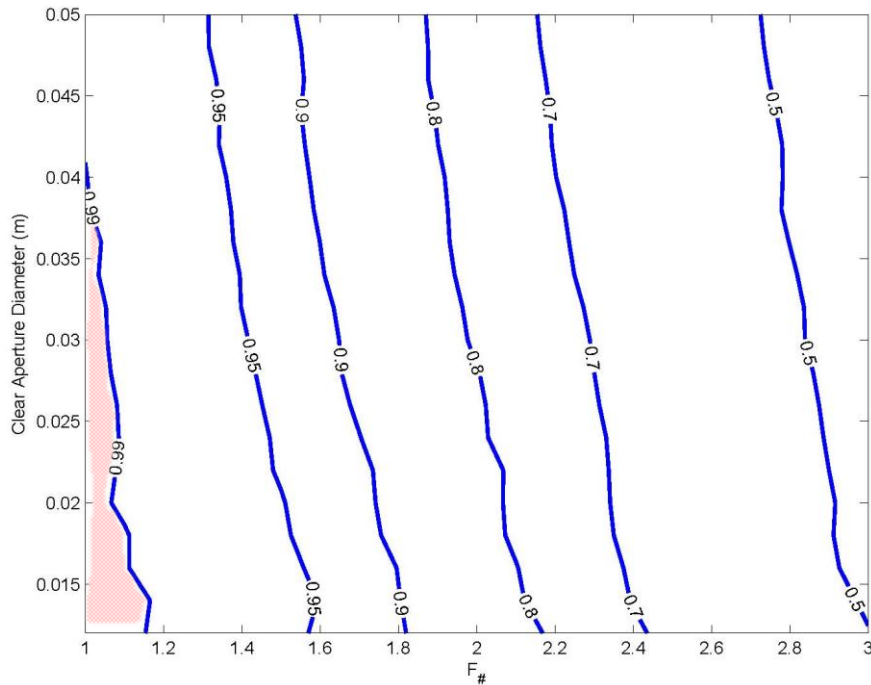
**Accuracy** – expected accuracy of the sensor

- Difficult to calculate analytically because it depends on the accuracy of individual star vectors as well as their distribution in the FOV
- We examine what centroid error we must have to ensure we meet the accuracy requirements.
- How does the ST-16 optical design limit performance?
- Can we achieve better performance with better optics and detectors?
  - We look for valid designs by changing F# and D
  - Each design is assessed by its availability and accuracy

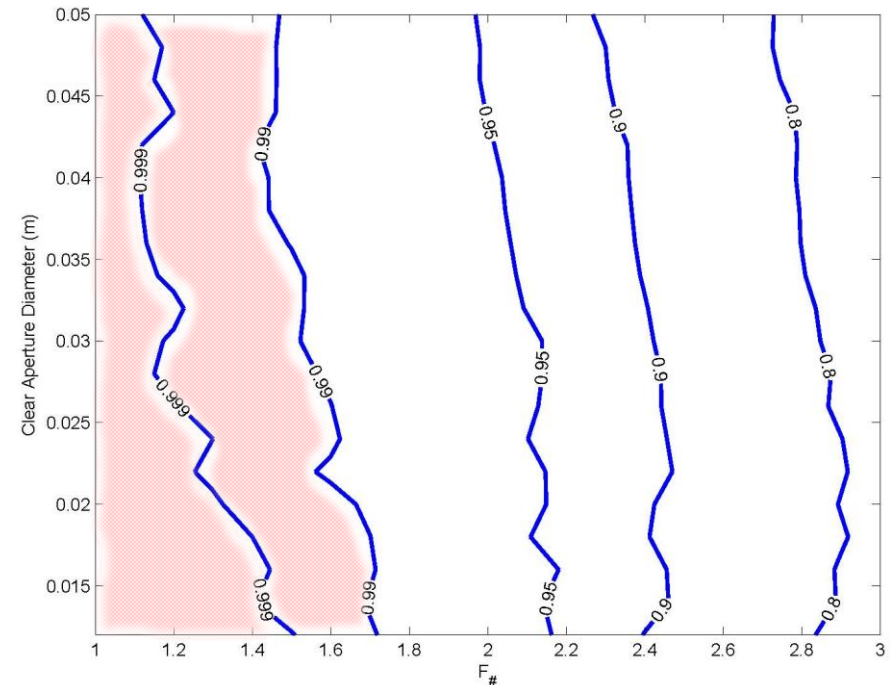
Parameter	MT9P031	CMV4000
$h$ (mm)	4.28	11.3
$\gamma$ ( $\mu\text{m}$ )	2.2	5.5
$\sigma_e$	3.5	13
Pix. Dim.	1944 x 2592	2048 x 2048

Table 1 – Detector Parameters

- Smaller focal lengths have a larger FOV and can thus see more stars.
- Star distribution favors increasing the # of stars in view by increasing the FOV rather than merely detecting dimmer stars via larger D.

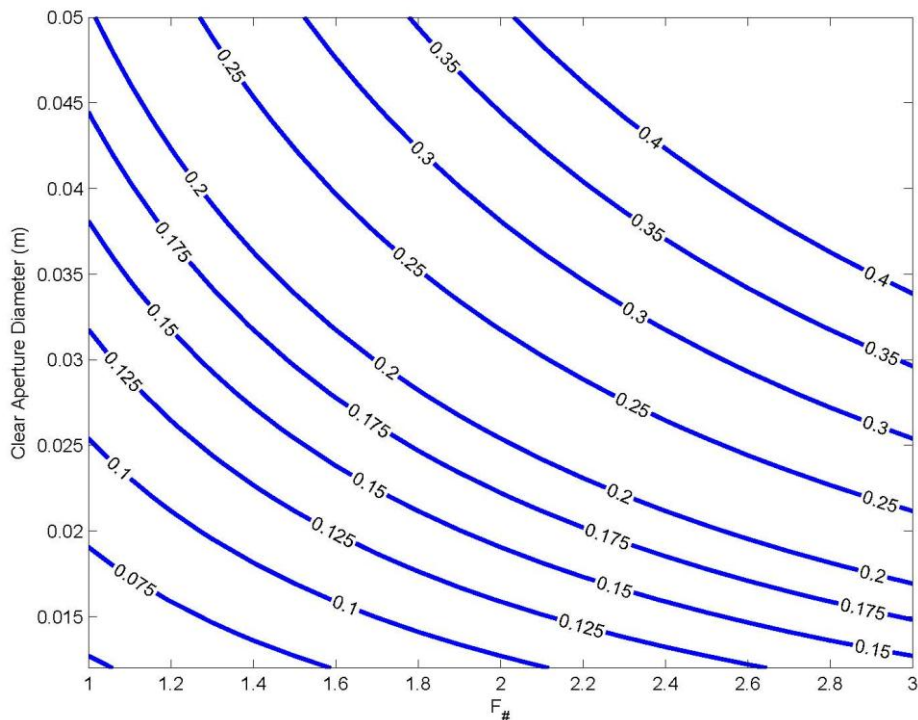


3-Star Availability from MT9P031 (@ 1°/s)

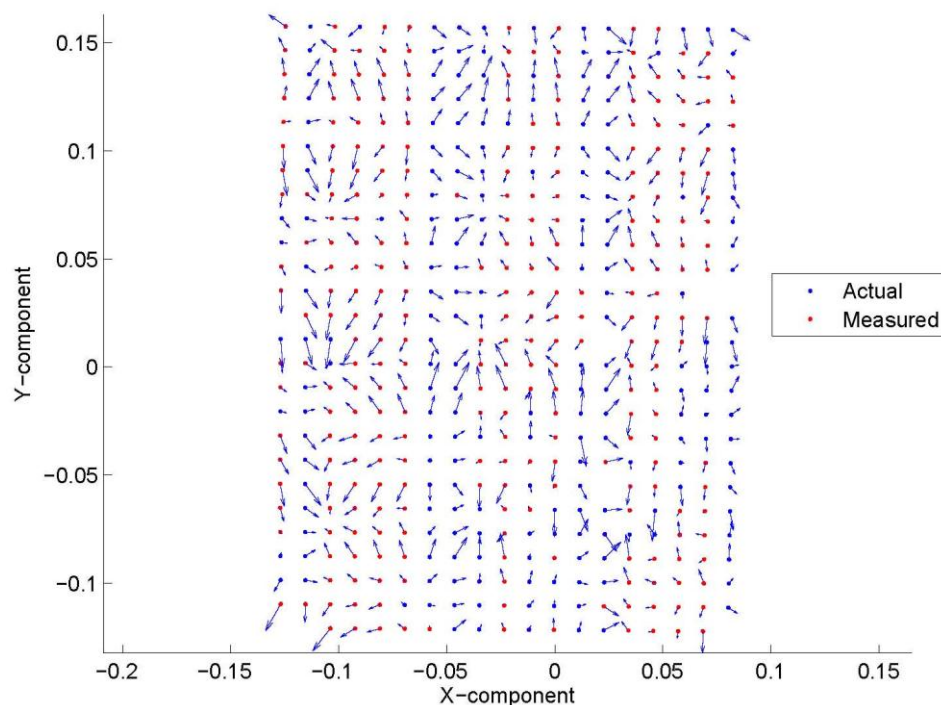


3-Star Availability from CMV400 (@ 1°/s)

- Trade studies show that without an improvement in centroid accuracy we cannot meet target requirements with just a lens change.
- If we can improve this from the current  $\sim 0.2$  pixels to  $\sim 0.07$  pixels, we can meet accuracy requirements.



Calibration Residual Req. – MT9P031



ST-16 Calibration Residual Plot

We consider two types of thermal deformation:

- Change in bulk temperature
  - Causes thermal expansion in the glass lens elements and in the structure that positions them.
  - Changes the index of refraction of the glass itself.
  - If we can still match stars, we can use the observed star positions to determine the effective focal length and correct these effects.
- Temperature gradients
  - Lateral temperature gradients across a cantilever lens assembly will result in bending.
  - Nothing inherent in the image that would allow for the bend angle to be measured and corrected. The design must minimize the thermal gradient bending of the optics.

# Effects we can't ignore: Star Positions

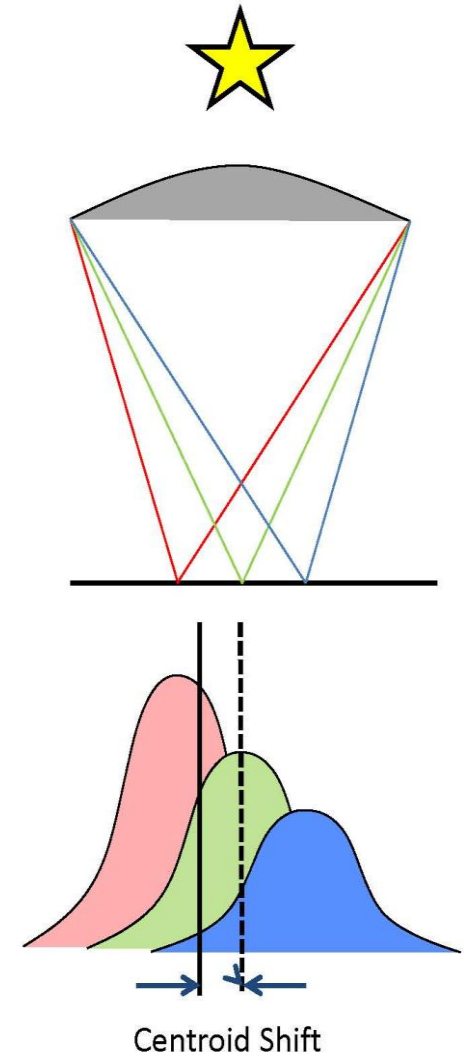
We consider three effects that can change the apparent star positions:

- Annual Parallax - Nearby stars will move slightly over six months due to the angular motion of the Earth around the Sun.
- Proper Motion – Caused by secular motion of the stars themselves
- Stellar Aberration – Angular displacement caused by the velocity of the observer (Earth around Sun  $\sim 100\mu\text{rad}$  & Satellite around Earth  $\sim 25\mu\text{rad}$ )

Effect	Magnitude	Correctable	Extra Info Required:
Annual Parallax	Small	Not Necessary	None
Proper Motion	Large	Yes	Absolute Time
Stellar Aberration	Small/Large	Yes	Ephemeris

# Effects we can't ignore: Chromatic Aberration

- Effective focal length varies as a function of wavelength
- Different stars have different surface temperatures and thus different dominant colors.
- Leads to uncertainty in the true star vector
- Can be eliminated from the optics (via Hardware changes) or compensated by software.
- Optics can be made almost achromatic by careful selection of glasses, and/or bandpass filters.
- Can be corrected in software with a color-dependent correction. (Catalog must include spectral information)





## **Optical Trades:**

- The impact of optical design on availability is well understood. Star distribution favors increasing the FOV over aperture diameter.
- The impact of optical design on accuracy is less clearly understood.

## **Star Tracker Calibration:**

- Lab. calibration of a sub-arcsecond ST using our current setup is not feasible.
- On-orbit self calibration not only allows for high accuracy model estimates but also tolerance to dimensional changes over time.

## **Effects we cannot ignore:**

- Chromatic aberration is significant and will require correction either via optics selection or software.
- Bulk thermal changes can be corrected using on-orbit recalibration. Temperature gradients cannot and must be minimized through mech. design.
- Stellar aberrations and proper motion can and must be corrected. To do this we need access to an accurate real-time clock and orbital ephemeris.

Thank you for you time.

Questions?