COMPUTATIONAL MODELING TO STUDY DISEASE DEVELOPMENT: APPLICATIONS TO BREAST CANCER AND AN IN VITRO MODEL OF MACULAR DEGENERATION

by

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Computational Modeling to Study Disease Development: Applications to Breast Cancer and an *In Vitro* Model of Macular Degeneration

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The progression of many diseases, such as breast cancer and age-related macular degeneration, is not fully understood. These diseases are mechanistically complex, nonlinear, and are driven by complex interacting processes that occur at different scales of time and space. When paired with traditional biological investigations, computational models can play a significant role in understanding disease progression, because computational models formalize and quantify mechanisms between interacting components and can test hypotheses about pathogenesis orders of magnitude faster than biological investigations. The results of these computational studies can then be used by biologists to inform their *in vivo* studies, and meaningful insights can be gained into disease, i.e., how to control its progression and how to treat it.

The ability of agent-based models to encompass multiple spatiotemporal scales of biological process makes this modeling framework well suited to explore biological systems and disease development. In this dissertation, we extend a multicellular hybrid agent-based modeling approach and use it to study the development of breast cancer and to better understand an *in vitro* model for age-related macular degeneration (AMD). To achieve this,
we needed to identify methods, algorithms and techniques that increase the effectiveness of agent-based models applied to disease development.

The transition in breast cancer from ductal carcinoma in situ to invasive ductal carcinoma was studied in the framework of two-dimensional breast duct structures. This model includes ductal, stromal and tumor cell types acting along with multiple biochemical and biomechanical interactions. The results of the model were qualitatively validated using micrographs of progressing ductal carcinoma and biochemical and biophysical properties reported in the literature. We also developed and applied an in silico model to an in vitro model of age-related macular degeneration. This in vitro model uses retinal cells grown in culture in territories of different controlled size to explore how the distribution of cells effects the production of vascular-endothelial growth factor (VEGF). VEGF overproduction plays a central role in AMD. The agent-based model was used to study the underlying mechanism of VEGF production, and predict the VEGF with varying configurations of cells. The model was quantitatively validated from experimental in vitro data. We developed an error-minimizing searching approach that uses available information about VEGF metabolism at the cell population level to predict currently unknown parameters of VEGF metabolisms at the cell level, essentially bridging the gap in scales between the multicellular and cellular levels of organization.
There have been several techniques developed in recent years to develop computer models of a variety of disease behaviors. Agent-based modeling is a discrete-based modeling approach used agents to represent individual cells that mechanically interact and secrete, consume or react to soluble products. It has become a powerful modeling approach, widely used by computational researchers. In this research, we utilized agent-based modeling to study and explore disease development, particularly in two applications, breast cancer and bioengineering experiments. We further proposed an error-minimization search approach and used it to estimate cellular parameters from multicellular \textit{in vitro} data.

In this dissertation, in the first study, we developed a 2D agent-based model that attempted to emulate the \textit{in vivo} structure of breast cancer. The model was applied to describe the progression from DCIS into DCI. This model confirms that the interaction between tumor cells and the surrounding stroma in the duct plays a critical role in tumor growth and metastasis. This interaction depends on many mechanical and chemical factors that work with each other to produce tumor invasion of the surrounding tissue. In the second study, an \textit{in silico} model was developed and applied to understanding the underlying mechanism of vascular-endothelial growth factor (VEGF) auto-regulation in REP and emulate the \textit{in vitro} experiments as part of bioengineering research. This model may provide a system with robust predictive modeling and visualization that could enable discovery of the molecular mechanisms involved in age-related macular degeneration (AMD) progression and provide
routers to the development of effective treatments. In the third and final study, a searching approach was applied to estimate cellular parameters from spatiotemporal data produced from bioengineered multicellular in vitro experiments. We applied a search method to an integrated cellular and multicellular model of retinal pigment epithelial cells to estimate the auto-regulation parameters of VEGF.
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ACRONYMS

**ABM** Agent-Based Model. One of a class of computational models for simulating the actions and interactions of autonomous agents (both individual or collective entities such as organizations or groups) with a view to assessing their effects on the system as a whole.

**AMD** Age-related Macular Degeneration. A deterioration or breakdown of the eye’s macula. The macula is a small area in the retina that is the light-sensitive tissue lining the back of the eye. The macula is the part of the retina that is responsible for central vision, allowing one to see fine details clearly.

**CA** Cellular Automata. A class of spatially and temporally discrete mathematical systems that are characterised by local interaction and synchronous dynamical evolution.

**DCIS** Ductal Carcinoma *in situ*. The presence of tumor cells inside a milk duct in the breast. DCIS is a noninvasive condition. DCIS can progress to become invasive cancer, but estimates of the likelihood of this vary widely.

**ECM** Extracellular Matrix. A collection of extracellular molecules secreted by cells that provide structural and biochemical support to the surrounding cells. It forms a meshwork of proteins and carbohydrates that binds cells together or divides one tissue from another.

**ECs** Epithelial Cells. Cells that line the inner and outer surfaces of the body by forming cellular layers (EPITHELIUM) or masses.

**IDC** Invasive Ductal Carcinoma. The cancer cells that began forming in the milk ducts and have spread beyond the ducts into other parts of the breast tissue. Invasive cancer cells can also spread to other parts of the body. It is also sometimes called infiltrative ductal carcinoma.

**LOX** Lysyl Oxidase. A copper-dependent amine oxidase enzyme that initiates the crosslinking of collagens and elastin. It plays a critical role in the biogenesis of connective tissue matrices by crosslinking the extracellular matrix proteins, collagen and elastin.

**MEs** Myoepithelial Cells. Smooth, musclelike cells of ectodermal origin, found between the epithelium and basement membrane in the surface of some acini of the salivary glands, which is believed to be responsible for facilitating the secretion of fluids from the gland.

**MMPs** Matrix Metalloproteinase. Also called matrixins. A large family of calcium-dependent zinc-containing endopeptidases, that are responsible for the tissue remodeling and degradation of the extracellular matrix. They play major roles in morphogenesis, wound healing, tissue repair and remodelling in response to injury.
**RPE** Retinal Pigmented Epithelium or Retinal Pigmented Epithelial (when used in the context of “cell”). The pigment cell layer that nourishes the retinal cells. It is located just outside the retina and is attached to the choroid, a layer filled with blood vessels that nourish the retina.

**TCs** Tumor Cells. An abnormal growth of tissue resulting from uncontrolled, progressive multiplication of cells and serving no physiological function.

**TGF-β** Transforming Growth Factor Beta. A secreted protein that controls many cellular functions, including cell growth, cell proliferation, cell differentiation and apoptosis.

**VEGF** Vascular Endothelial Growth Factor. A signal protein produced by cells that stimulates vasculogenesis and angiogenesis.
CHAPTER 1
INTRODUCTION

Biological systems are intrinsically complex. They are operate on multiple functional scales that span across multiple temporal and spatial domains at scales from the atomic level ($10^{-10}$ m) to the whole living organism (1 m), and from nanoseconds ($10^{-9}$ s) to years ($10^8$ s) (Figure 1.1). A successful understanding of biological function emerges if all relevant information at several levels of organization is integrated, as discussed in [6–8]. For example, in the context of heart function and pathology, Noble [9] illustrated how the success of drug therapy depends not only on understanding the functions at the protein level, but also on knowing how a protein interacts with its surrounding cellular machinery to generate functions at a higher level. There is no doubt that an understanding of the inter-scale and intra-scale interactions is critical to the study of human diseases and potential treatments.

The need to model complex temporal and spatiotemporal processes at many scales has led to the emergence of numerous computational modeling techniques including systems of differential equations, cellular automata simulators, and agent-based models [10]. Multi-scale computational models provide unique capabilities to capture the connectivity between diverse scales of biological function [11,12] and they can also bridge the gap in understanding between in vitro experiments and in vivo models [13–15]. The advent of powerful computing systems, combined with quantitative data from high-throughput experimental platforms, has expanded multi-scale modeling more comprehensively investigate biological phenomena [16].

The main challenge in multi-scale modeling is maintaining the balance between the computational complexity of the model and its fidelity [17]. The level of model resolution is tightly coupled to computational complexity, where the computational load increases as a function of the model details [18]. Computational modeling that aims to explore such
Figure 1.1. Multiscale models of the human body targeting complex processes that span diverse time and length scales of biological organization [2].

Multi-scale systems have to incorporate several techniques because of the diverse time and space scales involved. In section 1.1 we provide an overview of different approaches and techniques used to handle these tasks. Then, in Section 1.2, we summarized the main objectives for the research performed in this dissertation. In Section 1.3, we present the projects that were included in this research. In Section 1.4, the research methodology and strategies are explained. Finally, we demonstrate the impacts of the research in Section 1.5.

1.1 Modeling Approaches and Techniques in Computational Systems Biology

1.1.1 Top-down, Middle-Out, or Bottom-up Approaches

There are three approaches to multiscale modeling: top-down, middle-out or bottom-up [19]. The bottom-up approach begins with modeling the system components in isolation and then integrating them to study the emergent properties and predict the behavior of the entire system. The basic principle of the bottom-up approach is to mathematically or
graphically model relationships between the system's components, starting from the lowest level of the multi-scale structure, such as genes and proteins, setting model parameters based on available experimental values, then verifying the model by comparing its behaviors with real system behaviors [20, 21]. The bottom-up approach has a computational problem, which comes from the difficulty and complexity of the integration process across multiple scales. Also, the limitations of bottom-up understanding, as well as a lack of knowledge of many cellular- and tissue-level responses to stimuli that could be used to validate models, present additional long-term, fundamental challenges [22].

Top-down approaches start by considering biological properties and behaviors in the whole system. These behaviors are then used to develop a model that can describe the high-level properties used discover and characterize biological mechanisms at lower levels. Basically, the top-down approach involves defining ways in which the systemic function of interest varies with time or/and conditions, then inferring hypothetical lower-level structures responsible for this function. For instance, in [23], the researchers presented a top-down approach to modeling the single-chain antibody folding pathway [24, 25]. After the scope of the model was established, model development started with the construction of the most basic mathematical model. Incrementally, they appended desired biological details to the developing model and evaluated their effects on model performance until the desired level of detail had been achieved. The top-down approach is applicable to systems of all sizes and with all amounts of available biological information [26].

The third modeling strategy is the middle-out approach, which begins with an intermediate scale such as a cell, then is gradually expanded to include both smaller and larger scales. The middle-out approach is designed to overcome the intrinsic limitations of the above approaches, and it is typically constructed and tested at the levels where we have the most detailed information [27, 28]. For example Noble [9] used a middle-out approach in modeling the heart that it benefited from the wealth of accessible experimental data available at the cellular level and the data-rich modeling of the 3D geometry of the whole heart. In this dissertation, developed for ductal carcinoma in situ is a bottom-up approach
and the model developed for studying VEGF metabolism is a middle-out model.

### 1.1.2 Continuum, Discrete, or Hybrid Techniques

Modeling can take: discrete, continuum, or hybrid approaches. Continuum models use partial differential equations that are capable of capturing larger-scale systems and provide insight into the relationship among the components of the system. They can be used for modeling several levels of biological systems. Although a continuum model is relatively quicker and easy to implement, it does not capture the discrete nature of systems consisting of individual cells and becomes limited when it is used to model a complex process involving multiple variables [29,30].

On the other hand, in discrete models, individual cells are explicitly represented in space and time. In these models, individual cell behaviors and interactions with other cells and with the environment can be simulated, enabling emergent system behaviors and properties. Discrete models are usually limited to relatively small numbers of cells due to a large computational demand, and as a result a typical discrete model is usually designed with low domain size [31,32]. Two major, related discrete modeling strategies currently exist: Cellular Automata (CA) and Agent-Based Model (ABM). A typical CA is a collection of cells on a grid of specified shape. CA has a finite set of cell states, a regular discrete lattice, a finite set of neighboring cells, and rules for the transition of cell states, such as division, migration, apoptosis, and differentiation [29,29,33]. In contrast, an ABM asynchronously represents phenomena as dynamic systems of rule-based interactions among agents and their environment, following a set of rules. It is a rule-based, discrete-time, and discrete-event computational modeling methodology that employs computational objects called agents, as in [34–37]. ABM and CA are similar in that the behaviors of agents or cells are controlled by the rules in their environment or neighborhood, both belong to the bottom-up approach, and global emergent proprieties and behaviors are generated from local interactions. However, CA models impose a simpler quantization space which is unrealistic and limits fidelity, thus CA is weaker in its spatial representation [10]. Recently, agent-based models have become a powerful framework, widely used by computational biological and cancer researchers, since
they have potential to encompass several scales of biological organization and the locations of the agents.

A promising alternative modeling technique is the hybrid models which combine discrete and continuum approaches, and take the strengths of each approach. Recently, hybrid models have attracted considerable attention due to their success in many biological application [38–41]. The models developed in this dissertation are hybrid models that consider particles - the discrete component - and soluble products, such as diffusion proteins, and nutrient - the continuous part of the model.

A choice among modeling approaches should depend on the biological questions that are being addressed. Establishing which model framework to use and what level of detail to include still remain open questions. Many researchers provide strategies and tactics that can help in choosing a suitable approach based on the problem characteristics. Meier-Schellersheim et al. [3] provided an overview of how different scales of experimental research can be combined with the appropriate computational modeling techniques to
carry out multi-scale modeling of cell-to-organ systems as summarized in Figure 1.2. In this dissertation, we develop a hybrid, agent-based framework to model the transition in breast cancer from ductal carcinoma *in situ* to invasive ductal carcinoma (Project 1), and study the effect of retinal pigment epithelial cell patch size on VEGF expression (Project 2). Finally, we fit the developed model in Project 2 to available *in vitro* experimental data, so as to estimate the model's parameters (Project 3).

### 1.2 Objectives

The core goal of this research is to utilize a multicellular hybrid agent-based modeling approach in studying disease development and progression. The major question on which this research focuses is: how can a hybrid agent-based modeling approach be utilized to study and explore disease development, particularly in two applications, breast cancer and bioengineering experiments related to AMD? To achieve this, we need to identify methods, algorithms and techniques that increase the effectiveness of these models. We have realized this overall goal by completing three specific aims:

The first aim of the dissertation is to introduce a multicellular agent-based model of ductal carcinoma *in situ* growth and invasion that includes ductal, stromal and tumor cell types acting along with multiple biochemical and biomechanical interactions. This model replicates the disease state associated with breast cancer from initiation to invasion. This work provides a robust predictive modeling and visualization system to enable discovery of molecular mechanisms involved in tumorigenensis and metastasis, testing of candidate therapeutics, and more rapid identification of therapeutics against malignancy.

The second aim of this dissertation is to apply an agent-based framework to provide an *in silico* model that can be used to understand a central aspect of an *in vitro* model for age-related macular degeneration (AMD): the effect of retinal pigment epithelial cell patch sizes on growth factor expression. This framework provides a model for emulating disease states associated with the deterioration of retinal tissue during AMD.

The third and final aim of this dissertation is to develop an alternative approach to bridge the multi-scale gap by identifying cellular biochemical and biophysical parameters
from multicellular data. A search method is developed and applied to estimate cellular parameters related to VEGF metabolism from spatiotemporal data available from a bio-engineered multicellular *in vitro* model of AMD development. The method successfully identifies values for VEGF properties that can be used in the model produced in Project 2 to reproduce the spatiotemporal derived from *in vitro* experimental data.

1.3 Projects Outlines

1.3.1 Project 1: Interactions of Stroma and Tumor Cells in Carcinoma *in Situ* to Invasion: An Agent-Based Modeling Approach

Breast cancer is one of the main causes of cancer-related deaths in women. *In situ* ductal carcinoma of the breast is the most common precursor to invasive ductal carcinoma (IDC). Ductal carcinoma *in situ* (DCIS) develops over two to twelve years [42] and is not a life-threatening cancer, but is clinically important because it can be detected and treated before the duct is breached allowing the tumor to invade neighboring tissues. Left untreated, 14%-15% of DCIS progress to invasive cancer [43].

In this project, we developed a multicellular agent-based model of ductal carcinoma growth and invasion that includes ductal, stromal and tumor cell types, transforming growth factor beta (TGF-β), matrix metalloproteinase (MMP), lysyl oxidase (LOX), and extracellular matrix (ECM) protein assemblies, including the basement membrane. Unlike models that consider only biochemical inputs, the model developed in this work explicitly determined tensional and compressive forces within the developing tissue along with the distributions of and cellular responses to biochemical agents. The model demonstrated that MMP secretion sufficiently weakens the ductal basement membrane and epithelial tight junctions to undermine ductal integrity and that compressive and tensile stress within the growing tissue contributes to metastasis.
1.3.2 Project 2: Developing An in Silico Model to Study The Effect of Retinal Pigment Epithelial Cell Patch Sizes on VEGF Production

Age-related macular degeneration (AMD) is a leading cause of irreversible blindness worldwide [44,45]. Degeneration of retinal pigment epithelial (RPE) cells severely damages the visual function of retina photoreceptors. Age-related alterations of the RPE include changes in pigmentation and the reduction of cell density of RPE [46]. There are two forms of AMD: dry (atrophic) and wet (exudative). In exudative AMD, new blood vessels from the underlying choriocapillaris grow toward the RPE. These processes often lead to irreversible loss of the central visual field [47]. Anti-VEGF therapy is used to treat exudative AMD because of the central role that VEGF plays in neovascularization. In vitro studies provide powerful tools for examining the links between growth factor expression, tissue reorganization and the progression of the disease, and replicate the effect of atrophic and leaky RPE cells on VEGF expression. However, the stimuli leading to enhanced VEGF secreted from RPE cells and the subsequent neovascularization processes in the choroid are still not fully understood [48,49].

Vargis et al. [1] used the bioengineered micropatterning techniques to create a regular arrangement of circular colonies, called patches, populated with RPE cells surrounded by an empty substrate. Creation of this micropatterns involves many sequential steps. The non-populated regions imitate necrotic regions in the retina that result from repeated exposure to reactive oxidative species, triggering death of the retinal pigment epithelium followed by death of the overlying photoreceptors and neovascularization, which is leading exudative AMD [50,51].

The goal of this study was to develop a computational model to replicate the in vitro cellular model [1], and then to use the computational model to study how different configurations of cells influenced on VEGF expression. Quantitative analysis of RPE patch morphology and VEGF expression was performed. VEGF levels in each patch were studied as a function of cell number and patch area through time. VEGF expression from various sized patches was quantified following VEGF agonist administration in order to study
the hypothesis that VEGF expression is linked to VEGF auto-regulation in the microenvironment [52, 53] through targeting VEGF [54]. This work complements the experimental studies performed in vitro and provides a framework that can be used to study the influence of cell patterning on the secretion of VEGF by RPE tissue. The model has potential to point toward a path to mimicking the effects of tissue damage or atrophy that occurs in the retina during AMD. This model was applied to study additional mechanism and predict.

1.3.3 Project 3: Bridging the Multiscale Gap: Identifying Cellular Parameters from Multicellular Data

One of the main challenges in the computational modeling of biological systems is identifying values of model parameters. This problem is particularly acute with multiscale models. In this project, we developed an approach that estimates cellular parameters from spatiotemporal data produced from in vitro studies.

We developed a search technique to discover the values of biochemical parameters related to VEGF metabolism. The method began with data available from a multicellular model of retinal pigment epithelial cells. Understanding VEGF regulation is critical in treating AMD and many other diseases. Thousands of simulations were performed as the search method explored the parameter space. For each potential solution, multiple simulations were needed over each experimental case (different patch sizes) and because of the need for repeats due to model stochasticity. The method successfully identifies realistic values for VEGF autoregulatory parameters that reproduce the spatiotemporal in vitro experimental data.

1.4 Research Methodology and Strategies

The using modeling framework is an extension of iDynoMiCS [55], which is a hybrid agent-based modeling framework and originally developed to simulate biofilm development. Two major components of the framework are particles and soluble products, integrated within a reaction diffusion system. Particles, the discrete part of the model, represent individual cells that mechanically interact, secrete, consume or react to soluble products.
Soluble products represent extracellular diffusible biomolecules that make up the continuous component of the system whose distributions are determined by a diffusion solver that resolves all the local changes in concentration induced by the particle secretion and uptake and long-range diffusion.

In Project 1, the DCIS model was executed from an normal duct configuration at model initialization and run to simulate the development of the ductal tumor from initiation to ductal breach and invasion. This model is complex and includes a large number of parameters, including some parameters that cannot yet be measured. First, the known parameters were set from the literature, then the other parameters were estimated and refined by evaluating the ability of the model to recapitulate observed tumor progression. The model was limited to a relatively small numbers of cells due to the large computational demand, and as a result the model was defined over a small domain size as shown in Figure 2.5. Several assumptions were taken into consideration in the design of the model. For example, it was assumed that the ductal tissue has a limited number of fibroblasts that do not grow.

In Project 2, the RPE model was executed from the initial experimental conditions and simulated the *in vitro* model of VEGF metabolism from 1-72 hours. The known parameters were set from the experimental data in [1]. Unknown parameters (VEGF secretion rate of each RPE cell, VEGF binding affinity, and autoregulation strength) were randomly initialized; then they were refined based on the results of the optimization process in Project 3. The ultimate goal of any modeling effort is to provide actionable predictions. Ideally, important experiments that could not be performed *in vitro* could instead be done using the *in silico* approach. For instance, a more realistic model of retinal degeneration is a configuration in which there are cell-free areas in the midst of a largely cell-covered surface of the culture dish. This was modeled using circular patches were the cells are applied to the outside areas and the patches were left empty. This arrangement is the inverse used in the engineered *in vitro* cellular model and it provides a more realistic configuration.
In Project 3, the main objective is to develop a general-purpose techniques for determining the free parameters, error functions, realistic ranges, experimental measurements, search space constraints, and refinement operators. In order to minimize the error and identify likely values for the free-parameters in the model developed in Project 2, thousands of simulations are required. A single execution of the model can take hours, and hundreds of simulations must be run to identify the sensitive parameters, to adjust their ranges and to study model behavior. These computational challenges were taken in consideration, and we used several fast machines (The memory for each machine is 16GB RAM, and the processor is Intel(R) Core(TM) i7-3770K CPU, 3.50GHz (eight CPUs)) to run the experiments 24 hours a day.

1.5 Research Impacts

The work in Project 1 could provide a system with robust predictive modeling and visualization to enable discovery of molecular mechanisms involved in tumorigenesis and metastasis, testing of candidate therapeutics, and more rapid identification of therapeutics against malignancy. In addition, the emphasis on the interaction between biochemical and biomechanical properties in cancer progression may open the door to new treatments that exploit these mechanisms. We believe this model will have higher impacts in the future when this model is integrated with histological clinical and experimental data, such as that being collected in the TCGA project [56,57].

The work in Project 2 complements experimental studies performed in vitro and provides an in silico framework with reliable predictive modeling and visualization to examine the effects of the spatial organization of retinal pigment epithelial (RPE) cells grown in patches of several sizes on VEGF production. It could aid in the development of agents that target VEGF and inhibit angiogenesis, and may be useful in evaluating biomarkers of anti-angiogenic therapies in age-related macular degeneration. This work models the bioengineered multicellular configurations that provide strong experimental controls and customizations to target specific cellular mechanisms.

The multicellular search-based approach introduced in Project 3 is applied to identify
the parameter values of a cellular regulatory mechanism using spatiotemporal multicellular data. This approach was applied to predict the dynamic concentrations of VEGF and other VEGF parameters that are difficult to quantify experimentally. In addition, the results may aid understanding of how uncertainty in the values of particular parameters influence model outputs.
CHAPTER 2
AN AGENT-BASED MODELING APPROACH TO EXPLORE INTERACTIONS OF STROMA AND TUMOR CELLS: THE PROGRESSION OF IN DUCTAL CARCINOMA IN SITU TO INVASIVE DUCTAL CARCINOMA

2.1 Abstract

Invasive ductal carcinoma marks a significant drop in patient survival and is one of the leading causes of death in women. The timing and severity of ductal breach is primarily driven by biochemical and biomechanical mechanisms that interact to weaken duct integrity and induce stress in the duct wall. Understanding the cellular responses to these biomechanical and biochemical stimuli may lead to new therapeutic approaches to breast cancer. We introduce a multicellular agent-based model of ductal carcinoma growth and invasion that considers ductal, stromal and tumor cell types, transforming growth factor beta (TGF-β), matrix metalloproteinases (MMPs), lysyl oxidase (LOX), extracellular matrix (ECM) protein assemblies, including the basement membrane, and that explicitly determines tensional and compressive forces within the developing tissue along with the distributions of and cellular responses to biochemical agents. The model predicts that MMP secretion sufficiently weakens the ductal basement membrane and epithelial tight junctions to undermine ductal integrity and that compressive and tensile stress within the growing tissue contributes to metastasis.

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2.2 Introduction

Breast cancer is one of the main causes of cancer-related deaths in women. Ductal carcinoma \textit{in situ} (DCIS) of the breast is the most common precursor to invasive ductal carcinoma (IDC). Ductal carcinoma \textit{in situ} develops over two to twelve years [42] and is not a life-threatening cancer, but is clinically important because it can be detected and treated before the duct is breached. Clinical studies show that 14%-53% of misdiagnosed DCIS, if left untreated, will progress to invasive cancer [43].

Breast ducts are composed of radial layers of cells and extracellular matrix. Moving from the lumen outwards, these layers are epithelial cells (ECs), basement membrane, and myoepithelial cells (MEs) surrounded by stroma consisting of ECM, fibroblasts, myofibroblasts, and blood vessels (see Figure 2.1a). Figure 2.1 shows the steps in the transition from normal ducts to an invasive carcinoma [4]. DCIS occurs when abnormal epithelial cells begin growing within the duct. These are tumor cells (TCs) and they exert outward biomechanical stress on the ductal system of epithelial cells, myoepithelial cells and the supporting basement membrane and also secrete proteinases which weaken the ductal wall and trigger biomechanical changes in the surrounding stroma.

While the progression from DCIS to IDC is understood in outline, many open questions on DCIS biology remain. How do the mechanical properties of breast tissue contribute to disease progression, compromise treatment or alter metastasis risk? How does inter ductal pressure influence tumor progression, metastasis, and responses to cancer therapy? How are the material properties of breast tissues established and maintained? How do cells adapt to biochemical and biophysical changes that occur during \textit{in situ} tumor growth? Answers to these questions have important implications for clinical practice.

The simulation system developed here may aid in answering these questions. The objective of this paper is to explore the interplay between the buildup and relief of forces within the duct as a tumor grows and as both the cells and ECM change their biophysical properties in response to these forces. The model also considers how biochemical events, such as activation of growth factors and production of enzymes that change the mechanical
properties of the ECM, shape the unfolding biomechanical dynamics of the duct during tumor growth. The emphasis on the interaction between biochemical and biomechanical properties in cancer progression may open the door to new treatments that exploit these mechanisms.

2.3 Background

2.3.1 Previous Models of Ductal Carcinoma in situ

Many of computational approaches and modeling paradigms have been developed to understand and predict the dynamics of DCIS and its transition to IDS. Current computational cancer modeling approaches fall into three main categories: discrete, continuum, or hybrid approaches [37]. Continuum models usually use partial differential equations that are capable of capturing larger-scale systems and provide insight into the relationship among the components of the system. Continuum models can be used for modeling several levels
of biological systems. While a continuum model is relatively quick and easy to implement, it does not capture the discrete nature of systems consisting of individual cells and becomes limited when it is used to model a complex process involving multiple variables [29,30].

On the other hand, in discrete models, individual cells are explicitly represented in space and time. In these models, individual cell behaviors and interactions with other cells and with the environment can be simulated enabling emergent system behaviors and properties. Discrete models are usually limited to relatively small numbers of cells due to a large computational demand, and as a result a typical discrete model is usually designed with low domain size [31, 32]. Two major, related discrete modeling strategies currently exist: Cellular Automata (CA) and Agent-Based Models (ABMs). A typical CA model considers a collection of cells on a grid of specified shape. CA models usually include a finite set of cell states, a regular discrete lattice, a finite set of neighboring cells, and rules for the transition of cell states, such as division, migration, apoptosis, and differentiation as explained [29,33]. In contrast, ABM models represent phenomena as dynamic systems of rule-based interactions among agents and their environment, using discrete-time, and discrete-event modeling methodology [34–37]. ABM and CA modeling approaches are similar in that the behaviors of agents or cells are controlled by their environment or neighborhood, and both are bottom-up modeling approaches, and global system emergent properties and behaviors are generated from local interactions. However, CA models impose a simple quantization space that is unrealistic and limits fidelity, thus the CA modeling approach is weaker in its representation of space [10]. ABMs have recently been more widely used by computational biological and cancer researchers, because of their potential to encompass several scales of biological organization and their robust ability to consider the spatial arrangement of agents.

Even more promising alternative modeling techniques are hybrid models which combine discrete and continuum approaches and take advantage of each approach. Recently, hybrid models have attracted considerable attention due to their success in many biological applications [38–41]. The work reported here applies an agent-based modeling framework
to perform a study into how biomechanical and biochemical processes interact within ductal and stromal cells to trigger DCIS to IDS transition.

Franks et al. [58] described the initial stages of DCIS, where a nutrient-limited growth model was introduced that used Stokes flow to describe the behavior of the tumor cells. They applied numerical and asymptotic methods to examine the shape of the tumor boundary and the extent of tumor cell adhesion to the duct wall in early DCIS. They extended this work in [59] to develop a continuum mathematical model that was used to examine the effects of proteolytic enzyme production on tumor growth and invasion. This model predicts that mechanical stress on the duct wall is the dominant mechanism in the transition of invasive carcinoma.

Sontag and Axelrod [60] combined a population-scale model with machine learning techniques and statistical analyses to describe the progression from DCIS to IDC. Here four signalling pathways were investigated that describe relationships between different grades of DCIS and IDC found in the same patient.

Rejniak and Dillon [61] employed a cell-based technique to make predictions for DCIS morphologies based on differential growth and cell polarity. Their model utilized the immersed boundary method that treats cells as elastic bodies and models the cytoplasm and extracellular matrix as viscous incompressible fluids. They found that the formation of the four specific DCIS morphologies (micropapillary, cribriform, tufting, and solid) result from changes in cell orientation and growth rates.

Figueroedo et al. [62] compared agent-based modeling approaches to approaches that use ordinary differential equations. They considered three case studies using models of immune interactions within early-stage DCIS. They demonstrated that the stochastic elements that are essential components of agent-based models increase fidelity and provide unique insights beyond those of models based on differential equations. Norton et al. [63] developed a 2D model using a lattice-free agent model and conducted an investigation of the relationship among polarised cell adhesion, intraductal pressure, and subsequent DCIS morphology. Kim et al. [64] applied an agent-based model to study interactions among DCIS cells and
stromal cells via TGF-β and EGF soluble factors; their work included the effects of basement membrane expansion. Macklin et al. [65] developed an agent-based cell model and applied it to the process of necrosis in tumor morphology. In this work the first patient-specific calibration method was introduced to help constrain the model based on clinically-accessible histopathology data. Their work illustrated how computational modeling can provide new insights into the biophysical underpinnings of cancer. D’Antonio et al. [66] introduced an agent-based model to simulate the interactions between cells and the basement membrane. They modeled the basement membrane as a linked series of Hookean springs, each with time-varying length, thickness, and spring constant. In this model, each BM spring node exchanges adhesive and repulsive forces with the cell agents. Also, they modeled elastic BM-ECM interactions with analogous ECM springs. They found that varying the balance of BM and ECM elasticity can trigger heterogenous distribution of BM thickness that can lead to ductal breaching.

2.3.2 Key Biological Components involved in Ductal Carcinoma in situ progress

The accumulation of genetic and epigenetic alterations in the ductal epithelium cells accompanied by alterations in the matrix leads to unchecked proliferation and enhanced proliferation of luminal epithelial cells within the ductal tree [67]. With prolonged growth, luminal mammary epithelial cells eventually expand to fill the breast ducts.

Importantly, the abnormal luminal mammary epithelial cells secrete soluble factors including MMPs that diffuse into the stromal matrix. MMPs are a family of zinc- and calcium-dependent proteinases that degrade the collagen of the ECM and stimulate the expression of fibronectin through the activation of transforming growth factor-beta (TGF-β). The TGF-β is released as an inactive latent complex. Latent TGF-β can be activated by metalloproteases MMP-9 and MMP-2, which are often expressed by malignant cells [68], [69].

TGF-β activate resident fibroblasts to differentiate into myofibroblasts which are responsible for the changes in the composition, post-translational modifications and topology of ECM proteins, causing the ECM to stiffen over time. The number of myoepithelial
cells surrounding the abnormal luminal mammary epithelial cells mass decreases and the basement membrane thins, probably owing to increased (MMP) activity, decreased protein deposition, and compromised epithelial tight junctions [70], [71].

In the non-malignant state structural and metabolic proteins are present in the ECM. A subset of ECM proteins are overexpressed in the surrounding stromal matrix during tumorigenesis. ECM remodeling is driven by:

1. The increased levels of (LOX)-dependent ECM cross-linking [72], [73]. LOX is an amine oxidase which catalyzes the conversion of lysine and hydroxylysine residues in collagen molecules to their semi-aldehydes. This is the first step in forming of covalent intra- and intermolecular collagen crosslinks, and the creation of collagen fibrils and fibers to stabilize the mechanical integrity of collagen. Thus, LOX plays an important role in vivo in the stabilization of newly synthesized collagen and the stiffening of ECM [74], [75], [76].

2. Abnormal MMPs expression and function [77], including overexpression of MMP2 in the transformed ECs [78] and MMP3, MMP11, MMP12, and MMP13 in the tumor stroma. The synthesis and degradation of the ECM of the stromal matrix also depends on a balance between another class of MMPs and their tissue inhibitors (TIMPs).

3. Post-translational modifications of ECM proteins including altered deposition of proteoglycans [79], [80].

In this study, to model DCIS progression to IDC, we introduced a multicellular agent-based model of ductal carcinoma growth and invasion in a way that incorporates ductal, stromal and tumor cell types, transforming growth factor beta (TGF-β), matrix metalloproteinase (MMP), lysyl oxidase (LOX), and extracellular matrix (ECM) protein assemblies, including the basement membrane. This model can visualize and predict how perturbation of the local biochemical and biomechanical state influence DCIS evolution.
2.4 Methods

2.4.1 Domain-Independent Agent Based Model

Our modeling framework is an extension of iDynoMiCS [55], a modeling framework that was originally developed to simulate biofilm development. Two major components of our model are particles and soluble products integrated within a reaction diffusion system. Particles, the discrete part of the model, represent individual cells that mechanically interact and secrete, consume or react to soluble products. Soluble products represent extracellular diffusible biomolecules that make up the continuous component of the system. The distribution of the biomolecules is determined by a diffusion solver that resolves all the local changes in concentration induced by cell physiology and diffusion.

Particles

A particle is an incompressible sphere with a mass and set of regulatory components that depends on its type. The particle is positioned in space and occupies the volume of a single cell. Particles grow and mechanically interact with each other through packing constraints, pressure relief, adhesion, chemotaxis and other mechanisms. Signalling among particles is implemented through diffusion. Particles can be specified to represent distinct cell types through assignment of unique reaction-diffusion equations and biomechanical properties such as adhesion. Switching between cell states is possible and is triggered by the properties of the particle’s internal state and external environment.

Particle Dynamics

A configuration of particles represents the spatiotemporal state of the biological system. To update the configuration, the net force acting on each particle is first determined, then the particles are moved based on a force vector that is determined dynamically as the model runs. The mechanical forces acting on a particle ($\sigma_i$) are computed by vector addition of force contributions of each mechanism in play during the simulation, $F_m(\sigma_i, \sigma_j)$ where $i, j$ are indexes to each near-by particle and $m$ is the specific mechanism. Since the particles
are over damped, inertial effects are ignored and particle velocity is proportional to force. A weak stochastic force $\eta$ is added to each particle to model underlying fluctuations in cell movement using a Gaussian distribution with a variance of 0.1; this stochastic movement is essential for reaching cellular configurations of near-minimum energy.

The change in position of an arbitrary particle $\sigma_i$, denoted as $\Delta p(\sigma_i)$ is defined as:

$$\Delta p(\sigma_i) = (\sum_{m \in M} \sum_{j} F_m(\sigma_i, \sigma_j) + \sum_{l \in M} F_l(\sigma_i) + \eta) \Delta t$$  \hspace{1cm} (2.1)

Once forces are generated, a relaxation algorithm is executed to determine the quasi-steady state that minimizes the forces acting on the system. The process continues until the magnitude of particle movement drops below some threshold. The complete particle configuration is asynchronously updated by randomly selecting each particle then applying a small displacement based on equation 2.1 to avoid artifacts.

**Growth and Mass Decay**

Growth reactions lead to changes in the biomass of a particle. As the biomass increases so does the spherical particle volume and radius. When the radius equals or exceeds a maximum type-specific particle size parameter called the split radius $R_{sp}$, the particle is divided in two along a random cleavage plane. Any overlap with neighboring cells is ignored during placement and resolved during force relaxation.

Particle size can reduce through biochemical reactions that consume biomass or lead to decay, particle apoptosis, or necrosis. When the radius equals or falls below the minimum particle size parameter called the death radius ($R_d$), the particle is removed from the domain.

**Pairwise Particle Interaction**

Packing constraints cause particles to exert opposing forces (positive) on each other to minimize spatial overlapping caused by growth or cell movement. The process is illustrated in Figure 2.2. In this work, the opposing force magnitude is directly proportional to the overlap distance between each particle. So
Figure 2.2. Particle Shoving: $R_t(\sigma_i)$ is the radius of a particle of state $t(\sigma_i)$, $\alpha_t$ is the shoving factor for this state $t$ and $d$ is the distance between the objects. When two particles $i$ and $j$ are closer than $\alpha_t(R_t_i - R_t_j)$ then a force is applied to push them apart. For an impregnable boundary, the force is only applied to the particle.

\[
F_{ov}(\sigma_i, \sigma_j) = (\alpha_t|R_t_i + R_t_j| - d(\sigma_i, \sigma_j)), \\

\alpha_t|R_t_i + R_t_j| < \alpha_t|R_t_i + R_t_j| 
\]

where $R_t_i$ is the designated radius of particle $i$ based on its type $t(\sigma_i)$. $\alpha_t$ is termed the shoving factor and it determines the average packing density of particles of size $R_t_i$ and $R_t_j$.

Additionally, nearby particles experience attractive forces due to adhesion and surrounding ECM. This is represented as potential function applied when $d(\sigma_i, \sigma_j)$ is greater than or equal $\alpha_t|R_t_i + R_t_j|$. Initially attractive forces increase from zero then fall off to zero as the particle separate. The potential function in this case is a generalized Morse function [81].

Pairwise particle interactions can be associated or disassociated. Associated interactions model tight junction among cells of the ductal epithelium, the basement membrane, and the extracellular matrix crosslinks. Here the particle’s neighbors are initialized and do not change as particles move, creating a tight mesh that models the basement membrane,
between epithelial cells, and in crosslinked stiff ECM. In contrast, disassociated particles recompute their neighbors at each relaxation iteration before aggregate force calculation. In this way, the attractive forces among disassociated particles drops off as they are separated through movement, enabling displacement and separation by other particles as in the case of growth, invasion, or ductal breach.

**Mechanical Stress Fields**

The particle forces mechanism described above is insufficient for capturing and resolving all the movements in our simulation when ECM stiffens in response to the formation of new cross-links due to LOX or weakens due to MMP. While particle shoving is a local level interaction sufficient to model simple particle growth and division, a global mechanism is needed to compute the movements imposed both by tightly linked particles and by particle shrinkage that occurs in the modeling framework. Mechanical stress fields, increased by cell linking and growth, and decreased by cell shrinkage or death, are used to apply movement vectors to particles move them toward the locations as the stress is relaxed. This pressure, termed “biomass pressure,” is expressed as the following elliptic differential equation [82], [83]:

\[-\nabla \cdot \left( \frac{k}{\mu} \nabla P \right) = \sum_{i=1}^{n} \frac{1}{\rho_i} \frac{dM_i}{dt} \]  

(2.3)

where \( P \) is the pressure generated from the growth or loss of biomass, \( \frac{dM_i}{dt} \) is the local biomass production or loss rate, \( \rho \) is the density, and the summation is iterated over all \( n \) biomass types present in the model. This second order elliptic partial differential equation specifies that the gradient of pressure transport is proportional to rate of volume production or decay at each grid point. This equation is solved in our simulation by a semi-multigrid equation solver to relax the pressure to a quasi stable state. Computing the pressure gradient and applying the movement vectors is performed before applying the shoving.
Extracellular Cellular Matrix

We model the ECM using a hybrid of discrete and continuous models. The discrete component is as an organization of particles interacting with each other as described above. The density, adhesion strength and particle interactions of this group specifies the emergent properties of the formed matrix; particles do not represent the matrix directly, but rather the cross-links between fibers (see Figure 2.3). The density of the links and their pair-wise interaction responses indirectly determine the stiffness of the tissue-scale ECM.

The continuum component of ECM, introduced by Alpkvist et al. [82], models the local secretion and accretion of ECM proteins as a local diffusion process. ECM is secreted from one particle to accrete on a neighboring particle to form fibrious crosslinks (bonds between particles).

ECM degradation occurs when MMPs reduce the stiffness of the ECM, weakening bonds between particles and ultimately causing the particle's disappearance. This process is modeled by reducing the mass of ECM particles proportional to the amount of MMP in the microenvironment, and removing ECM and the associated crosslinks if their mass falls below a threshold [84]. An example of this process is illustrated in Figure 2.4 along with the reciprocal process of ECM stiffening caused by secretion of LOX.

Figure 2.3. Extracellular Matrix formation as crosslinks between ECM particles (spheres in the figure).
Figure 2.4. (a) ECM stiffening viewed over time (earlier to later is left to right). Blue particles are secreting stiffening enzyme (LOX) that increases amount of ECM (spheres) and cross links between ECM particles, causing the ECM to stiffen; (b) ECM degradation. Red particles are secreting MMPs that degrade the surrounding fibers.

2.4.2 Ductal Carcinoma Model

This model incorporates the primary processes in ECM remodeling during the progression of DCIS to IDC described in Section 2.3. Figure 2.5 represents breast duct microarchitecture in cross-section in the initial state of the model. The duct is a tubular arrangement of epithelial cells (pink particles), surrounded by myoepithelial cells (yellow particles) and the basement membrane (small black linked particle forming a tight mesh). The initialing tumor cell (TC) is the single blue particle positioned on the internal duct surface. Surrounding and supporting the duct is the stroma consisting of: ECM (the small light gray particles) that contains fibroblasts (big gray particles) and myofibroblasts (cyan particles). The stroma also contains blood vessels (red particles) that supply the duct with nutrients, oxygen, and growth factors through the basement membrane.

In addition to different cell types, the model includes three diffusible biochemical factors that determine cellular and ECM properties important for DCIS progression. Figure 2.6 illustrates an overview of the model components and their interactions. The model considers two broad spatial domains: the region within the duct that contains epithelial cells and
Figure 2.5. The initial condition of the DCIS to IDC simulation. The duct is a tubular arrangement of epithelial cells, surrounded by basement membrane and myoepithelial cells. The duct is embedded within stroma that includes: ECM, fibroblasts and blood vessels cells. There is a single tumor cell on the internal wall of the duct.

Tumor cells and the stroma that contain the ECM and all other cell types. Tumor cells produce MMPs (many forms of MMP aggregated by the model as a single class) that act on the basement membrane and that can diffuse into the stroma.

In the basal state prior to DCIS, the rate of TGF-β production, a central regulator of normal cell proliferation, is controlled, and ECM stiffening and degradation are in balance. When ductal tumor cells begin to proliferate, they cause activation of latent TGF-β trigger by the increased MMPs production by the tumor cells [68, 85]. The increased activity of TGF-β in the stroma stimulates differentiation of fibroblasts into myofibroblasts (Figure 2.6). Fibroblasts and myofibroblasts produce local ECM components at a constant rate. Additionally, myofibroblasts secrete LOX that stiffens the ECM [86].

In the model, MMPs are degrade the ECM and MMPs are over produced by malignant epithelial cells. MMPs secretion is upregulated by mechanical stress experienced locally by each cell due to the ECM stiffening and tumor growth. The secreted MMP transforms the basement membrane from a tight association with epithelial cells to being dissociated from
epithelial cells. MMPs weaken cross links between the ECM and ECs particles and causes transformation from associated ECs to disassociated ECs. LOX initiates the covalent cross-linking of collagen and the elastin, increasing the tensile strength (stiffness) of the ECM modeled the addition of particle links. The model, we assumed that the LOX is secreted only by myofibroblasts after their differentiation from fibroblasts [87].

In the following model equations, all soluble factors are denoted $S_i$, cell and ECM mass is denoted $M_i$, $D_i$ represents diffusion rate, and $\mu_i$ represents maximum specific rate, where $i$ denotes for cell or particle type. See Table 2.1 for a summary of model parameters.
**Nutrient (oxygen) Secretion**

The model considers that nutrients are secreted by capillary endothelial cells of capillaries ($M_{bc}$) and consumed by tumor cells ($M_{tc}$) based on the following equation:

\[
\frac{\partial S_n}{\partial t} = D_{S_n} \nabla^2 S_n + \mu_{S_n} M_{bc} - \mu_{Scn} M_{tc}
\]  

(2.4)

In this equation, $D_{S_n}$ is the nutrients diffusion coefficient, $\mu_{S_n}$ is the maximum specific rate of nutrients secretion (units of 1/hour), $\mu_{Scn}$ is the maximum specific rate of the nutrient consumption (units of 1/hour), and $M_{tc}$ is the mass of tumor cells.

**Tumor Growth**

The tumor growth is activated by nutrients supplied by blood vessels, and down-regulated by mechanical pressure effects according to Equation 2.5.

\[
\frac{\partial M_{tc}}{\partial t} = \mu_{tc} S_n + \frac{K_{tc}}{S_n + K_n} P + \frac{K_{tc}}{M_{tc}}
\]  

(2.5)

Here, $\mu_{tc}$ is the maximum specific rate of tumor growth (units of 1/hour), and $M_{tc}$ is the mass of tumor cells. Note that pressure down-regulates growth (shown in Figure 2.6).

**MMP Secretion**

The model includes the influence of increasing mechanical stress (represented by pressure $P$) on the up-regulation of MMP secretion as shown in equation 2.6.

\[
\frac{\partial S_m}{\partial t} = D_{S_m} \nabla^2 S_m + \mu_{Sm} \frac{P}{K_m + P} M_{tc}
\]  

(2.6)

Here, $D_{S_m}$ is MMP diffusion coefficient, $P$ is the pressure that affects the cell, $\mu_{Sm}$ is the maximum rate of MMP secretion (units of 1/hour,) and $M_{tc}$ is the mass of the tumor cell.
TGF-β Secretion

TGF-β is a protein that controls cellular proliferation, and differentiation. The TGF-β exists in a latent, ECM-bound form that is converted to an active, diffusible form of TGF-B according to Equation 2.7.

\[ \frac{\partial S_{tg}}{\partial t} = D_{S_{tg}} \nabla^2 S_{tg} + \mu_{Stg} \frac{S_m}{K_{tg} + S_m} M_e \]  (2.7)

Here, \( D_{S_{tg}} \) is the active form TGF-β diffusion coefficient, \( \mu_{Stg} \) is the maximum rate of the TGF-β release (units of 1/hour), and \( M_e \) is the mass of ECM. TGF-β is converted from a latent to an active form when the MMPs concentration exceeds a threshold [68].

LOX Secretion

LOX is an amine oxidase that plays a critical role in the biogenesis of connective tissue matrices by cross-linking, collagen and elastin in the ECM. The LOX is secreted in the stroma by myofibroblasts based on Equation 2.8.

\[ \frac{\partial S_l}{\partial t} = D_{S_l} \nabla^2 S_l + \mu_{Sl} M_{mc} \]  (2.8)

In this equation, \( D_{S_l} \) is the LOX diffusion coefficient, \( \mu_{Sl} \) is the maximum rate of the LOX secretion (units of 1/hour), and \( M_{mc} \) is the mass of myofibroblasts.

ECM Protein Secretion

The model considers that ECM proteins are synthesized by fibroblasts and myofibroblasts according to the following equation:

\[ \frac{\partial S_e}{\partial t} = D_{S_e} \nabla^2 S_e + \mu_{Sem} M_{mc} + \mu_{Sef} M_{fc} \]  (2.9)

Here, \( D_{S_e} \) is the ECM protein diffusion coefficient, \( \mu_{Sem} \) is the maximum secretion rate of ECM protein secretion by myofibroblasts (in units of 1/hour), \( \mu_{Sef} \) is the maximum secretion rate of ECM protein secretion by fibroblasts (units of 1/hour), and \( M_{mc} \) is the mass.
of myofibroblasts, and $M_{fc}$ is the mass of fibroblasts. We assumed that ECM proteins are secreted at constant rate by both myofibroblasts and fibroblasts and that ECM protein secretion rate by myofibroblasts is greater than by fibroblasts.

**ECM Degradation and Accretion**

The ECM is degraded by MMPs based on equation 2.10.

$$\frac{\partial M_e}{\partial t} = -\mu_M e \frac{S_m}{K_m + S_m} M_e + \mu_s e S_e$$

(2.10)

In this equation, $\mu_M$ is the maximum ECM degradation, $M_e$ is the mass of ECM, $S_m$ is the MMP concentration, and $\mu_s e$ is the accretion rate at which the soluble ECM proteins are incorporated into the insoluble ECM.

**Mechanical Stress**

As the right-hand side of Equation 2.3 shows, the changes in the rate of volume increase alter the pressure fields. In the progression of DCIS to IDC, tumor growth, ECM decay, and production and remodeling are the main sources of volume changes. If the right part of Equation 2.3 is rewritten using these terms, new equation can be written that is tailored for this model:

$$- \nabla \cdot (\lambda \nabla P) = \frac{1}{\rho_c} \frac{\partial M_{tc}}{\partial t} + \frac{1}{\rho_e} \frac{\partial M_e}{\partial t}$$

(2.11)

where $\rho_{tc}$ and $\rho_e$ are the spatial density distributions of tumor cells and the ECM, respectively. This equation reflect the activity of the feedback loops seen in Figure 2.6. Cross-linking and cells growth increase pressure while cell shrinkage or death decrease pressure.

Table 2.2 summarizes the reactions in each type of cell and ECM used in the model.
Figure 2.7. The stages from a normal duct into an invasive tumor during simulation. (A) The initial condition for DCIS at iteration 2. (B) The growing tumor triggers the activation of TGF-β that promotes differentiation of fibroblasts into myofibroblasts at iteration 100. (C) Newly differentiated myofibroblasts secrete LOX that begins stiffening the ECM with additional cross-linking and accretion. The ductal wall integrity at the location of tumor initiation has been compromised, but tumor cells are still contained within the duct at iteration 130. (D) The tumor cells have filled the duct, broken through the ductal wall and begun invasion of the surrounding stroma at iteration 180. (E) The duct is so weakened that multiple breaches have occurred and tumor cells have invaded throughout the stroma at iteration 215.

2.5 Results

In this study, we execute the model of the progression of DCIS to IDC, starting from the initial condition of single cancerous cell in a mammary duct as shown in Figure 2.5. Once known parameters were set from the literature (see Table 2.4), the few remaining parameters were estimated and refined by evaluating the ability of the model to recapitulate tumor progression.

Five studies were performed:

1. The fidelity of the tissue-scale behavior of the simulation was evaluated by comparing the sequence of events that emerge in running the model with the sequence of events that unfold in the progression of DCIS to IDC.

2. Interactions that weaken ductal integrity were studied to understand how tumor growth-driven biomechanical stress leads to MMP secretion and subsequent epithelial tight-junction and basement membrane degradation.
3. The effects of stromal stiffening due to TGF-β activation, fibroblast differentiation, LOX secretion and ECM cross linking were explored.

4. The growth of tumor and stromal cells were studied to understand their effect on breach of the duct basement membrane.

5. Micrographs of ductal tissue during progression from DCIS to IDC were compared to the model output.

2.5.1 Emergence of DCIS Progression to IDC Developmental Stages / Emergence Stages of DCIS Progression to IDC

The simulator is initialized at a state of health breast duct microarchitecture, as shown in Figure 2.5. The initial location of the tumor cell is specified randomly. We identify five stages of progression to IDC that occur at iteration 2, 100, 130, 180, and 215 (see Figure 2.7). These are: (A) TCs start growing, consuming nutrients and producing higher amounts of MMP due in response to biomechanical stress, converts TGF-β into active
TGF-β, as shown in Figure 2.7 (A). (B) The active TGF-β within the ECM promotes the differentiation of fibroblasts into myofibroblasts, shown in Figure 2.7 (B). (C) The myofibroblasts begin secreting LOX that in turn induces collagen cross-linking and stiffens ECM, shown as small dark gray particles in Figure 2.7. (D) A feedback loop between the stroma and ECs is formed, where tumor growth combined with the stiffening-ECM heightens the compressive and tensile forces on the duct. The increasing pressure promotes ECs and TCs to secrete yet more MMP to bring the tissue back to homeostasis. The increased MMPs degrade more ECM and weaken the junctions between epithelial cells and basement membrane particles, as shown in Figure 2.7 (D). (E) As a result, the TCs breach the basement membrane and initiate invasion of the surrounding stroma (Figure 2.7 (E)).

2.5.2 Biomechanical Stress and MMP Effects on Ductal Integrity

We monitored the spatial distribution of biomechanical stress (referred to as tissue pressure) and MMP concentration, illustrated in Figure 2.9 A through E. In the early stage of tumor growth, a small amount of MMP is secreted by TCs, while tumor growth produces a local region of pressure centered on the site of tumor initiation. The pressure prompts the TCs to increase their MMPs secretion. The increased MMP weakens the junctions between EC particles and the basement membrane, and degrades the ECM. In addition, the pressure inside the duct builds, causing the TCs to push against the basement membrane. The increased pressure inside the duct, and the weakened junctions between epithelial cells and the basement membrane causes tumor cells to breach the basement membrane and escape within stroma.

The model indicates a significant pressure relief within the duct as multiple breach points occur and tumor cells disperse through the surrounding stromal tissue, as illustrated in Figure 2.9 stage E. This intra-ductal pressure relief is countered by a significant increase in pressure in the surrounding stroma that can lead to increased MMP secretion and subsequent ECM weakening, further promoting invasion.

The pressure and MMP concentration is illustrated in Figure 2.10 at the locations around the duct shown in Figure 2.8. Figure 2.10 illustrates how the evolution of pressure
Figure 2.9. Spatial distributions of pressure and MMP in different simulation iterations (iteration 2, iteration 100, iteration 130, 180, and iteration 215, respectively) along with the corresponding morphology. Red indicates a high value, blue a low value.

and MMP concentration in the surrounding stroma varies by location. We noted that the region near the growing tumor has the highest pressure and MMP concentration where the breach occurs. We observed that the pressure increases at L1 until about iteration 130, when pressure decreases within the duct after release of stress into the stroma due to the breach of duct basement membrane. In contrast, at L2, a stromal location near the breach point, and at L3, a stromal location opposite the break point, the pressure rapidly increases following the breach. The simulation indicates that pressure at breach points is highest, the pressure is relaxed after breach of the basement membrane, and the breach point occurs near the site of the initial tumor cells.
Figure 2.10. Pressure and MMP levels as a function of model iteration in the different locations in the duct given in Figure 2.8.

2.5.3 TGF-β and LOX Effects on Stromal Stiffening

We investigated the biomechanical and biochemical mechanisms that lead to stiffening of the ECM. Figure 2.11 shows the spatial distribution of active TGF-β, which triggers fibroblast-to-myofibroblast differentiation, and the concentration of LOX, which stiffens the ECM. In an early stage, at iteration 2, a high level of active TGF-β appears at the tumor initiation site. This is due to increased MMP secretion. At this early stage, the TGF-β concentration in the ECM is still low and insufficient to prompt fibroblast differentiation. The LOX concentration is also very low since there no myofibroblasts, the source of LOX, in the stroma. By iteration 100, these has been sufficient tumor growth to secret a high amount of MMP. This triggers the conversion of latent TGF-β into active TGF-β. This
active TGF-β triggers the differentiation of fibroblast cells into myofibroblasts in iterations 130. Subsequently, LOX is secreted by myofibroblasts and diffuses into the stroma, crosslinking and thereby a stiffening the ECM. The model indicates that, TGF-β and LOX work to modulate the microenvironment in a way that promotes the early stages of metastasis. Disrupting the cross talk between TGF-B and LOX may offer a target to slow or prevent the DCIS to IDC transition.

Figure 2.12 illustrates TGF-β and LOX concentration at different locations around the duct (see Figure 2.8). The distribution of TGF-β is nearly uniform throughout the stroma due to its high diffusibility. LOX on the other hand has low diffusibility and is mostly locally concentrated around the recently differentiated myofibroblasts. The reduction in LOX around the breach point following the breach event is due to the ECM being displaced.
2.5.4 Cell Population Dynamics

The number of TCs, myofibroblasts, and TCs were monitored over the course of the simulation to understand cell population dynamics in the transition from DCIS to IDC. The upper panel of Figure 2.13 shows the number of tumor cells over the course of the simulation. It illustrates that the number of tumor cells increases exponentially during the initial stages when the cells are confined to the duct. However, as the duct fills and the cells become invasive, the growth rate slows due to increasing stromal pressure. The differentiation of fibroblasts into myofibroblasts takes place relatively quickly and is completed when the duct

Figure 2.12. TGF-$\beta$ and LOX concentrations as a function of iteration in different locations in the duct.

by the invading tumor cells.
Figure 2.13. The number of TCs, myofibroblasts, and TCs outside the duct as a function of iteration.

is filled with TCs.

### 2.5.5 Fidelity of the tumor growth model

We compared the model simulation of the normal non-cancerous breast duct with a micrograph of normal duct, and did a similar comparison at the transition to IDC during ductal breach with an image of this stage in vivo. Figure 2.14 a micrograph of a normal duct with the corresponding initial state of the model. The normal breast duct shown in the micrograph and at the initial stage of the model are very similar.

Figure 2.15 shows the early stage of IDC as the basement membrane is being breached in a mammary duct and as simulated in the model. Once again, at this level of observation,
Figure 2.14. The architectural relationship of the basement membrane, myoepithelial cells, and epithelial cells of ducts in a normal human mammary gland. The left one is micrograph image where the arrow identifies the basement membrane (brown), the arrowhead designates a ME cell (red) [5]. The right one is simulation image where the bold arrow identifies the basement membrane (black) and the thin arrow designates myoepithelial cell (yellow).

the agreement is good between the model and the actual progressing cancer in the mammary duct.

2.6 Conclusions

In summary, we developed a 2D agent-based model of the development of ductal carcinoma in situ and its progression to invasive ductal carcinoma. This model is different from the majority of computational models of breast cancer in its explicit consideration of biomechanical forces in addition to the activities of biochemical agents.
Figure 2.15. Disruption of the myoepithelial cells layer and breach of the basement membrane are prerequisites for invasion. The myoepithelial cell layer and basement membrane in one duct is locally disrupted and the epithelial cells are in direct contact with the stroma (an arrow) [5].

The model supports the idea that the interaction between tumor cells in the duct and the surrounding stroma plays a critical role in tumor growth and invasion of tissues outside the duct. Many mechanical and chemical factors work together to allow invasion. This work may provide a system with a robust predictive modeling and visualization to aid in the discovery of mechanisms of tumorigenesis and the earliest stages of metastasis, and the rapid testing of candidate therapeutics approaches.
### 2.7 Appendix

**Table 2.1. List of parameters symbol description**

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>$M_{mc}$</td>
<td>Biomass of myofibroblasts</td>
</tr>
<tr>
<td>$M_{fc}$</td>
<td>Biomass of fibroblasts</td>
</tr>
<tr>
<td>$M_{tc}$</td>
<td>Biomass of tumor cell</td>
</tr>
<tr>
<td>$M_e$</td>
<td>Biomass of ECM</td>
</tr>
<tr>
<td>$M_{bc}$</td>
<td>Biomass of blood vessels</td>
</tr>
<tr>
<td>$S_n$</td>
<td>Nutrients soluble factor</td>
</tr>
<tr>
<td>$S_m$</td>
<td>MMP soluble factor</td>
</tr>
<tr>
<td>$S_{tg}$</td>
<td>TGF-β soluble factor</td>
</tr>
<tr>
<td>$S_l$</td>
<td>LOX soluble factor</td>
</tr>
<tr>
<td>$S_e$</td>
<td>ECM soluble factor</td>
</tr>
<tr>
<td>$D_{Sc}$</td>
<td>ECM proteins solute diffusion coefficient</td>
</tr>
<tr>
<td>$D_{Sm}$</td>
<td>MMP soluble factor diffusion coefficient</td>
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<tr>
<td>$D_{Sl}$</td>
<td>LOX soluble factor diffusion coefficient</td>
</tr>
<tr>
<td>$D_{Sn}$</td>
<td>Nutrients soluble factor diffusion coefficient</td>
</tr>
<tr>
<td>$D_{Stg}$</td>
<td>TGF-β soluble factor diffusion coefficient</td>
</tr>
<tr>
<td>$\mu_{Scm}$</td>
<td>Maximum specific rate for ECM secretion by myofibroblast</td>
</tr>
<tr>
<td>$\mu_{Scf}$</td>
<td>Maximum specific rate for ECM secretion by fibroblasts</td>
</tr>
<tr>
<td>$\mu_{Sm}$</td>
<td>Maximum specific rate for MMP secretion reaction</td>
</tr>
<tr>
<td>$\mu_{Sl}$</td>
<td>Maximum specific rate for LOX secretion reaction</td>
</tr>
<tr>
<td>$\mu_{Me}$</td>
<td>Maximum specific rate for ECM degradation reaction</td>
</tr>
<tr>
<td>$\mu_{Sn}$</td>
<td>Maximum specific rate for nutrients secretion reaction</td>
</tr>
<tr>
<td>$\mu_{Stg}$</td>
<td>Maximum specific rate for TGF-β secretion reaction</td>
</tr>
<tr>
<td>$\mu_{Mtc}$</td>
<td>Maximum specific rate for tumor cell growth reaction</td>
</tr>
<tr>
<td>$K_S$</td>
<td>half-maximum concentrations parameter where $S$ denoted soluble factor/biomass type</td>
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</table>

**Table 2.2. List of Equations number per cell type**

<table>
<thead>
<tr>
<th>Cell \ ECM Type</th>
<th>Equations number</th>
</tr>
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<tbody>
<tr>
<td>Tumor Cell</td>
<td>2.6, 2.5</td>
</tr>
<tr>
<td>MyoFibroblast</td>
<td>2.8, 2.9</td>
</tr>
<tr>
<td>Fibroblasts</td>
<td>2.9</td>
</tr>
<tr>
<td>Blood Vessel</td>
<td>2.4</td>
</tr>
<tr>
<td>ECM</td>
<td>2.10, 2.7</td>
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Table 2.3. List of soluble factor per cell type

<table>
<thead>
<tr>
<th>Secreted soluble Factor</th>
<th>Variables</th>
</tr>
</thead>
<tbody>
<tr>
<td>MMP</td>
<td>$S_m$</td>
</tr>
<tr>
<td>LOX</td>
<td>$S_i$</td>
</tr>
<tr>
<td>Continuous ECM protein</td>
<td>$S_e$</td>
</tr>
<tr>
<td>Nutrients</td>
<td>$S_n$</td>
</tr>
<tr>
<td>TGF-β</td>
<td>$S_{tg}$</td>
</tr>
</tbody>
</table>

Table 2.4. *In Vitro* Parameters for DCIS Model

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Explanation</th>
<th>Value</th>
<th>Refs.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Epithelial cell radius</td>
<td>0.5</td>
<td></td>
<td>63</td>
</tr>
<tr>
<td>Myoepithelial cell radius</td>
<td>0.25</td>
<td></td>
<td>63</td>
</tr>
<tr>
<td>Tumor Cell Radius</td>
<td>9.953 um</td>
<td></td>
<td>65</td>
</tr>
<tr>
<td>Production rate of TGF-β from TCs</td>
<td>$1.72 \times 10^{-9} \text{s}^{-1}$</td>
<td></td>
<td>88</td>
</tr>
<tr>
<td>TGF-β Diffusion Coefficient</td>
<td>$1.8 \times 10^{-7} \text{cm}^2 \text{s}^{-1}$</td>
<td></td>
<td>89</td>
</tr>
<tr>
<td>Oxygen Diffusion Coefficient</td>
<td>$1.55 \times 10^{-4} \text{m}^2 \text{day}^{-1}$</td>
<td></td>
<td>64</td>
</tr>
<tr>
<td>MMP Diffusion Coefficient</td>
<td>$1 \times 10^{-6} \text{cm}^2 \text{s}^{-1}$</td>
<td></td>
<td>64</td>
</tr>
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</table>
CHAPTER 3
DEVELOPING AN IN SILICO MODEL TO STUDY THE EFFECT OF RETINAL PIGMENT EPITHELIAL CELL PATCH SIZE ON VEGF PRODUCTION

3.1 Abstract

The spatial organization and growth of retinal pigment epithelial (RPE) cells is a vital process in the progress of age-related macular degeneration (AMD). While in vitro experiments provide models for replicating disease states associated with the deterioration of retinal tissue during AMD, the progression and behaviors of RPE cells in AMD and the stimuli leading to the enhanced secretion of the central driver of AMD progression, vascular endothelial growth factor (VEGF) from RPE cells are not fully understood. In addition, in vitro culture methods are generally expensive and time-consuming. In this study, an in silico model was developed to provide a framework used for understanding the underlying mechanism of VEGF production, predicting the VEGF produced by each cell in colonies (patches) of different sizes, and analyzing the effect of a VEGF agonist. We also present experimental validation of the simulated results and predict the spatial distribution of VEGF produced by cells in different sized patches. This model may provide a system with robust predictive modeling and visualization that could enable discovery of the molecular mechanisms involved in AMD progression and provide routes to the development of effective treatments.

The coauthors for this chapter are: Qanita Bani Baker, Gregory J. Podgorski, Elizabeth Vargis, and Nicholas S. Flann
3.2 Introduction

Age-related macular degeneration (AMD) is a leading cause of irreversible blindness, particularly among adults over age 50 [44,45,90]. Degeneration of retinal pigment epithelial (RPE) cells severely damages the visual function of retina photoreceptors. In AMD, new blood vessels from the underlying choriocapillaris disruptively invades the retina [91]. Vascular Endothelial Growth Factor (VEGF) is the primary growth factor in angiogenesis [92] and an important biomarker of AMD [93]. In the retina, VEGF is secreted in the RPE and is mainly responsible for retinal vasculature development [94,95]. In vitro models that allow controlling the spatial organization and growth of RPE cells can provide important tools for understanding cell behavior in AMD processes. Monitoring the expression of VEGF within the controlled environments of these model systems can lead to new insights that improve our understanding of how AMD is initiated and developed over time.

In the cell culture model of AMD that is the focus of this work, micropatterning techniques are used to restrict the location and shape of the substrate regions on which cells attach [96–98]. The impact of micropatterning on cellular functions and morphologies has been investigated with many types of cells including fibroblasts [99], neuronal cells [100], retinal pigment epithelial cells [1,101–104], stem cells [105], epithelial cells [106], and cancer cells [107]. Vargis et al. [1] used micropatterned surfaces to control the spatial organization of RPE cells in Figure 3.1 to explore how atrophy, loss-of-function, or tissue damage within the retina affect VEGF production. While cell culture provides a model for replicating disease states associated with the deterioration of retinal tissue during AMD, the stimuli leading to enhanced VEGF secreted from RPE cells and the subsequent neovascularization processes in the choroid are still not fully understood [48,49], and little is known about the VEGF regulation in the eye [95]. In addition, little is known about the drugs’ mechanisms of action, how and why several diseases such as AMD become resistant to the treatment, or the types of patients that can benefit most from these drugs [108]. Computational approaches combined with in vitro experimental studies can shed light on these issues by providing a framework for generating and testing hypotheses related to VEGF regulation and transport.
Figure 3.1. Micropatterning method used in [1]. Substrate functionalization and cell seeding are accomplished by molding a PDMS stamp from an etched silicon master as in steps (a, and b). Then, the stamp is inked using a fibronectin solution, allowed to dry and then placed in contact with a polystyrene or glass culture dish as in steps (c-f). After that, the surface is blocked with Pluronic prior to seeding RPE cells onto the fibronectin-patterned substrate as in steps (g, and h).

in the tissue retina [109].

Developing an in silico framework for the in vitro cell patterning model provides a system that could be extremely useful in evaluating the temporal-spatial effects of VEGF transport and expression within these controlled environments, and in replicating the disease state to gain new insights on disease progression and outcomes. It also can be used to study internal and external regulatory mechanisms influenced by feedback from the evolving cellular environment. Developing this predictive model is essential to improve understanding and generate new hypotheses that may be used in the development of pharmaceutical agents.
The goal of this study was to develop an \textit{in silico} model to replicate and extend cell microprinting model for AMD reported in [1]. Using this model, we studied the growth of RPE cells in discrete patches and measure the effect of patch size on VEGF expression. The VEGF level in each patch is studied as a function of cell number and patch area over time. To study the hypothesis that VEGF expression is linked to global VEGF concentration in culture, VEGF expression from various size patches was quantified following VEGF agonist administration. This study complements experiments performed \textit{in vitro} and provides a framework that can be used to study the influence of cell patterning on the secretion of VEGF by the RPE tissue, and opens a path towards mimicking the effects of tissue damage or atrophy in tissue engineering. This model is applied to extend the study of Vargis et al [1] and to make new predictions. The \textit{in silico} model may be used to examine the effects of anti-VEGF agents that potentially can aid in the optimization of anti-angiogenic therapeutics.

3.3 Materials and Methods

3.3.1 \textit{In vitro} methods

The bioengineered micropatterning techniques are used to create a regular arrangement of circular colonies, called patches, populated with RPE cells surrounded by a empty substrate as shown in [1]. Creation of this micropatterns involves multiple sequential steps as shown in Figure 3.1. The non-populated regions imitate necrotic regions in the retina that result from repeated exposure to reactive oxidative species, triggering death of the retinal pigment epithelium followed by death of the overlying photoreceptors and neovascularization, leading exudative AMD [50, 51]. Recreating these regular spatially-organized cellular configurations helps to isolate the impact that local cell-cell and cell-environment interactions have on VEGF expression.

In the experimental study, described in [1], stamps with patches of 100 $\mu$m, 200 $\mu$m, 300 $\mu$m, and 400 $\mu$m were employed to vary the mix of cell-cell and cell-environment in each experiment. Each patch was seeded with retinal pigment epithelial cells and grown in
a cellular culture. VEGF per cell was measured at regular intervals: 4, 24, 30, 48, 54, and 72 h after cells seeding and reported in pg/ml. To measure the VEGF per cell, the total VEGF contained within the cell culture was determined using enzyme-linked immunosorbent assay (human VEGF ELISA kit), and the number of cells per patch was determined using image analysis proceeded by staining. Figure 4.1(a) (taken from [1]) illustrates the stained patches at 72 h. The experiments were repeated at least ten times and averaged. The final spatial-temporal data obtained are illustrated in Figure 4.1(b). The final spatial-temporal data obtained after adding the VEGF agonist are illustrated in Figure 4.1(c).

A VEGF agonist was also added to the patterned surfaces at a concentration of 5 ng/mL after 20 h in culture, in order to determine if the higher levels of VEGF expression observed in cells grown in small patches was the result of cells responding to lower initial overall levels of VEGF in the RPE microenvironment. VEGF expression was also measured before the addition of the VEGF agonist (at 4 h) and after the addition at (24, 30, 48, 54, and 72 h). The final spatial-temporal data produced are illustrated in Figure 4.1(c).

3.3.2 Hybrid Agent-Based Model Framework

*In silico* computer-based modeling has proved its effectiveness in several biological research studies [110]. *In silico* models, especially agent-cell-based models, can bridge *in vitro* and *in vivo* experiments since they can integrate measurements from several *in vitro* experiments, reconstruct certain aspects of *in vivo* environments, and provide the capabilities for a systematic analysis of the influence of individual as well as combined factors on full-scale biological system behavior [111]. To simulate the RPE cell growth in several patch sizes, we extend the agent-based modeling framework developed by the Kreft group at University of Birmingham, called iDynoMiCs [55].

In this framework, we have two main components: particles and soluble products, integrated within a reaction diffusion system. Particles represent individual cells that mechanically interact, secrete, consume or react to soluble products. They are positioned in space and occupy the volume of a single cell. Soluble product distributions make up the continuous component of the system and are determined by a diffusion solver which resolves
Figure 3.2. The result as shown in the experiments performed by Vargis et al. in [1] (a) Patches of stained RPE cells at 72 h for each patch size. [1]. (b) Time course of VEGF expression per cell measured at 4, 24, 30, 48, and 72 h as in [1]. (c) Time course of VEGF expression per cell measured before the addition of the VEGF agonist (at 4 h) and after (24, 30, 48, 54, 72 h) [1].

all the local changes in concentration induced by the particle and long range diffusion. In the simulation, it is assumed that the soluble product fields are in steady-state with respect to cell mechanisms since solute reaction and diffusion occur on the order of seconds, while cell mechanisms occur on the order of hours to days.

Reactions drive growth to increase the biomass of a particle. As the biomass increases so does the particle radius, based on the cubic root of the volume. When the radius equals or exceeds a maximum state-specific particle size parameter called the split radius $R_{sp}$ in
units $\mu m$, the particle is divided into two particles along a random cleavage plane, such that the sum of the volumes of the new particles approximately equals the specified maximum volume. The two smaller particles are positioned without mutual overlap in the place of the parent particle. Any overlap with neighboring cells is ignored during placement and resolved during force relaxation. Particle size can be reduced through biochemical reactions that cause biomass consumption, decay, particle apoptosis, or necrosis. When the radius equals or falls below the minimum particle size parameter, called the death radius $R_d$ in units $\mu m$, the particle is removed from the domain. This framework is explained in more detail in the Supporting Information section.

In this model, it is assumed that the boundary conditions are cyclic for the sides of the 2D domain. Cyclic boundaries allow simulation of larger domains by assuming that the computation domain region is replicated indefinitely. The two connected boundaries are specified together when creating cyclic boundary conditions. Solute concentrations are kept constant across cyclic boundaries, and any agent crossing one of the cyclic boundaries will be instantly moved to the connected boundary.

### 3.3.3 In silico model for RPE growth in several in vitro patch sizes

The bioengineered experiments are simulated using the hybrid agent-based approach. The setup of the simulations replicates the same experimental conditions and units as in the in vitro experiments. The domain size of each simulation is 2400 $\mu m$, initial cell size is set to 80$\mu m^2$, and 36 h is the doubling time due to growth. Each simulation begins with multiple RPE cells distributed at the reported patterning efficiency (cell density) in several patches arranged in the specific experimental pattern. The simulation replicates the first 72 h of the in vitro experiments. The initial conditions for different patches are shown in Figure 3.3. Illustrations of the simulated experiments, after 72 h, are shown in Figure 4.2.

The autoregulation of VEGF secretion as a function of biomass $M$ and local VEGF concentration $V$ is described using Equation 4.1. The diffusion coefficient of VEGF $D_V$ is set to $5.8 \times 10^{-11} m^2 s^{-1}$, taken from microfluidic experiments described in [112]. As shown from this Equation 4.1, VEGF expression is auto-regulated by negative feedback inhibition
Table 3.1. Initial Number of Cells in Each Patch based on [1]

<table>
<thead>
<tr>
<th>PatchSize</th>
<th>Initial Number of Cells</th>
</tr>
</thead>
<tbody>
<tr>
<td>Patch 100</td>
<td>15 Cells</td>
</tr>
<tr>
<td>Patch 200</td>
<td>74 Cells</td>
</tr>
<tr>
<td>Patch 300</td>
<td>189 Cells</td>
</tr>
<tr>
<td>Patch 400</td>
<td>351 Cells</td>
</tr>
<tr>
<td>Patch 500</td>
<td>612 Cells</td>
</tr>
</tbody>
</table>

Figure 3.3. Patch arrangement in the simulation. (A) Patch 100 µm, 12 patches in each side. (B) Patch 200 µm, 6 patches in each side. (C) Patch 300 µm, 4 patches in each side. (D) Patch 400 µm, 3 patches in each side.

loop via the amount of VEGF in the surrounding domain.

\[
\frac{\partial V}{\partial t} = D_V \nabla^2 V + \alpha_V \frac{K}{\beta V + K} M \tag{3.1}
\]

The equation after adding VEGF agonist will be as in Equation 3.2. This equation assumed that the receptor singling for VEGF is the same for VRGF agonist. This suggest that the cell may function to maintain a consistent level of VEGF and VEGF agonist within their local environment.

\[
\frac{\partial V}{\partial t} = D_{(V+V_a)} \nabla^2 V + \alpha_V \frac{K}{\beta(V+V_a) + K} M \tag{3.2}
\]
Over time, the RPE cells grow based on a doubling time of 36 h [113], which determines the growth rate parameter $\mu_M$. Since nutrient is unlimited and cell crowding is not an issue within the 72 hour time line, we applied first order kinetics reaction for cell growth as shown in Equation 4.2.

$$\frac{\partial M}{\partial t} = \mu_M M$$ (3.3)

Table 3.2 summarizes the description of the parameters used in the equations above and identifies the known parameters and those that need to be determined by the method developed in Chapter 4.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
<th>Description</th>
<th>Ref</th>
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<tbody>
<tr>
<td>$D_V$</td>
<td>$5.8 \times 10^{-11} \text{m}^2\text{s}^{-1}$</td>
<td>Diffusion coefficient</td>
<td>[112]</td>
</tr>
<tr>
<td>$\mu_M$</td>
<td>1.0194 hour$^{-1}$</td>
<td>Max. growth rate for RPE cells</td>
<td>[113]</td>
</tr>
<tr>
<td>$K$</td>
<td>0.13</td>
<td>Auto regulation rate</td>
<td>Chapter 4</td>
</tr>
<tr>
<td>$\mu_V$</td>
<td>0.09</td>
<td>Secretion rate</td>
<td>Chapter 4</td>
</tr>
<tr>
<td>$\beta$</td>
<td>0.850</td>
<td>Binding affinity</td>
<td>Chapter 4</td>
</tr>
<tr>
<td>$R_{sp}$</td>
<td>6.2996 $\mu$m</td>
<td>Cell Division Radius</td>
<td>[1]</td>
</tr>
</tbody>
</table>

### 3.4 Results

In this study, we utilized the hybrid agent-based framework to model RPE cell growth within different patches size setups. The *in silico* model was executed from the initial condition, shown in Figure 3.3, and assessed the simulated changes from the first hour to the end of the experiments at hour 72. In this section, using the developed *in silico* model, the VEGF concentration per cell was measured at various time intervals and after adding a VEGF agonist to the patterned surfaces with several sizes. The visualization of VEGF distribution in different patch sizes was also reported. This framework was also applied to study a more realistic model of retinal degeneration when open areas with no living cells develop in the retinal endothelium. Additionally, we used this model to study the effect of VEGF agonist concentration on the final VEGF concentration per cell. Here, the concentration of VEGF per cell was measured after adding several VEGF agonist concentrations
VEGF concentration per cell

The total VEGF expression in the simulation was first calculated for each domain after 72 h and was reported as VEGF concentration per cell as shown in Figure 3.4 (b). In these studies, the VEGF concentration per cell is inversely proportional to the patch size, i.e. RPE cells in the smaller patches express higher levels of VEGF per cell. To validate the in silico model, we compared the simulation results with the in vitro data from [1]. In both, 3.4 (a) and 3.4 (b), it is noted that the RPE cells in small patches express higher levels of VEGF per cell. This indicates that these cells are auto-regulated VEGF to maintain a consistent level of VEGF within their local microenvironment. Cells in smaller patches respond by expressing higher amounts of VEGF to maintain basal VEGF levels, while RPE cells in larger patches maintain the same basal levels of VEGF by expressing smaller amounts of VEGF per cell.

To show how the concentration of VEGF changes over time in the simulation, VEGF expression levels were also calculated at various time intervals (4, 24, 30, 48, 54, and 72 h) and reported as VEGF concentration per cell. As shown in Figure 3.5 (b), the level of VEGF increased over time. At hour 4, VEGF concentration per cell was approximately...
Figure 3.5. Comparing the time course of VEGF expression per cell measured at 4, 24, 30, 48, and 72 h, different patch sizes (100 µm, 200 µm, 300 µm, and 400 µm), \textit{in vitro} and in simulation. (a) The left graph represents the data obtained \textit{in vitro} from [1]. (b) The right graph represents the data obtained from the simulation.

the same for all patch sizes. However, significant differences were observed after hour 48, where smaller patches produced a higher amount of VEGF than larger patches. In both 3.4 (a) and 3.4 (B), it is noted that the RPE cells in small patches expressed higher levels of VEGF per cell than the larger patches. This confirms that cells growing in small patches may experience different local concentrations of VEGF compared to cells in larger patches.

\textbf{VEGF concentration per cell with VEGF agonist}

To determine if the higher levels of VEGF expression observed in cells grown in small patches are the result of cells responding to lower initial overall levels of VEGF in the RPE cells microenvironment, the VEGF agonist was added to the patches 20 h after the initial cell seeding, at a concentration of 5 ng/ml based in both \textit{in vitro} experiments and \textit{in silico} simulations. In the \textit{in silico} VEGF agonist $V_a$ is auto-regulated based on Equation 3.2. Then the concentration of VEGF per cell after the addition of the VEGF agonist was calculated at the same intervals as previous experiments and reported as the change in VEGF expression per cell for each patch size.

In both the \textit{in vitro} and \textit{in silico}, as shown in 3.6 (a) and 3.6 (b), respectively, adding the VEGF agonist effectively increased the amount of VEGF detected by the cultured cells in each sample. In both the \textit{in vitro} culture and the simulation, the VEGF levels per cell
Figure 3.6. *In vitro* and simulated effects of the VEGF agonist addition on VEGF expression. The agonist was added after 20 h of culture. (a) Data obtained *in vitro*. (b) Results of the simulation.

obtained from smaller patch sizes (100, 200, 300 µm) decreased after the VEGF agonist was added. This confirms the hypothesis that cells within these smaller patches reduce VEGF expression levels because of the increased levels of VEGF detected within their local environment. The patches of larger sizes (400 µm) were already exposed to higher levels of VEGF; hence they showed small changes in expression levels after the addition the VEGF agonist.

**VEGF Distribution**

Using the *in silico* model, we monitored the spatial distribution of VEGF in the different patches. Simultaneous VEGF concentration profile is evolved using the *in silico* models. Figure 3.7 shows the VEGF distribution profile in 2400 µm X 2400 µm area for different patch sizes 100 µm, 200 µm, 300 µm, and 400 µm). This insight gained by the model observations, cannot be made experimentally either through *in vitro* or *in vivo* models.

The results indicate that VEGF distribution in tissues increased gradually over a specific period. This also suggest that patterning efficiency and detailed quantitative distribution of VEGF could be another factors that are worth to study their effects in the disease progression.
Figure 3.7. Simultaneous evolution of the VEGF distribution profile in 2400 micrometers area for different patches size.

**Prediction**

The ultimate goal of any modeling effort is to provide actionable predictions [34]. Ideally, important experiments that could not be performed *in vitro* could instead be done using the developed *in silico* approach. For instance, a more realistic model of retinal degeneration is one in which open areas with no living cells develop in the retinal endothelium. This can be modeled using a similar arrangement of patches, but where the cells are applied to the areas outside of the disks, which are left empty. The inverse distributions of the cells (where cells is located outside the patches and all patches are empty) were modeled and the effects of different sizes patches were simulated and studied through the developed
To show how the concentration of VEGF changes over time in the simulation with inverse distributions setup, VEGF expression levels were also calculated at various time intervals (4, 24, 30, 48, 54, and 72 h) and reported as VEGF concentration per cell as shown in Figure 3.10. The results got from this experiments suggest that this inverse setup is not so informative, since the several patches’ sizes do not play a critical role in such distribution.

3.5 Discussion

This study offers an in silico model that utilized a hybrid agent based framework to model bioengineering in vitro experiments. The coupling between in silico models and bioengineering laboratory works provide an effective strategy for mechanistic understanding of mechanisms and interaction using spatial-temporal data. This coupling could help in identifying key regulating parameters of the laboratory process and predicting the early information in order to assess the systems’ and processes’ behaviors. We argue that using a hybrid agent based framework for such system is adequate, since this framework is implicitly include the spatiotemporal locality effects within the cell, or cell-cell interactions.

In vitro experiments provide a model for replicating disease states associated with the deterioration of retinal tissue during age-related macular degeneration (AMD). To quantitatively interpret such experimental results, an in silico model can be beneficial and predictive. In this study, in silico model was developed in order to replicate the in vitro experiments in [1]. The setups of the in silico model imitate the same experimental conditions and units as described in the in vitro works and predict the VEGF concentrations per cell in several spatiotemporal conditions. The results obtained from the in silico model confirm that the RPE cells in small patches expressed higher levels of VEGF per cell. This suggests that these cells may function to maintain a consistent level of VEGF within their local microenvironment. Additionally, cells in smaller patches respond by expressing higher amounts of VEGF to maintain VEGF levels. RPE cells in larger patches can maintain the same levels of VEGF by expressing smaller amounts of VEGF per cell.
Figure 3.8. (a) Closeup of initial condition of a 400 µm patch (b) Experiment with 400 µm, 3 patches in each side. (c) Closeup of the VEGF distribution after 72 h, (d) VEGF distribution over whole domain after 72 h.

The developed *in silico* model is quantitatively validated based on the available experimental data. The model can provide quantitative interpretation of the *in vitro* data and may be used in predicking the effects of further spatial cells distribution conditions. In future work, we suggest to use a searching approach to find the patches organization
Figure 3.9. Patch arrangement in the simulation. (A) Patch 100 µm, 12 patches in each side. (B) Patch 200 µm, 6 patches in each side. (C) Patch 300 µm, 4 patches in each side. (D) Patch 400 µm, 3 patches in each side.

Figure 3.10. VEGF expression per cell measured at 4, 24, 30, 48, and 72 h from the simulation in inverse distributions of the cells as shown in Figure 3.9.

that identify the most informative configuration. This search will identify several spatial cell organizations that may effectively mimic the effect of atrophy and loss-of-function that occurs in the retina during degenerative diseases. The model can be utilized to guide the laboratory towards the most informative experiments.
CHAPTER 4
BRIDGING THE MULTISCALE GAP: IDENTIFYING CELLULAR PARAMETERS FROM MULTICELLULAR DATA

4.1 Abstract

Multiscale models that link sub-cellular, cellular and multicellular components offer powerful insights in disease development. Such models need a realistic set of parameters to represent the physical and chemical mechanisms at the sub-cellular and cellular levels to produce high fidelity multicellular outcomes. However, determining correct values for some of the parameters is often difficult and expensive using high-throughput microfluidic approaches. This work presents an alternative approach that estimates cellular parameters from spatiotemporal data produced from bioengineered multicellular in vitro experiments. Specifically, we apply a search technique to an integrated cellular and multicellular model of retinal pigment epithelial (RPE) cells to estimate the binding rate and auto-regulation rate of vascular endothelial growth factor (VEGF). Understanding VEGF regulation is critical in treating age-related macular degeneration and many other diseases. The method successfully identifies realistic values for autoregulatory cellular parameters that reproduce the spatiotemporal in vitro experimental data.

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The coauthors for this chapter are: Qanita Bani Baker, Gregory J. Podgorski, Christopher D. Johnson, Elizabeth Vargis, and Nicholas S. Flann
4.2 Introduction

An important aspect of computational systems biology is the investigation of dynamic biological processes that operate across multiple temporal and spatial scales by constructing and running multiscale models [2], [10], [15], [114], [115]. These models incorporate a set of parameters that represent the physical and chemical properties of the biological system [116]. The parameters are used to define the components of the models that when simulated reproduce the behavior of the biological system. Often the correct values of these parameters are unknown or difficult to obtain [117], [118].

Recently, there has been an increase in the number of model-fitting methods proposed to estimate model parameters’ values [119], [120], [121] from experimental data. Without accurate estimations of parameters, predictions from simulation studies will most likely be erroneous and provide little scientific insight and guidance in disease treatment [122]. This scenario can be ameliorated by fitting the model to experimental in vitro / in vivo data [123] [124]. Finding the best-fit values for the unknown parameters enhances the possibility of performing accurate quantitative predictions.

Vascular endothelial growth factor (VEGF) is a key promoter of angiogenesis and vascular development and is the target in numerous anti-angiogenic therapies [125]. Angiogenesis is the growth of blood vessels from the preexisting vasculature, a process involved in the physiological functions of several diseases, such as cancer and age-related macular degeneration (AMD). Moreover, in spite of substantial basic science and translational research to develop anti-angiogenic therapies, many questions remain about the mechanisms of action of angiogenic drugs, how and why several diseases such as AMD become resistant to the treatment, or the patient conditions that can benefit most from these drugs [108]. For these reasons, computational models of angiogenesis have been developed to simulate the process and provide a framework for generating and testing hypotheses of VEGF-driven processes [109,126,127]. Models have aided in the development of novel and effective anti-angiogenic therapeutics that target VEGF regulation and receptors [116], [128,129]. Advancing these computational approaches combined with progress in in vitro experimental
studies will shed light on these issues by providing an effective framework for generating and testing hypotheses related to VEGF regulation and transport in the tissue [109].

An essential mechanism for understanding VEGF’s role in disease development is its auto-regulation. The rate of VEGF secretion is controlled through an auto-inhibitory regulatory mechanism where the VEGF concentration of a cell’s microenvironment down-regulates the secretion of VEGF. This control loop enables a community of cells to maintain a stable background concentration of VEGF [130]. Disruption of the loop is implicated in multiple disease states.

This paper presents a method for accurately characterizing this auto-regulation, not from microfluidic assays that interrogate individual or mixed cell populations but from spatially organized multicellular experimental data sampled over time. As will be explained later, spatiotemporal data provides unique insights because auto-regulation is inherently a mechanism that is manifested over space and time. The rest of the paper is structured as follows: First the experimental setup and computational model is described, along with the specific autoregulatory parameters that are known and those to be estimated. Second, the search method for finding the values for the parameters is described in detail. Next the method is evaluated by validating the identified parameter values. Finally, a summary of the method’s effectiveness and suggestions for future work are given.

4.3 Multicellular Experiment and Model

The experiment from which the unknown parameter values are derived employs bioengineered micropatterning techniques. The micropatterns form a regular arrangement of circular 2D patches populated with cells surrounded by an exposed substrate. The exposed regions emulate necrotic areas of the retinal tissue that result from repeated exposure to reactive oxidative species, triggering neovascularization and exudative AMD [50]. Recreating these regular spatially organized cellular configurations is essential to understanding the impact of local cell-cell and cell-environment interactions on VEGF autoregulation.

In the experimental study, described in [1], the bioengineered circular micro patterns were employed to control the extent of cell-cell interactions, which occur within the patch,
and cell-environment interactions, which occur at the perimeter. Several patch sizes were used in this study (100 µm, 200 µm, 300 µm, and 400 µm) to sample the proportion of cell-cell and cell-environment interactions in each experiment. Such sampling constrains the possible parameter values. Each patch was seeded with retinal pigment epithelial (RPE) cells and grown in a cellular culture. As the cells grew, the VEGF per cell was measured at regular intervals: 4, 24, 30 48, 54, 72 h. To measure the VEGF per cell, enzyme-linked immunosorbent assay (ELISA) was used to determine the total VEGF contained within the cell culture, and the number of cells per patch was determined by image analysis proceeded by staining. Figure 4.1(a) (taken from [1]) illustrates the stained patches at 72 hours. Experiments were repeated ten times and averaged. The final spatiotemporal data produced is illustrated in Figure 4.1(b) and forms the target prediction for the computational model simulation.

The bioengineered experiments were simulated using a hybrid agent-based approach, which is an extension of iDynoMiCs framework developed by the Kreft group at University of Birmingham [55]. This model was selected because of its extensibility and easy of use. All inputs to the model such as parameter values and initial condition are easily specified using an XML document called the protocol file. Hybrid models integrate discrete components to represent the cells and continuous equations to represent biochemical reactions and diffusion. Each cell is a spherical particle that grows by consuming nutrient and accumulating biomass volume; when the volume exceeds twice the initial volume, cell division is simulated by splitting the particle into two. Particles can secrete and uptake soluble biochemicals (such as VEGF) which diffuse through the domain; regulatory reactions that model interactions among intracellular and inter-cellular proteins become PDEs. The simulation interlaces cellular growth and movement (implemented by relaxing forces between particles) with biochemical redistribution (implemented by solving the PDEs). Random noise disrupts cellular movement and the division volume to represent the inherent stochasticity of the biological processes.

The setup of the simulations replicate the experimental conditions and units of the
in vitro experiments. The 2D domain size of each simulation is $2400\mu m$ by $2400\mu m$, initial cell size is set to $80\mu m^2$ and the doubling time due to growth is set at 36 hours. Each simulation begins with multiple RPE cells distributed randomly at the same density and with the patch pattern. The simulation replicates the first 72 hours of the in vitro experiments. Illustrations of the simulated experiments are shown in Figure 4.2.

This framework is inherently multiscale in that the parameters that control the low-level mechanisms at the cellular level, e.g., growth, the VEGF secretion rate and autoregulation, determine the cell population and VEGF concentration over the complete multicellular domain. Figure 4.2 illustrate the VEGF distributions in the domain. To compute the VEGF concentration per cell, the total VEGF is computed over the whole domain, while the number of cells is directly determined by the simulator. This approach intrinsically includes the quantitative spatiotemporal control effects as the cells grow, secret VEGF which diffuses over the domain. Moreover, the simulations provide insight into the spatial VEGF gradients within and between patches, unavailable in in vitro studies.

The autoregulation of VEGF secretion is described in Equation 4.1 as a function of biomass $M$ and local VEGF concentration $V$. The diffusion coefficient of VEGF, $D_V$, is set to $5.8 \times 10^{-11} m^2 s^{-1}$ given in microfluidic experiments from [112].

$$\frac{\partial V}{\partial t} = D_V \nabla^2 V + \mu_V \frac{K}{\beta V + K} M$$  \hspace{1cm} (4.1)

Over time, the RPE cells grow based on a doubling time of 36 hours [113], which determines the growth rate parameter $\mu_M$. Since nutrient is unlimited and cell crowding is not an issue within the 72 hour time line, we applied first order kinetics for cell growth as shown in Equation 4.2.

$$\frac{\partial M}{\partial t} = \mu_M M$$  \hspace{1cm} (4.2)

Table 4.1 summarizes the description of the parameters used in the equations above.
Figure 4.1. (a) Patches of stained RPE cells at 72 h for each patch size [1]. (b) Time course of VEGF expression per cell measured at 4, 24, 30, 48, and 72 h (data for each time from the \textit{in vitro} [1]).

and identifies the known parameters and those that need to be determined by the method introduced in this paper.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
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</tr>
<tr>
<td>$K$</td>
<td>Unknown</td>
<td>Auto regulation rate</td>
</tr>
<tr>
<td>$\mu_V$</td>
<td>Unknown</td>
<td>Secretion rate</td>
</tr>
<tr>
<td>$\beta$</td>
<td>Unknown</td>
<td>Binding affinity</td>
</tr>
</tbody>
</table>

### 4.4 Method

In this work, we apply a parameter fitting technique to validate a hybrid agent-based model with available \textit{in vitro} experimental data in order to explore the best-fit values for the unknown parameters given in Table 4.1. The three unknown parameters are termed
Figure 4.2. (a) Closeup of initial condition of a 400 µm patch (b) Experiment with 400 µm, 3 patches in each side. (c) Closeup of the VEGF distribution after 72 h, (d) VEGF distribution over whole domain after 72 h.
Figure 4.3. An overview for the error-minimization multicellular search-based approach. In (A), RPE cells are cultured using micropatterning techniques. In (B), the parameters are initialized in the XML protocol file. In (C), a simulation is performed and the results are calculated. In (D), the error is calculated based on the difference in VEGF concentration per cell between the experimental results and simulation outputs as in Equation 4.3. Based on the change in error, new parameter values are selected for another simulation run (E and F). This process (B-F) will be repeated until an exit condition is met where the error improvement is below a threshold value or the search time runs out.

the free parameters and together they define the vector $\vec{P} = < K, \mu_V, \beta >$. We use an error-minimization search approach that explores the space of free parameters and returns the vector $\vec{P}$ that yields the simulation results best fitting the experimental data [1]. The fitting process is summarized as follows:

**Given:** Model free parameters, simulation outputs, and experimental in vitro data.

**Find:** Best-fit values for the free parameters (best $\vec{P}$)

**Such:** The error between the simulation and experimental in vitro data is minimized.

The search for the correct $\vec{P}$ (described in Algorithm 1 and Figure 4.3) starts by sweeping over an initial range of values for each free parameter being fitted. A single sweep consists of running simulations for the space of $\vec{P}$ (all combinations of free parameter values
based on their ranges). The range is defined by a minimum value, a maximum value, and a step value. In a sweep, each parameter starts from its minimum value and incrementally increases to its maximum value by its step value. An error is calculated for each parameter vector by comparing the time-series outputs of the simulation with experimental in vitro data (see Figure 4.3D). The vector \( \bar{P} \) of parameter values with the minimum error is selected and becomes the midpoint for the parameter ranges in the next sweep (see Figure 4.3E and F). The process continues until an exit condition is met where the reduction in error is below a threshold or the preset search time runs out. The parameter values (both free and known parameters) for a simulation are specified via the protocol file. (see Figure 4.3B).

In this model, the error was calculated using Equation 4.3. \( V_s(i,t) \) and \( V_e(i,t) \) are the VEGF concentrations per cell in the simulation and in vitro, respectively; \( i \) is the patch size, \( i \in \{100, 200, 300, 400\, \mu m\} \) and \( t \) is the time in hours, \( t \in \{4, 24, 30, 48, 54, 72\, \text{hours}\} \). The model error (\( \varepsilon_m \)) is the sum of the errors over the four patch sizes and six time points. The error was calculated for each parameter vector \( \bar{P} \). Additionally, since the simulation process is stochastic, each simulation was repeated 10 times, starting from different random seeds, and the results averaged for all presented data. Here it is important to note that this approach could be used to fit other models using different parameters, experimental results, and error functions.

\[
\varepsilon_m = \sum_i \sum_t (V_e(i,t) - V_s(i,t))^2 \quad |\bar{P} = < K, \mu_V, \beta > \quad (4.3)
\]

4.5 Results

Initially the method was applied to a single parameter, \( K \). Figure 4.4 shows the error values for five sweep iterations over \( K \). In each iteration, a parameter sweep for each patch size was performed. In this run, the values of VEGF secretion rate \( \mu_V \) and VEGF binding rate \( \beta \) were set to 0.09 pg/ml and 1.0, respectively. In iteration 1 (It1) the parameters were swept from 0.1 to 0.9, then the best value was chosen to determine the sweeping range for iteration 2 (It2). Over repeated sweeps the range of possible valid values for \( K \) was greatly
Algorithm 1 Algorithm for the Error-Minimization Search-Based approach using parameter sweeps which identifies a parameters vector $\bar{P}$ that is locally optimal

1: **Input**: List of Free-Parameters $P$, XML Protocol Files $P_{files}$, and realistic parameter ranges $Rs$.

2: For each parameter $p_k$ in $P$, initialize $max_k$, $min_k$, $step_k$ randomly within $Rs$.

3: **while** time-out is not reached and $error_{change} > error_{threshold}$ **do**

4: \[SWEEP(P_{files}, 1, max_1, min_1, step_1, \{\}, 10)\] ▸ Recursive parameter sweeping algorithm. Started with the first parameter. See Algorithm 2

5: For each simulation result from the space of $\bar{P}$s, calculate the VEGF concentration per cell for each patch size $i$ and time $t$ ▸ There are 10 repeats for each simulation using different random seeds

6: Calculate the average $VEGF$ concentration

7: Find the $error$ based on equation 4.3

8: $error_{change} = error_{previous} - error$

9: **if** $error < error_{lowest}$ **then**

10: \[error_{lowest} = error\] ▸ Keep track of the lowest error found so far and the change in error from the last sweep

11: Change $max_k$, $min_k$, $step_k$ based on parameter values associated with $error$

12: **end if**

13: **end while**

14: Return the parameters values $\bar{P}$ associated with $error_{lowest}$ ▸ this will return the best value(s) found

![Figure 4.4. Error based on different $K$ values with iteration number $It$](image_url)

Reduced. After five iterations of sweep processes, the best $K$ value obtained was 0.13 and the associated error was 1.01. This search considered many potential solutions and all but one were rejected as sub-optimal.
Algorithm 2 The parameter sweep algorithm that performs a simulation for all $P$ (a combination of free parameters). $P_{files}$ are the XML protocol files that define the model input and initial condition, $K$ is the parameter count, $k$ is a counter that ranges from 1 to $K$, $max_k$ is the maximum value for parameter $k$, $min_k$ is the minimum value for the $k$th parameter, and $step_k$ is the value by which parameter $k$ is incremented, $\bar{P}$ holds a single combination of parameter values for which a simulation will be performed, $P$ is a matrix of size $Kxj$ where $j$ is the number of values in the range of some parameter (which changes as the algorithm progresses) and $P[k][j]$ holds the $j$th value of the $k$th parameter, and $Run_N$ is the number of repeated runs, each using different random seeds.

```
procedure Sweep($P_{files}$, $k$, $max_k$, $min_k$, $step_k$, $\bar{P}$, $Run_N$)
2:  if $k = K$ then
    Generate XML Protocol Files $G_{P_{files}}$ with the same setup as in $P_{files}$ with the parameter values $\bar{P}$
4:      $Run(G_{P_{files}}, P_{Set}, Run_N)$ > random seeds runs
    $\bar{P}.Empty$
6:  else
      $j = 1$
8:      $P[k][j] = min_k - step_k$
    while $P[k][j] < max_k$ do
10:    $P[k][j] = P[k][j] + step_k$
    $\bar{P}.Add(P[k][j])$
12:    $j = j + 1$
    $k = k + 1$
14:    SWEEP($G_{P_{files}}, k, max_k$, $min_k$, $step_k$, $\bar{P}$, 10)
16:  end while
18: end if
19:  end procedure
```

Figure 4.5 shows the error heat map of the first sweep iteration ($It_1$) over two parameters ($K$ and $\beta$). For this run, the VEGF secretion rate $\mu_V$ was set to 0.078 pg/ml/hour. As shown, the error is lowest when the VEGF binding rate ($\beta$) is less than 0.3 and the $K$ value is greater than 0.03. Figure 4.6 shows the second sweep ($It_2$), which has adjusted sweeping ranges for $K$ and $\beta$. Successive iterations refine the parameter values, as shown through reduced error in Figure 4.7, which shows the third sweep ($It_3$). The same sweeping processes was also performed between ($\mu_V$ and $K$) and ($\mu_V$ and $\beta$) (data not shown).

To show how the concentration of VEGF changes over time in the simulation, VEGF expression levels were calculated at various time intervals (4, 24, 30, 48, 54, 72 h). Figure
Figure 4.5. The heat map of error between $K$ and VEGF binding coefficient/rate ($\beta$) determined from the first round sweep.

Figure 4.6. The heat map of error between $K$ and VEGF binding coefficient/rate ($\beta$) determined from the second round sweep.

4.9(a) shows the data from *in vitro* and Figure 4.9(b) the *in silico* model, $K$, $\mu_V$, and $\beta$ are set to 0.13, 0.09 and 0.85, respectively, which were determined from a near-optimal solution discovered by the search method. The error associated with these results is 0.925. As shown in figure 4.9(a) and 4.9(b), in both *in silico* and *in vitro*, RPE cells in the smaller patches expressed higher levels of VEGF per cell. This indicates that these cells function to maintain a consistent level of VEGF within their local microenvironment. Cells in smaller patches respond by expressing higher amounts of VEGF because the VEGF expression levels are dominated by cell-environment interactions. In contrast, larger patches maintain
lower basal levels of VEGF because cell-cell auto-inhibitory regulation dominates.

Now the parameters $K$, $\mu_V$ and $\beta$ have been determined, we replace the variables with their values in Equation 4.1 and set the mass $M$ to that of a single cell ($M = 25.95 \text{pg}$) resulting in the VEGF autoregulatory function for RPE cells being:

$$\frac{dV}{dt} = 0.09 \times \frac{0.13}{0.85V + 0.13} \times 25.95$$

(4.4)

This function is plotted in Figure 4.8.

4.6 Conclusions

One of the main challenges in the computational modeling of biological systems is the determination of the models’ parameters. This problem is particularly acute with multiscale models that are gaining in popularity due to their realism. In this work, we identified the parameter values of a cellular regulatory mechanism using spatiotemporal multicellular data. While the problem of finding parameter values that describe the VEGF autoregulatory mechanism of RPE cells is simple, this problem domain serves and a proof-of-concept for the overall method. Most importantly, the method demonstrates that it is possible to utilize data at one scale to determine parameter values at a different scale.

In the work presented here, thousands of simulations were performed as the search
method explored the parameter space. For each potential solution, multiple simulations were needed over each experimental case (different patch sizes) and because of the need for repeats due to model stochasticity. For the simple 2D RPE model, each simulation took less than a minute and so the process could be completed quickly. In general, the method can rapidly become infeasible as the number of unknown parameters grows, domains become larger and more complex, and the number of specific experimental cases grows.

A recently developed hybrid simulation system called Biocellion [114] could be used instead of the iDynamics to speedup the rate of simulations. Biocellion can utilize thousands of processing nodes and rapidly simulate complex models of billions of cells. The search method utilized in this paper was chosen for its simplicity and insights on the local error surfaces provided by the sweeping process. However, the fitting method is independent of the method employed to search the parameter space. Alternative methods of combinatorial optimization may improve performance.

One problem all fitting methods must deal with is under or over fitting the model. There is a possibility that the fitting problem may be under-constrained for lack of data.
Figure 4.9. (a) Time course of VEGF expression per cell measured at 4, 24, 30, 48, and 72 h (data from the *in vitro* work [1]. (b) Time course of VEGF expression per cell measured at 4, 24, 30, 48, and 72 h (data from the *in silico* model after optimization).

This problem will be explored in the RPE domain by expanding the data set to include additional studies with VEGF agonists and alternative pattern arrangements.

To extend the method to other domains, alternative error functions can be employed that measure discrepancies over a diversity of spatiotemporal features which quantify both the experimental observations and simulator outcomes. For instance, in [131] image processing is applied to bright field time-lapse images of growing yeast colonies to extract trajectories of many visual features including volume, roughness, dominant frequency etc. The same features could be extracted from the morphologies of simulated colonies and used to fit parameters of the yeast model.
CHAPTER 5

CONCLUSIONS

Computational biology is an integrative and holistic rather than reductionist approach to understanding and controlling biological complexity [132]. It permits the development of predictive and actionable models of multiscale biological systems that are vital to making strides against the constellation of diseases that affect the world. These diseases are defined by their mechanistic complexity and nonlinearity, which spans several spatiotemporal scales. The ability of agent-based modeling to encompass multiple spatiotemporal scales of biological processes, suggests that this modeling framework is well suited for studying these complex systems.

In this research, a multicellular hybrid agent-based modeling approach is utilized in order to study disease development and progression, particularly in two applications: breast cancer and bioengineered experiments. The models outlined were used to study in vitro experimental work and in vivo development to gain new insights and integrate experimental data to validate simulations.

In the first study, we developed a 2D agent-based model that attempted to emulate the in vivo structure of breast cancer. The model was used to describe the transition from DCIS into DCI. We concluded that the interaction between tumor cells and the surrounding stroma in the duct plays a critical role in tumor growth and metastasis. This interaction depends on many mechanical and chemical factors that work with each other to produce tumor invasion of the surrounding tissue. In the second study, an in silico model was proposed and applied to understanding the underlying mechanism of VEGF auto-regulation in REP and emulate the in vitro experiments as part of bioengineering research. In the third and final study, an innovative approach was presented that estimates cellular parameters from spatiotemporal data produced from bioengineered multicellular in vitro experiments.
We applied a search method to an integrated cellular and multicellular model of retinal pigment epithelial cells to estimate the auto-regulation parameters of VEGF. This searching method can be extended to other domains and alternative error functions, which can be employed to measure discrepancies over a diversity of spatiotemporal features to quantify both the experimental *in vitro* *in vivo* observations and simulator outcomes.

From the studies performed in this research, we learned that models are more useful if they can be predictive and the predictions are in a form that can be directly measured in laboratory and clinical experiments. These predictive models can be utilized to guide the laboratory towards the most informative experiments. To obtain such predictive models, parameters estimation and models validation are essential. We have found that as granularity of model becomes more complex, the amount of data needed for validation becomes greater than what can be generated by typical laboratory experiments, and so is often difficult to obtain. Finding the right model size is a challenge. The opportunities for the future is to better understand how to take the large model, such as breast cancer it down to a level where the parameters can be estimated robustly from experimental data, as illustrated in the bioengineered application.

Future prospects for such modeling approaches include the development of patient-calibrated models by specialization of cell physiology obtained from clinical histopathology data. These also include the creation of patient-specific digitized cell lines, which can then be read by a collection of appropriate simulators to search, visualize, compare, predict, and help guide the patient’s treatment options. Attaining this future will require considerable cooperation among *in vitro* research, clinical data, and computational biology work. Another developed hybrid simulation system called Biocellion [114] could be used instead of the iDynamics to speed up the simulations. Biocellion has the ability to utilize thousands of processing nodes and rapidly simulate complex models of billions of cells. Using the Biocellion framework, the models developed in this dissertation can be extends to large-scale in order to support of high-throughput experiments and the discovery and evaluation of therapies.
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*Biomedical Optics Express*, vol. 4, no. 11, pp. 2527–2539, 2013. [Online]. Available: http://dx.doi.org/10.1364/boe.4.002527


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I am in the process of preparing my dissertation in the Computer Science department at Utah State University. I hope to complete my degree program in Computer Science.
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To coauthor Soonjo Kwon

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Dear Soonjo Kwon:
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To coauthor Christopher D. Johnson

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EDUCATION

• Ph.D., Computer Science. Utah State University, Logan, UT. 2015.
• M.S., Computer Science. Jordan University of Science and Technology, Irbid, Jordan. 2007.

RESEARCH INTERESTS

• Bioinformatics (Multi-scale modeling).
• Sensor technology.

PUBLICATION

THESIS


PUBLICATIONS IN CONFERENCE

• Qanita BaniBaker, Gregory J.Podgorski, Nicholas S. Flann, Interaction Stroma and Tumor Growth in Ductal Carcinoma in Situ Metastasis: 2D and 3D Agent-Based Modeling. Utah state university tenth annual celebration of faculty and student research at Utah State University. Logan. USA (Apr. 4-11, 2014).
• Agent-based model for breast tissue culture development in vitro. Qanita Bani Baker, Nicholas S. Flann, Soonjo Kwon, Gregory J. Podgorski, and Ahmadreza Ghaffarizadeh, Utah State University. IBe 2014

• A 3D agentbased model of the transition from ductal carcinoma in situ to invasion. Qanita Bani Baker, Nicholas S. Flann, Soonjo Kwon, Gregory J. Podgorski, Ahmadreza Ghaffarizadeh, IBe 2014

• Qanita Bani Baker, Gregory J. Podgorski, Christopher D. Johnson, Elizabeth Vargis, Nicholas S. Flann, Bridging the Multiscale gap: Identifying Cellular Parameters from Multicellular Data. IEEE, 2015

PUBLICATIONS IN JOURNALS

• Qanita Bani Baker, Ahmadreza Ghaffarizadeh, Soonjo Kwon, Gregory J. Podgorski and Nicholas S. Flann. Interaction of Stroma and Tumor Growth in Ductal Carcinoma in Situ Metastasis: An Agent-Based Modeling Approach. 2015( under review )

• Qanita Bani Baker, Gregory J. Podgorski, and Elizabeth Vargis, Nicholas S. Flann. Developing in Silico Model to Study the Effect of Retinal Pigment Epithelial Cell Patch Size.2015(under review)

POSTER


• Qanita Bani Baker, Ahmadreza Ghaffarizadeh, Soonjo Kwon, Gregory J. Podgorski and Nicholas S. Flann. Interaction of Stroma and Tumor Growth in Ductal Carcinoma in Situ Metastasis. Utah state university tenth annual celebration of faculty and student research at Utah State University. Logan. USA (Apr. 4-11, 2014).

• Interaction of Stroma and Tumor Growth in Ductal Carcinoma in Situ Metastasis: A 2D Agent-Based Modeling. SBI Science and Technology Review Winter Meeting. Utah State University Eccles Conference Center. (Feb.12, 2014)

• Developing in Silico Model to Study The Effect of Retinal Pigment Epithelial Cell Patch Size. USU Jan 6 2015

HONORS AND AWARDS

• Scholarship from Jordan University of Science and Technology to study PhD in computer science at Utah state university. August 2011

• Travel award from USC (university of southern California) to attend the Short Course and participate in poster session. October 2013
• Wining poster award among the graduated students in Utah State University CS department. Fall 2013.

• Wining poster award among the graduated students in Utah State University CS department. Spring 2014.

• USU Pinnacle Honor Society.

• USU Golden Key Society.

TEACHING EXPERIENCE

• Graduated Student/Teaching Assistant, Department of Computer Science, Utah State University (Sep 2011- now)

• Full Time Instructor, Computer Science Department Jordan University of Science and Technology (May 2008 - July 2011): Teaching C++, visual basic, Vb.Net, introduction to information technology. Web design courses, computer skills, and working as supervisor for graduated project.

• Part Time Instructor, Computer Science Department Jordan University of Science and Technology (July 2007 - May 2008): Teaching web design courses, computer skills, and different programming language courses (C++, Java, Vb, and Vb.Net).

• Graduated Student/Research Assistant Department Jordan University of Science and Technology (Feb 2005 - May 2007)

TRAINING AND WORKSHOP

• International Teacher Assistance workshop nov-2011(USU,UT,USA)

• INTERNATIONAL VISITOR LEADER SHIP PROGRAM. UNITED STATE DEPARTMENT OF STATE .BUREAU OF EDUCATIONAL AND CULTURAL AFFAIRS.

• Attendance in the 23rd Annual Conference on Distance Teaching And Learning ACADEMY FOR EDUCATIONAL DEVELOPMENT. August, 2007. Monona Terrace Convention Center. Madison, Wisconsin, U.S.A.

• International Computer Driving License certification/issued by the UNESCO Cairo office.

• Three (3) months in JUST computer center to learn Oracle.2003.

• World-links certificate/worlds linked organization (160 hours).

• Computer maintenance courses and certification/Al- shark center (84 hours).

• English conservation Certification / from oxford center (32 hours).

• online training courses/ HKJ -Ministry Of Education and ESP(100 hours).

• Teaching methods / HKJ -Ministry Of Education(60 hours).
KEY SKILLS

- 2D/3D Modeling, Multi-scale Modeling
- Programming Language: (C++ (under window or linux), VISUAL BASIC.NET, C, Java, AspectJ).
- Web Programming (XHTML, HTML, XPath, XQuery, XML)
- Database Management System: (SQL, Oracle, Advanced Access)
- Web Page Application (ASP.NET)
- Parallel Computing: MPI under Linux-C++.
- Image Processing Language MATLAB.

PERSONAL SKILLS AND COMPETENCES

- Communication skills, Team work and Ability to work under pressure for long hours. Have the potential of learning new programming languages and technologies. Have the spirit of proficiency and creativity. Fast learner, enthusiastic, dedicated, organized, clear and logical thinker, motivated, reliable. Ability to work as programming Languages Instructor and applications trainer.
- LANGUAGES: Arabic (Fluent), English (Excellent) 99 in TOEFL-IBT