Electric Field instrumentation for CubeSats

Sunday, August 9th, 2015

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• The Need:
Distributed multipoint measurements of the electric field in the space environment.

• A Solution:
One way to affordably achieve these observations is to make use of constellations of miniature spacecraft with miniature instrumentation.

• Technology Gap:
New low SWaP instrumentation for observing DC electric fields suitable for flight on spacecraft as small as CubeSats -> Instrument is the CubeSat
### Motivating Requirements

<table>
<thead>
<tr>
<th>Quantity</th>
<th>Requirement</th>
<th>Goal</th>
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<tbody>
<tr>
<td>Range</td>
<td>0-150 mV/m</td>
<td>0-250 mV/m</td>
</tr>
<tr>
<td>Precision</td>
<td>±2 mV/m</td>
<td>±0.1 mV/m</td>
</tr>
<tr>
<td>Accuracy</td>
<td>±3 mV/m</td>
<td>±0.1 mV/m</td>
</tr>
<tr>
<td>In-track Resolution*</td>
<td>1.0 km</td>
<td>0.1 km</td>
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*unspecified for E-field in IORD, using values from the IORD-II B-field requirements.

**Primary Objective:** Measure ionospheric E-fields using a wire-boom double-probe on a spinning CubeSat platform.

**Minimum Success Criteria:**

a) **Deploy E-field booms, verify deployment**

b) **Collect on orbit and download 50,000 minutes* of E-field data that satisfies the measurement requirements of the IORD-II.**

*over a 3-month period
Above: Yahtzee and Farkle 1.5 U CubeSats with communications antenna deployment mechanism shown.

**Two** spinning spacecraft (Yahtzee and Farkle) launched from Vandenberg on October 28th. Leader–follower with spin rate: ~0.2 Hz and 102° inc. 455x810km orbit

**Electric Field** ~0.2 mV/m, Double Probe Technique, 5 m wire booms (10 m tip-to-tip), ~80 Hz sample rate

**Plasma Density** ~10² cm⁻³, Dual Langmuir Probes, ~80 Hz sample rate

**Magnetic Field** ~10 nT, ~80 Hz sample rate
Mission Update: DICE Makes First CubeSat Observations of an SED

In March 2013, DICE made the first CubeSat measurements of Storm Enhanced Densities (SED, pictured above) in the ionosphere. IDA4D assimilation successfully reproduced the SED feature over the southern hemisphere (see Figure on the right). The SED evolution followed a trajectory wrapping around the AMIE-specified dusk convection cell.

Above: DICE plasma density observations compared with IDA4D assimilation of the south polar ionosphere. Note that the enhanced densities observed by DICE (red arrows in the bottom plot) correspond to when the DICE satellite passes through a tongue of ionization during successive passes (red arrows).
Mission Update: DICE Observes Field Aligned Currents

Above: AMIE reveals that the DICE ΔB event corresponds to a region of enhanced FACs in the cusp region.

On May 22\textsuperscript{nd}, 2012, at 22:34UT one of the DICE satellites flew through an intense region of field aligned current (FAC) and detected the event with the body-mounted magnetometer. These measurements demonstrated for the first time that strong FAC’s can be detected from a strap-down magnetometer on a CubeSat.
Diagram showing the parts of the DICE Instrument Design:
- Aluminum Disk
- Boom Wire
- Inner Spool
- Delrin Spacer
Lessons Learned from DICE - roadmap towards DIME

<table>
<thead>
<tr>
<th>DICE</th>
<th>DIME</th>
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| Telemetry rates of 16 kbps | • Demonstrated 3000 kbps with Wallops facility  
• Developed and demonstrated database conditioning and processing software (9GB down) |
| Spin up to >1Hz | • Utilizing DICE heritage communications  
• Re-using database-processing software for DIME |
| • Validated sun-sensor and magnetometer determination  
• Insufficient attitude observability during commissioning  
• Problems with deploying and locking the custom deployable mass-trim booms resulted in insufficient MOI margins as well as momentum coupling during the spin-up process. This prevented at least one of the spacecraft from spinning up  
• Could not exert sufficient torque authority for open loop control  
• Control periods were interrupted by low-power modes  
• Required more configurability to address sensing issues during spin-up  
• Demonstrated de-tumble algorithm successfully  
• Validated ground determination algorithms |
| • Using the same sun-sensor and magnetometer  
• Implemented gyro sensor, added additional sun-sensor and photodiodes for improved observability  
• Simplified mass-trim deployment and implemented independent COTS actuator, hinge, and spring designs  
• Increased MOI margin to >1.20  
• Raised spacecraft stiffness  
• Improved spacecraft symmetry and fine-tuning control  
• Increased torque authority  
• Increased power margins  
• Implemented new control algorithms which are simplified and more configurable  
• Augmenting DICE ground-determination algorithms for DIME |
| Measure ion densities | • Measured on densities compared with IDA4D and IRI validating the Langmuir Probe  
• Langmuir probes successfully deployed but could be made stiffer |
| • Langmuir Probe electronics based on DICE heritage  
• Langmuir Probe mechanical design simplified and fundamental mode increased |
• Deployment Mechanism: Ratchet brake design did not allow for fast boom deployment. Now using a toothed brake

• Spool Design: Non-concentric outer spool/inner spool bushing caused excessive play. Enhancements will be reflected in the new design by incorporating precise ceramic bearings.

• Spool Design: Clearance between bearing cap and outer spool allowed for excessive rocking. Incorporated precise ceramic bearings.

• Spool Design: Spool winding was not repeatable, and had to be reset for each test, costing time. Design enhancements are reflected in the new by using a motor to enable winding and unwinding of the spool, a tensioner to maintain force on the cable, and a spool guard to prevent cable from slipping from the spool. During rewind

• Wire Boom: Coiling 5 meter wire is difficult. Already addressed in DIME design. Use of motor and independent spool segments which allow for independent adjustments of uneven cable lengths.
Deployable solar panels provide enhanced power margins (x4)

Electric Field Probe (x4)

Langmuir Probe (x2)

Tungsten Masses for enhanced balance and MOI margin (x4)

Turnstile Antenna Element (x4)
PCB Motor for DIME

- Outer Spool (rotor)
- EF Sensor
- PCB Motor (stator)

PCB Motor Concept for DIME
**Electric Field** 0.2-1000 mV/m, 4 m tip-to-tip wire booms, 379 Hz sample rate

**Electric Field Spectrometer** 16 Channels, 85-12.5k Hz, 23.7 Hz sample rate

**Plasma Density** $10^2$-$10^7$ cm$^{-3}$, Langmuir Probe, 379 Hz sample rate

**Magnetic Field** $\sim$2 nT, 379 Hz sample rate

- **Launched December 2014, Poker Flat**
- **Payload in functioning testing**
CLARA: Compact Long-boom and Antennae Release Assembly

- **Spin Rate Trim Maneuvers**
- **Point of Max. Torque (8 N-m)**
- **Point of Min. Torque (0.2 N-m)**

Dimensions:
- 229 mm
- Φ229 mm

Graph showing:
- Deployed cable length [m]
- Max force per cable [N]
- Spin rate [Hz]

8/20/15
Conclusions

• Major strides have been made in developing hardware infrastructure and instrumentation for science on small payloads.

• DICE was a step in this evolution. It was an ambitious program with two CubeSats, each carrying three space weather instruments. DICE was unable to orient and spin to deploy its cable booms, yet resulted in the development of the most capable radio system to date for CubeSats, enabling data downloads many times faster than existing hardware.

• The mission had many successes, and there were also many lessons learned that were implemented on ASSP and DIME, and the new CLARA instrument
Thank You!
(...or what we will do with “DIMEsat” Risk Reduction mission once it’s in space...)

• VxB validation (1 continuous day of data)
• DMSP conjunctions
• ISR + SuperDarn conjunctions (minimum of 3 conjunctions)
• CALVAL is better at high latitudes because of more conjunction opportunities, suggesting that a high inclination orbit is preferred for this technology demonstration mission
• DICE Electric Field Instruments and CubeSats
• Review the challenges and lessons learned from the DICE mission
• Describe the DIME SensorSat, showing how the various challenges are being addressed for DIME, and demonstrating how the new systems will meet its measurement requirements.
• Auroral Spatial Structures Probe
• deployment lengths of 50 meters.
### Dynamic Ionospheric Measurement of Electric fields Satellite (DIMEsat)

<table>
<thead>
<tr>
<th>Driving Requirement (Goal)</th>
<th>Capability</th>
<th>Margin (Goal)</th>
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<tbody>
<tr>
<td><strong>E-Field (Satellite Ref Frame)</strong></td>
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<td><strong>E-Field</strong></td>
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<tr>
<td>1. ± 1250 (1250) mV/m range</td>
<td>1. ± 1625 mV/m range</td>
<td>1. 27% (26%)</td>
</tr>
<tr>
<td>2. 0.5 (0.15 ) mV/m sensitivity</td>
<td>2. 0.057 mV/m sensitivity</td>
<td>2. 908% (202%)</td>
</tr>
<tr>
<td>3. 3.6 (0.15) mV/m uncertainty</td>
<td>3. 1.96 mV/m uncertainty*</td>
<td>3. 14% (-49%) *</td>
</tr>
<tr>
<td>4. DC to 4 (50) Hz bandwidth</td>
<td>4. DC to 20 Hz bandwidth</td>
<td>4. 400% (-60%)</td>
</tr>
<tr>
<td>5. 4 to 1k (12k) Hz spectrometer</td>
<td>5. 20 to 12k Hz spectrometer</td>
<td>5. Meets Goal</td>
</tr>
<tr>
<td>6. 4 (16) spectrometer channels</td>
<td>6. 16 spectrometer channels</td>
<td>6. Meets Goal</td>
</tr>
</tbody>
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<table>
<thead>
<tr>
<th><strong>B-field</strong></th>
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<tbody>
<tr>
<td>1. ± 60,000 nT range</td>
<td>1. ± 61,000 nT range</td>
</tr>
<tr>
<td>2. 5.0 (2.0) nT sensitivity</td>
<td>2. 0.5 nT sensitivity</td>
</tr>
<tr>
<td>3. 30.4 (10.2) nT uncertainty</td>
<td>3. 5 nT uncertainty</td>
</tr>
<tr>
<td>4. DC to 4 (50) Hz bandwidth</td>
<td>4. DC to 20 Hz bandwidth</td>
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<table>
<thead>
<tr>
<th><strong>Plasma Density/Temperature</strong></th>
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</tr>
</thead>
<tbody>
<tr>
<td>1. $10^4$ ($10^3$) to $10^7$ p/cm$^3$ range</td>
<td>1. $7.3 \times 10^3$ to $6.2 \times 10^8$ p/cm$^3$</td>
</tr>
<tr>
<td>2. $10^3$ (10) p/cm$^3$ sensitivity</td>
<td>2. 73 p/cm$^3$ sensitivity</td>
</tr>
<tr>
<td>3. DC to 4 (50) Hz bandwidth</td>
<td>3. DC to 20 Hz bandwidth</td>
</tr>
<tr>
<td>4. 500 (300) to 5,000 K</td>
<td>4. 300 to 5,000 K</td>
</tr>
</tbody>
</table>

*Assuming an attitude uncertainty of 0.40°