



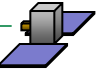
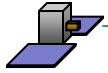
# GRAIL

Gravity  
Recovery  
and  
Interior  
Laboratory

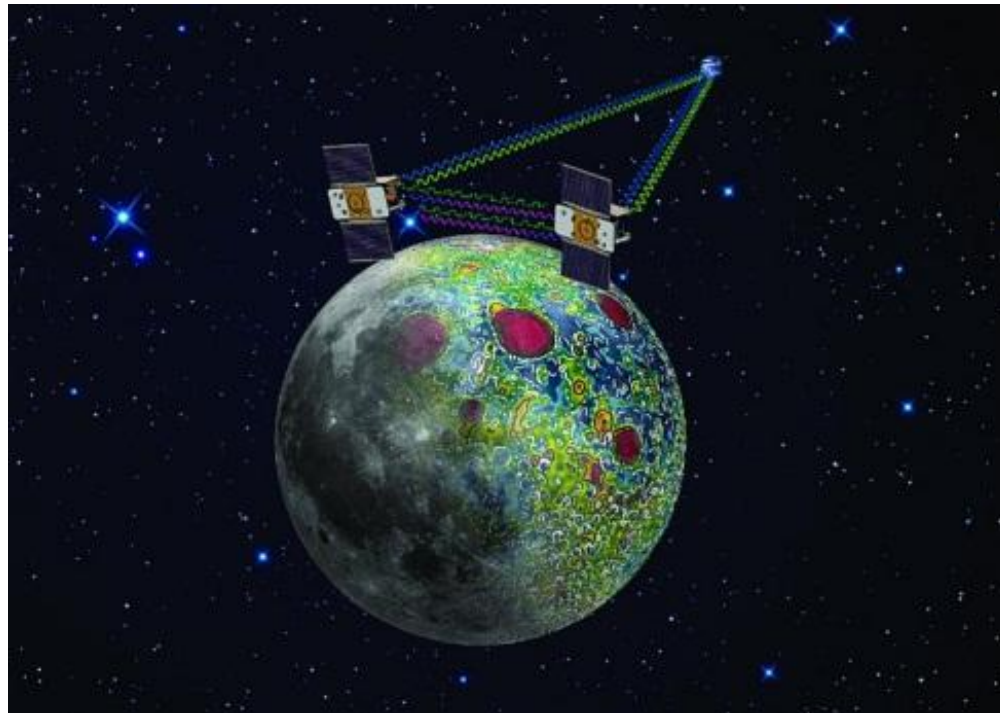
## **NASA GRAIL Spacecraft Formation Flight, End of Mission Results, and Small Satellite Applications**

Christine Edwards-Stewart  
**Lockheed Martin Space Systems Company**

# Introduction



- Overview of Gravity Recovery and Interior Laboratory (GRAIL) mission
- GRAIL design evolution from small-satellite technology
- Small-satellite formation-flight applications
- Lessons learned for future small-satellite missions



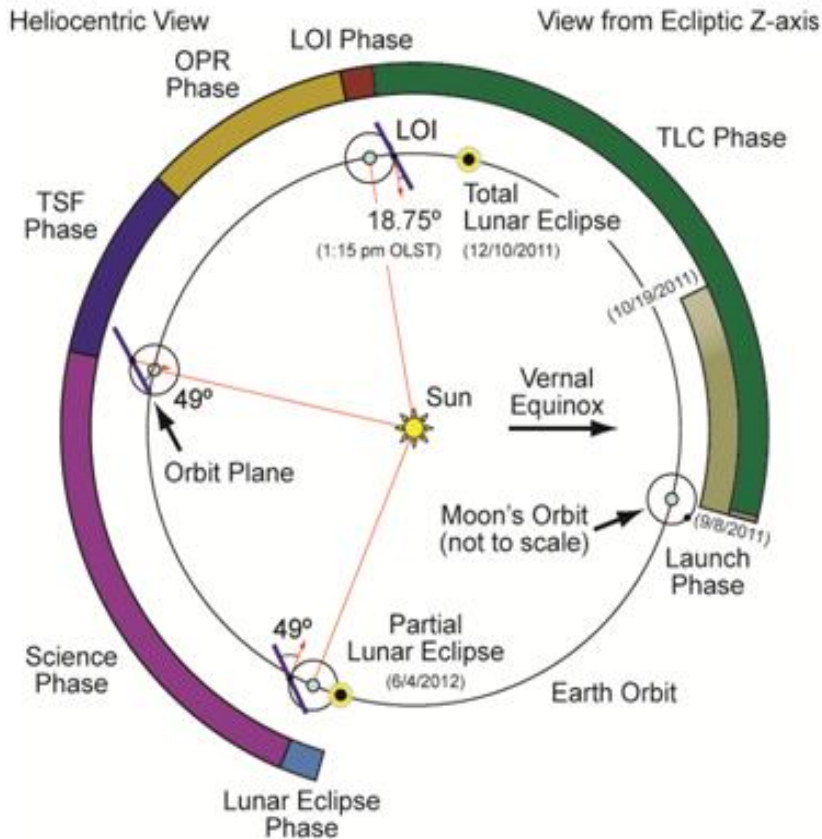
# Overview of Mission



- NASA Discovery Program mission to develop high-resolution gravity map of Moon
- Team: NASA, JPL, Lockheed Martin, Goddard, MIT, and Sally Ride Science

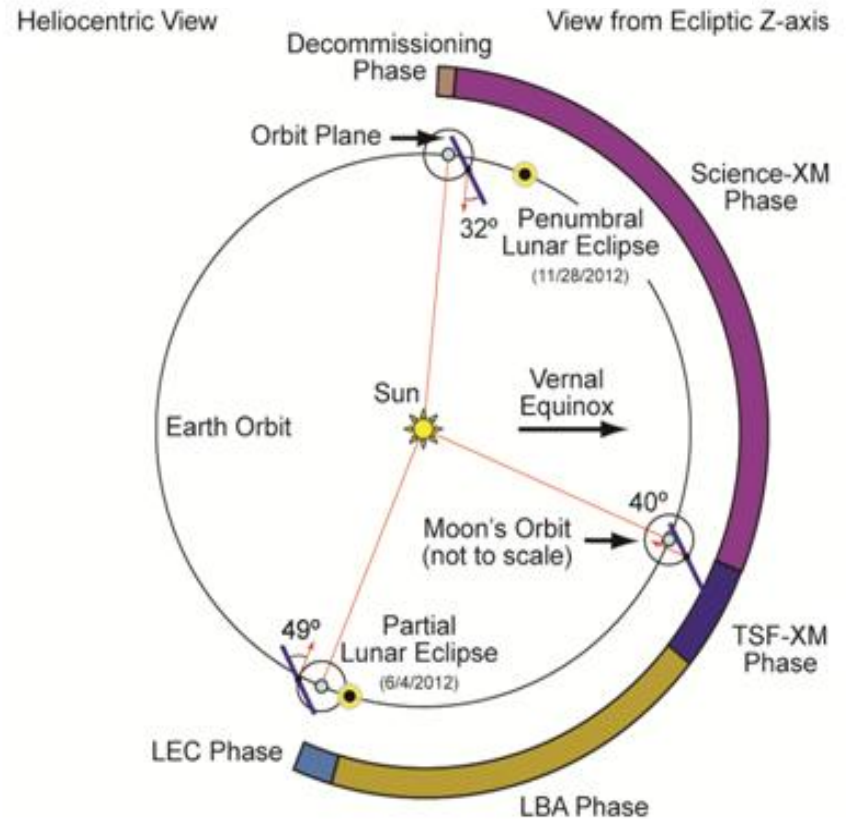
## Primary Mission

Separation of 175-225 km  
Average Altitude of 55 km



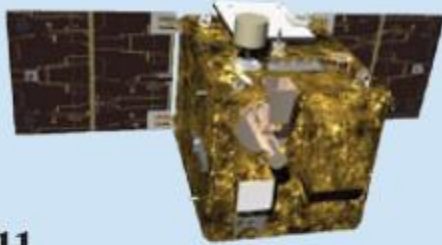
## Extended Mission

Separation of 40 km  
Altitude as low as 11 km



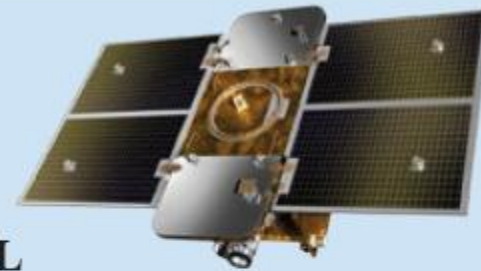
# GRAIL Design Evolution from Small-Sat Technology

- GRAIL adapted from the platform of XSS-11
  - *XSS-11 was an AFRL technology demonstration mission for autonomous rendezvous and proximity operations*
  - *Implemented the LM 300 bus*
  - *Modifications made to increase propellant tank and solar array sizing to meet mission's delta-v and power requirements*



## XSS-11

- Experimental Satellite System-11
- Autonomous Rendezvous & Proximity Operations for MicroSats
- Baseline for LM 300 Bus
- 100 kg
- Launched: April 2005

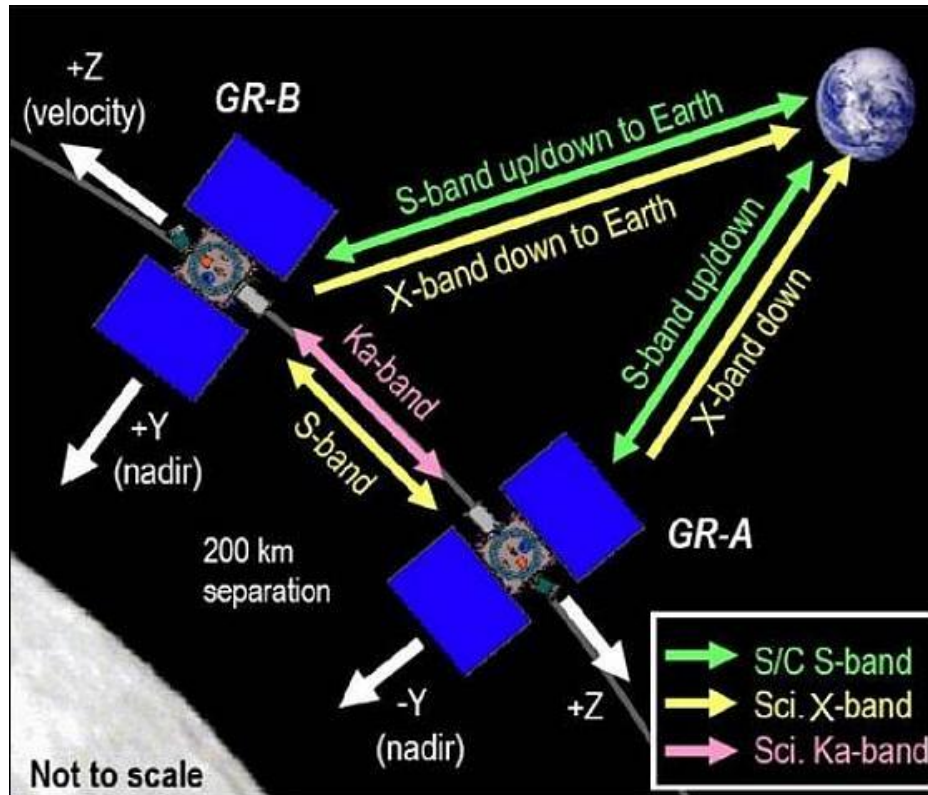


## GRAIL

- Gravity Recovery and Interior Laboratory
- High Resolution Mapping of the Moon's Gravity Field
- Studying Lunar Interior Structure
- Utilizing the LM 300 Bus
- 133 kg
- Launched: Sept 2011

# Formation Flight Approach

- Primary science instrument, the Lunar Gravity Ranging System (LGRS)
  - Measured range with the  $K_a$ -band inter-spacecraft link
  - Each LGRS pointed towards the other spacecraft along the  $-Z$  axis in the local spacecraft body frame



# Formation Flight Approach, continued

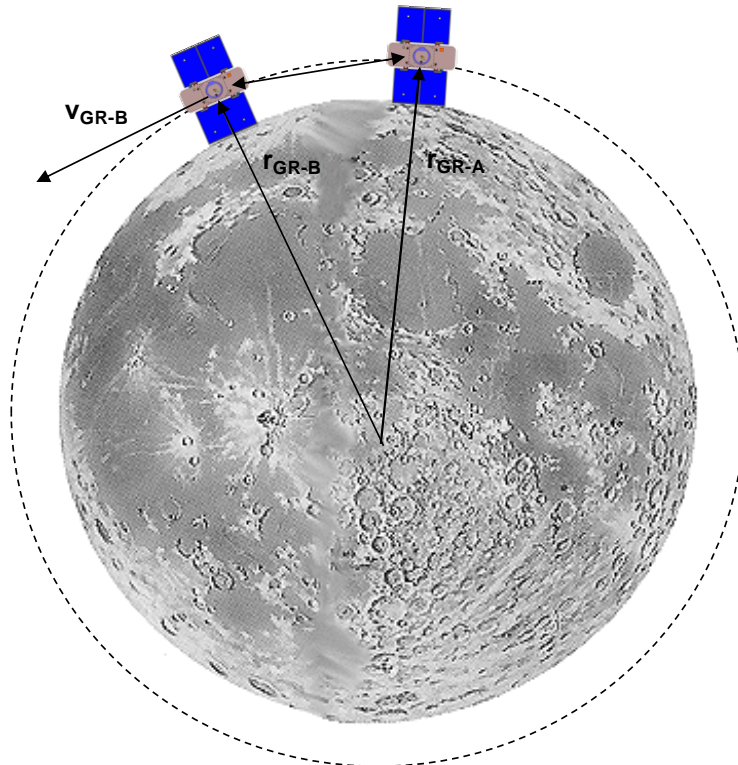
- Dual spacecraft system's elliptical orbits represented with Chebyshev polynomial coefficients as an input to flight software, called the Ephemeris files

## Orbiter Point Mode

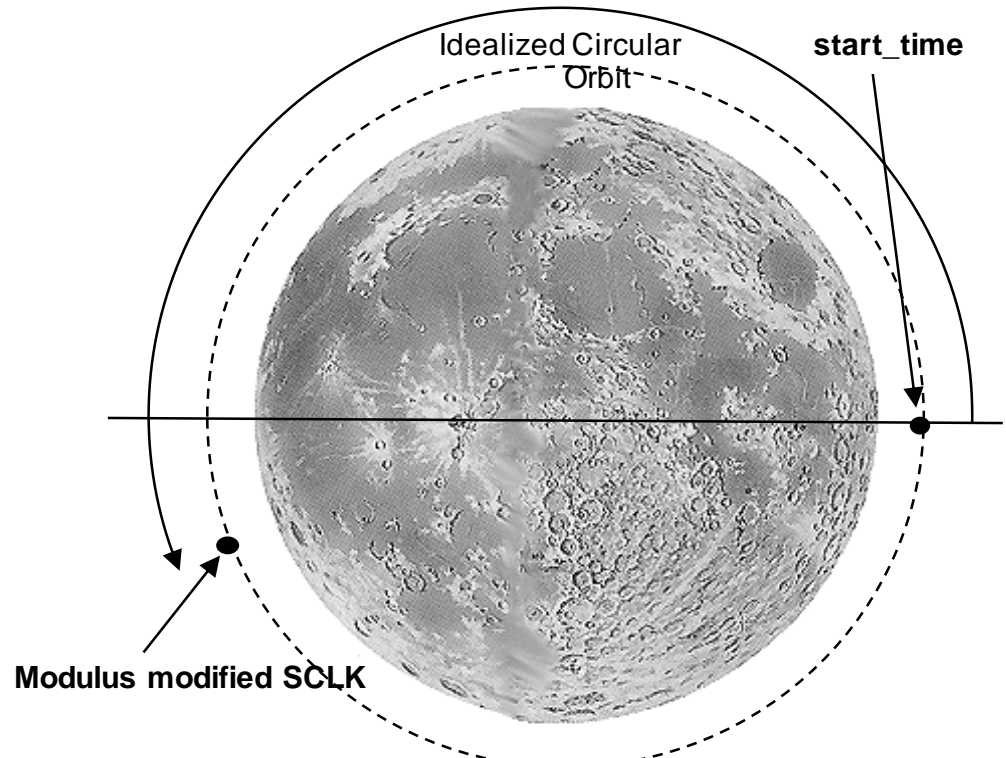
Ephemeris files formed the basis for the relative reference vectors in spacecraft-to-spacecraft pointing, or Orbiter Point Mode

## Contingency Velocity Point

Contingency implementation was a circular orbit representing the mean of the actual elliptical orbit, modulus modified SCLK, and Velocity Point



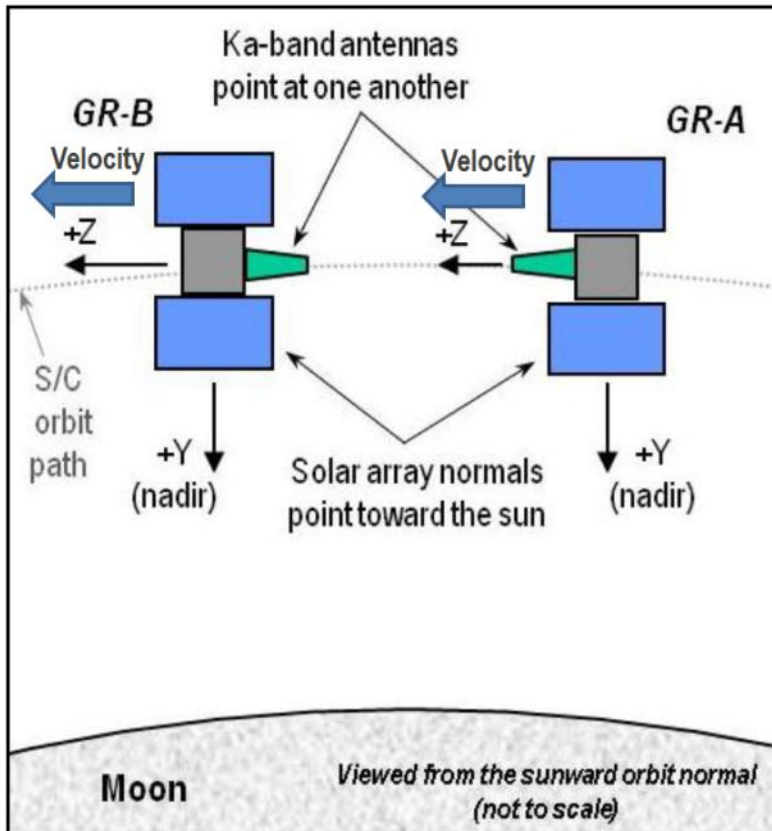
**Orbiter Point Mode with Nominal Orbit**



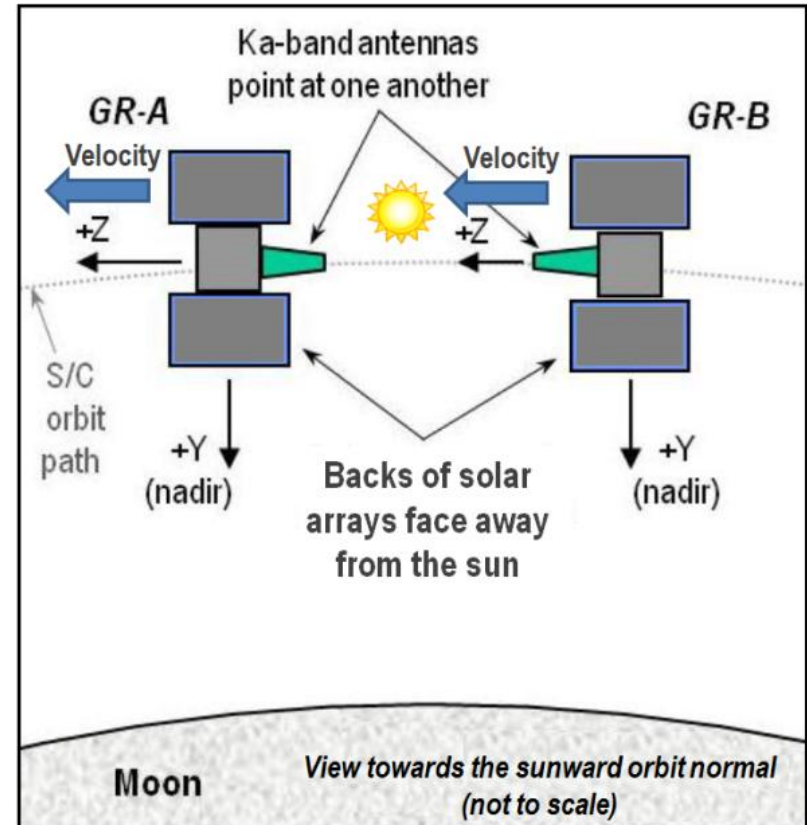
**Velocity Point with Contingency Orbit**

# Adjusting the Formation for Extended Mission

- Geometry between Sun and spacecraft orbit changed from primary to extended mission
  - *Caused the need to swap GRAIL-A and GRAIL-B positions in the formation*

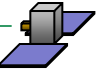
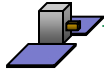


**Primary Mission Science Phase**



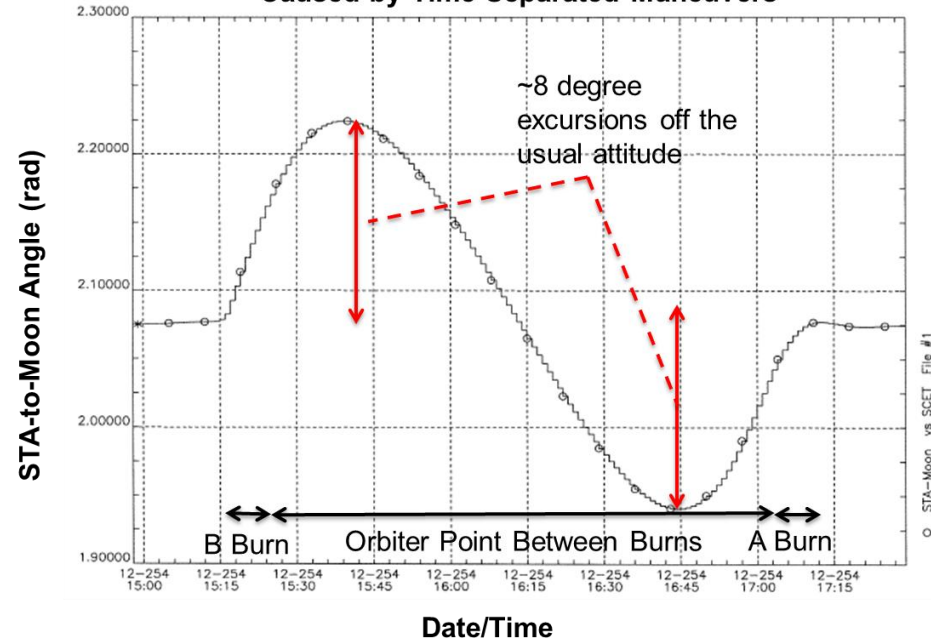
**Extended Mission Science Phase**

# Trajectory Maintenance Maneuvers



- Frequent maneuvers were required to maintain low altitude in extended mission.
- If Orbiter Point was continued between maneuvers with a 2 hour separation, spacecraft would have significant attitude excursions.
- Trade study goals:
  - Minimize attitude excursions and operational complexity
  - Maximize science collection

Simulation Results for GRAIL-B Attitude Excursions Caused by Time-Separated Maneuvers

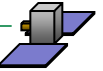
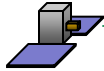


## Options Considered in Trade Study

Option #	Option Description
Option 1	Do Nothing: Perform maneuvers with same timing separation as Primary Mission, and accept attitude excursions
Option 2	Perform maneuvers at the same time, potentially avoiding attitude excursions
Option 3	Make each spacecraft point as if the other spacecraft is still in the same orbit
Option 4	Command the spacecraft out of Orbiter Point around the maneuvers



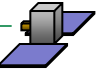
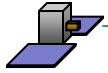
# Trade Study for Formation Flight Around Maneuvers



- Best solution from trade study was to perform maneuvers nearly simultaneously

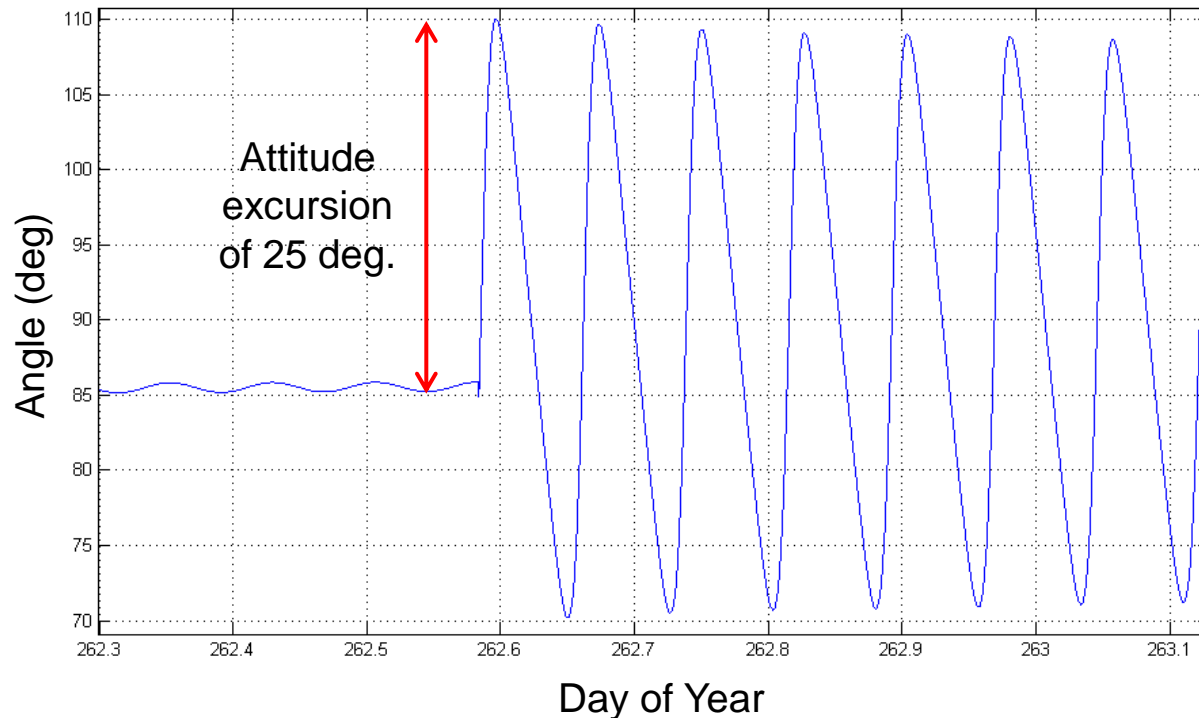
Option	Meet Attitude Error Requirements?	Operations Impact	Science Impact
<b>Option 0:</b> Do nothing	No	Low	Low to Medium
<b>Option 1:</b> Perform Burns at the Same Time	Yes	Low to Medium	Low
<b>Option 2:</b> Make Spacecraft Point as if Other is Still in Same Orbit	Yes	High	Medium
<b>Option 3:</b> Take Spacecraft Out of Orbiter Point Around Burns	Yes	High	Medium to High

# Contingency Operations for Missed Maneuver



- If one spacecraft missed a maneuver, as soon as onboard ephemeris knowledge was updated, it would point at the other spacecraft in a different orbit causing attitude excursions of ~25 degrees.
- Solution: Command both spacecraft into velocity point until the next maneuver transitioned them into the same orbit again.

**Simulation Results of Missed Maneuver**



# Lessons Learned



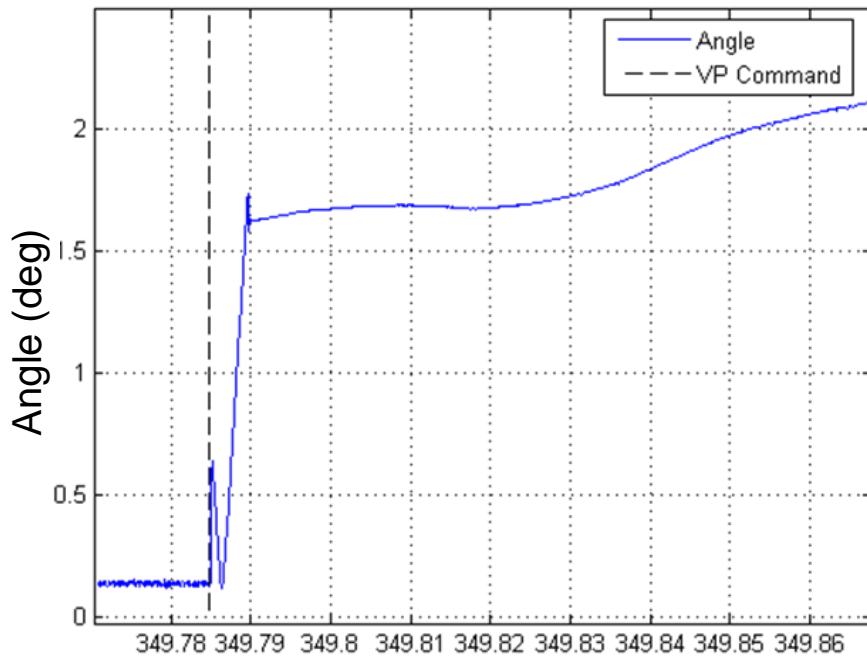
- Future small-satellites missions that can benefit from the demonstrated technology on GRAIL
  - *Formation-flight missions implementing swarm operations, distributed and networked satellites, interferometry, or gravity mapping*
  - *Future Great Observatories*
- Reuse of heritage spacecraft architecture and low-cost solutions
  - *Design costs reduced through:*
    - Reuse of XSS-11 bus
    - Implementation of innovative approach to single-string redundancy
- Formation-flight operations require vigilance to maintain situational awareness
  - *Small satellites can affect each other in formation flight*
- Preparations for changes in the formation configuration
  - *Perform careful planning, thorough investigations, stakeholder inclusive trade studies, and early simulation testing*
- Implementation of a contingency mode in case the formation is broken
  - *Velocity point mode would have enabled continued flight without dependency on other spacecraft if it had been needed*

# Lessons Learned, continued



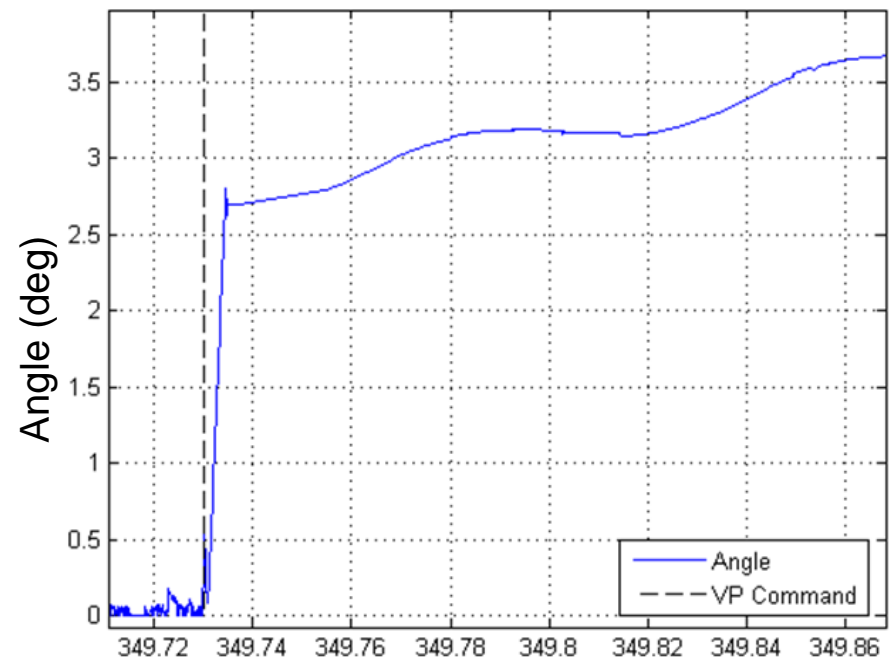
- Flight demonstration of velocity point
  - *Part of decommissioning activities*
  - *Both spacecraft were commanded to velocity point as an engineering test to validate the function for future missions*
  - *Velocity point performed successfully*

**Flight Results of GRAIL-A Velocity Point**



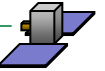
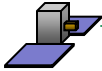
2012 Day of Year

**Flight Results of GRAIL-B Velocity Point**



2012 Day of Year

# Conclusion



- To obtain lunar gravity data, the two GRAIL spacecraft flew in formation with coordinated high precision pointing in an Orbiter Point Mode
- Orbital altitude of spacecraft lowered during second half of 2012 to increase the resolution of the gravity data
  - *Changes to operations made to achieve and maintain formation flight at the lower altitudes*
- GRAIL mission completed at the end of 2012
- The two spacecraft had no emergency safe mode entries, and no need to implement the contingency plans for a missed maneuver
  - *Contingency Velocity Point demonstrated during decommissioning*
- Successful mission created a lunar gravity map of unprecedented resolution